

Video Segmentation and its Applications.

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at Google



Efficient Hierarchical Graph-Based Video Segmentation & More

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^{}Georgia Tech*

⁺Google Research

[#](now at Nvidia Research)



Video Segmentation: Motivation

- ✦ Spatio-temporal regions:
Group appearance and motion
in space and time
- ✦ Application: Selecting regions
⇒ rapid annotation of objects
etc.
- ✦ Grundmann, Kwatra, Han, and
Essa (2010), "Efficient
Hierarchical Graph-Based
Video Segmentation," *CVPR*
2010.



region color indicates region identity



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Segmentation (Images)



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- ✦ Partitioning a digital image into multiple segments (sets of pixels, also known as superpixels).
- ✦ *to extract representation of an image into something that is more “meaningful” and “easier” to analyze*



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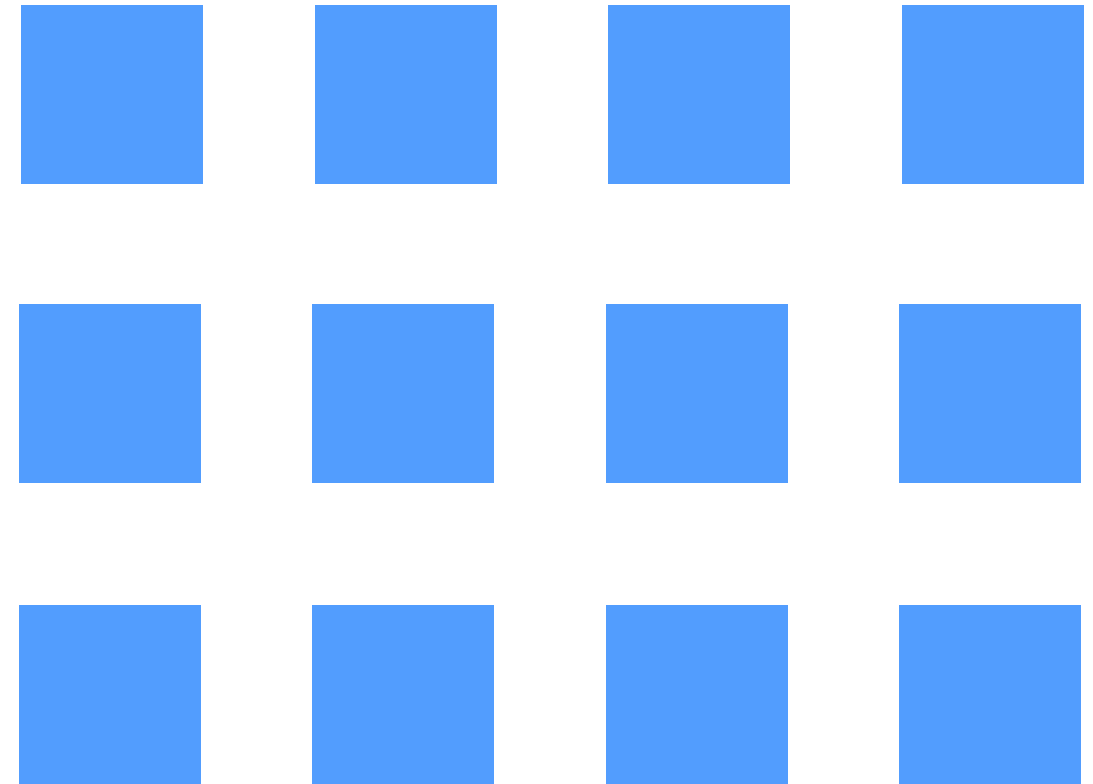
- ✦ Partitioning a digital image into multiple segments (sets of pixels, also known as superpixels).
- ✦ *to extract representation of an image into something that is more “meaningful” and “easier” to analyze*
- ✦ *typically used to locate objects and boundaries (lines, curves, etc.) in images.*
- ✦ *A process of assigning a label to every pixel in an image such that pixels with the same label share certain characteristics.*



Graph-based segmentation

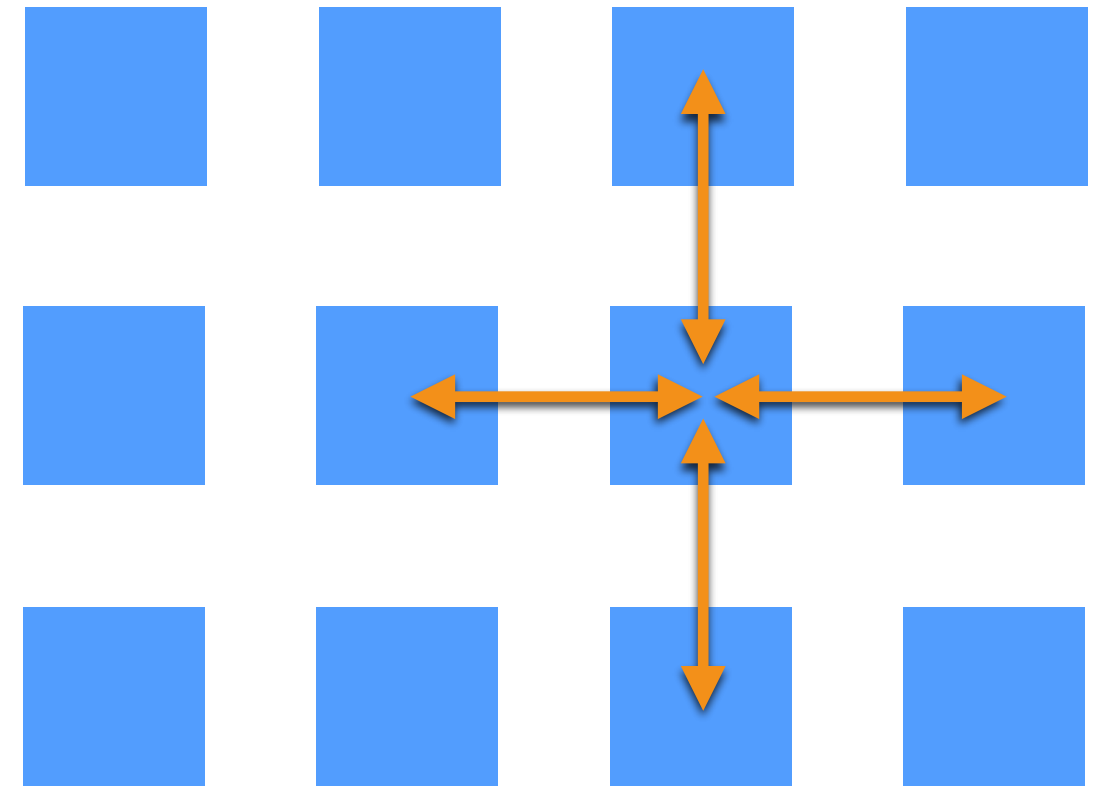
Graph-based segmentation

- ✦ Grid graph over image domain



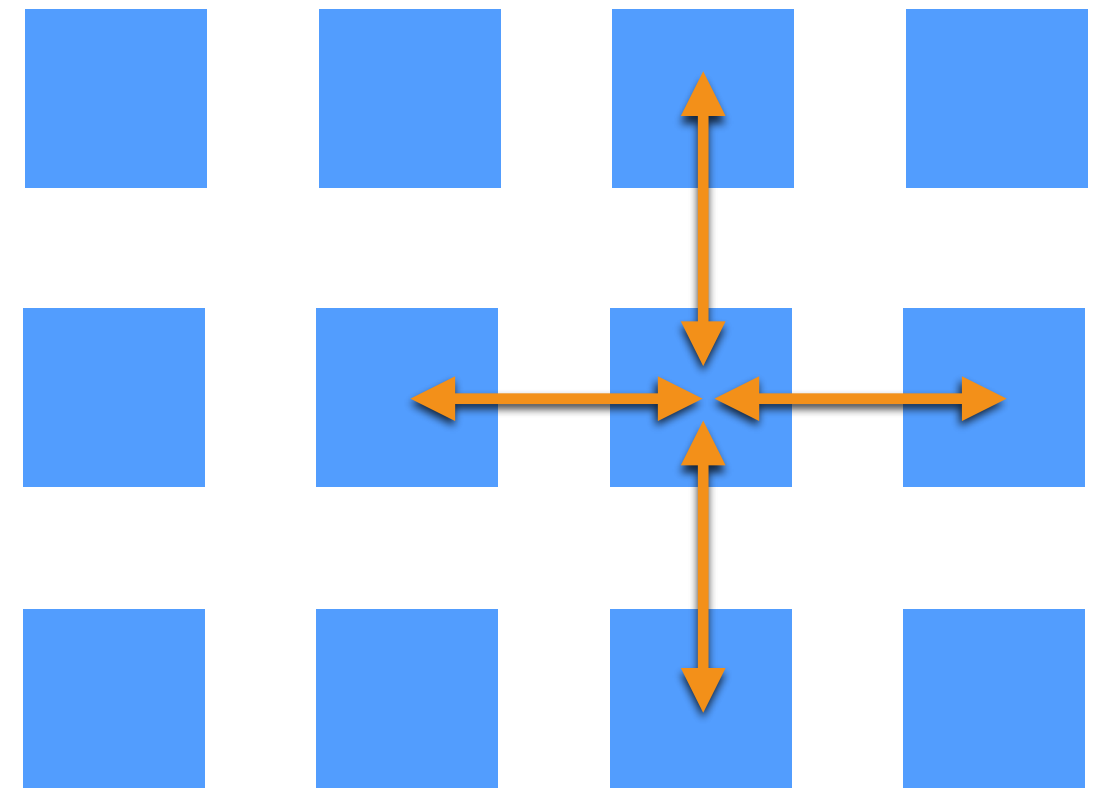
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- ✦ Grid graph over image domain
- ✦ Connectedness: N4 or N8



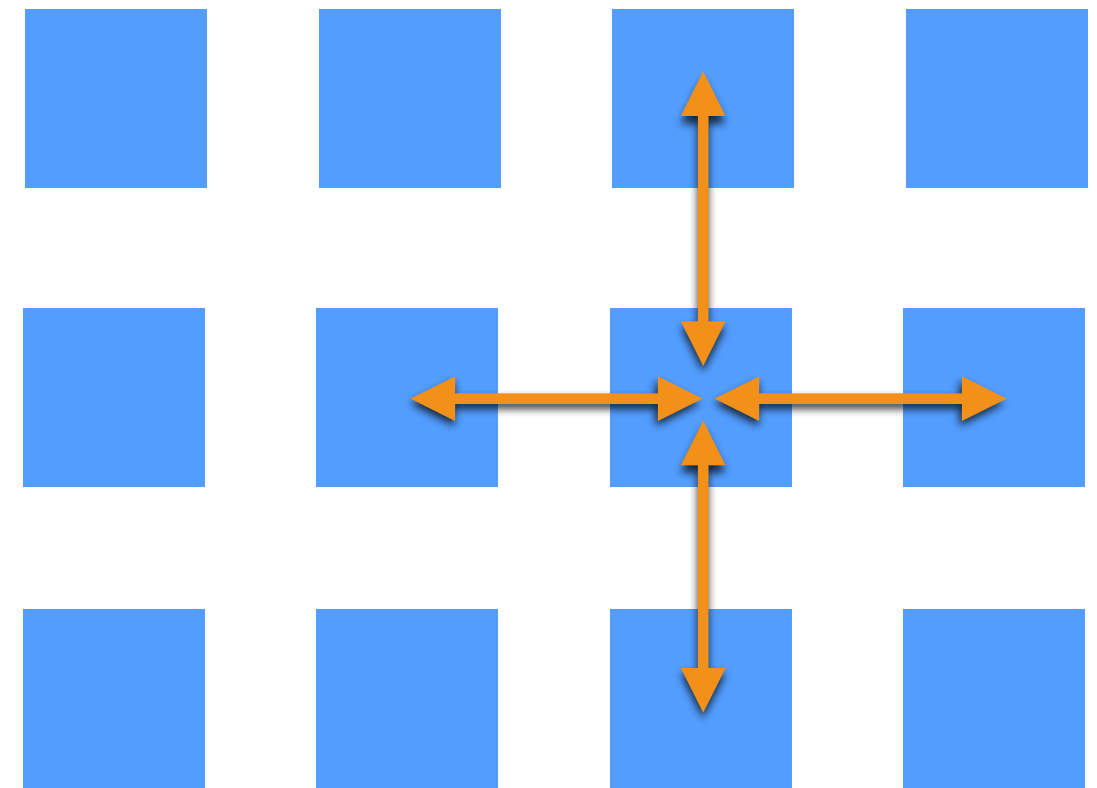
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 - ◆ *Color distance*
 - ◆ *Weighted with gradients*
 - ◆ *From per pixel classifiers, etc.*



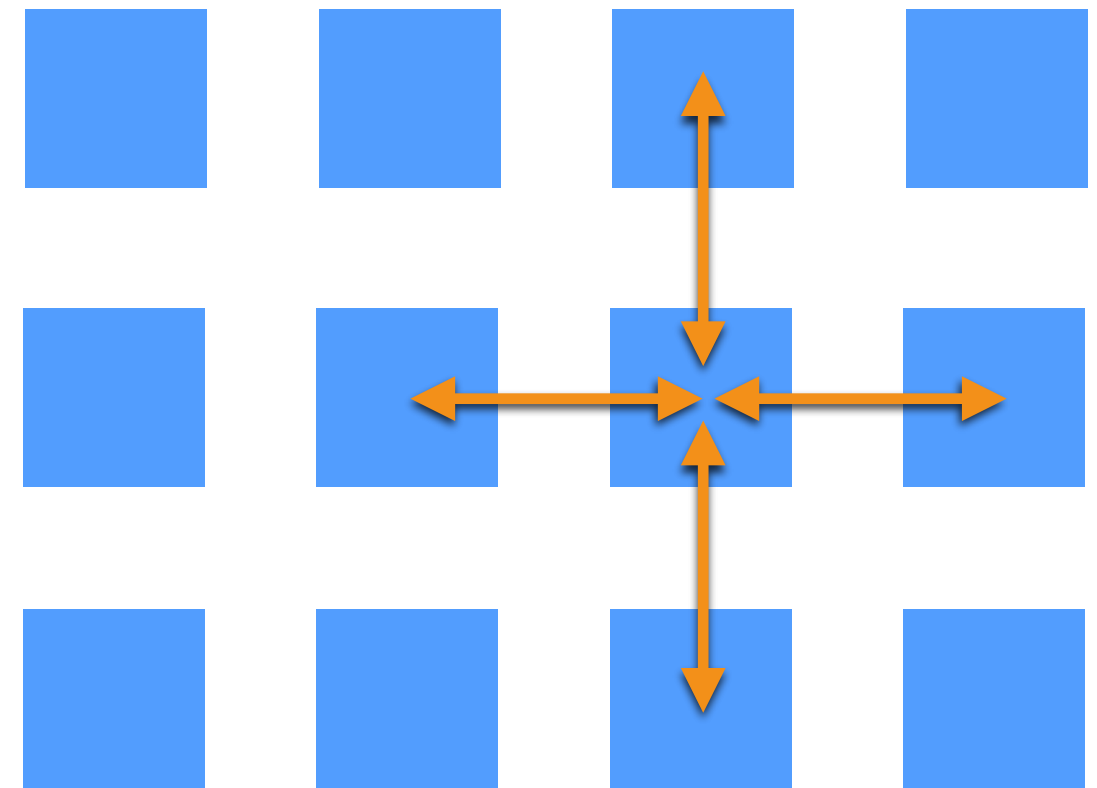
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- ◆ Cluster Pixels, Merge Regions

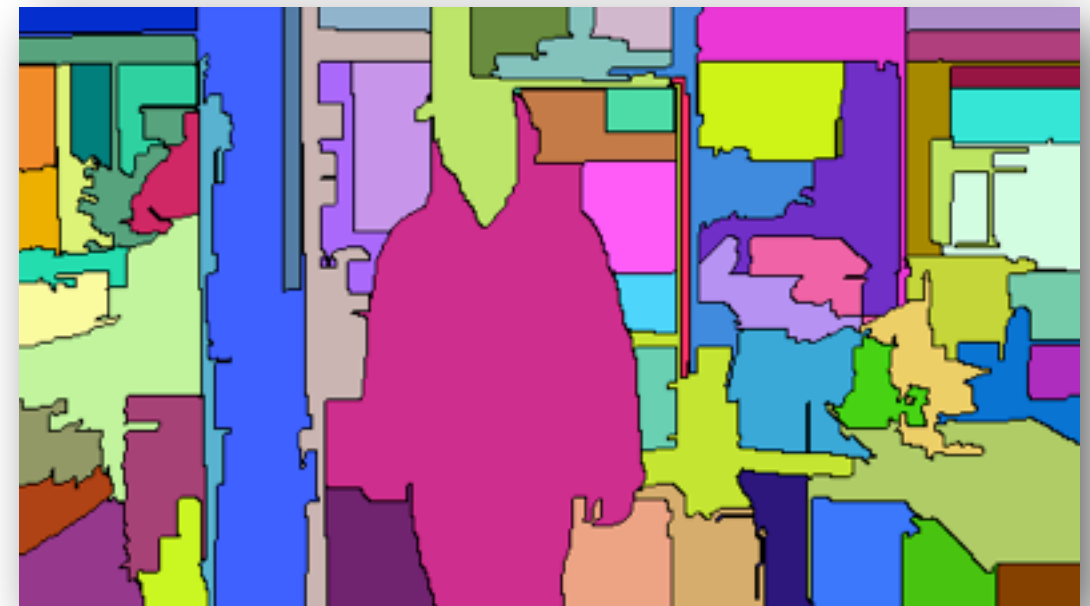


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- ◆ [Felzenszwalb & Huttenlocher 2004] “Efficient Graph-Based Image Segmentation” ([link](#))



Extending to Video Domain



Extending to Video Domain

- ✦ Direct application of image-based algorithm per frame
- ✦ [Felzenszwalb and Huttenlocher 2004]

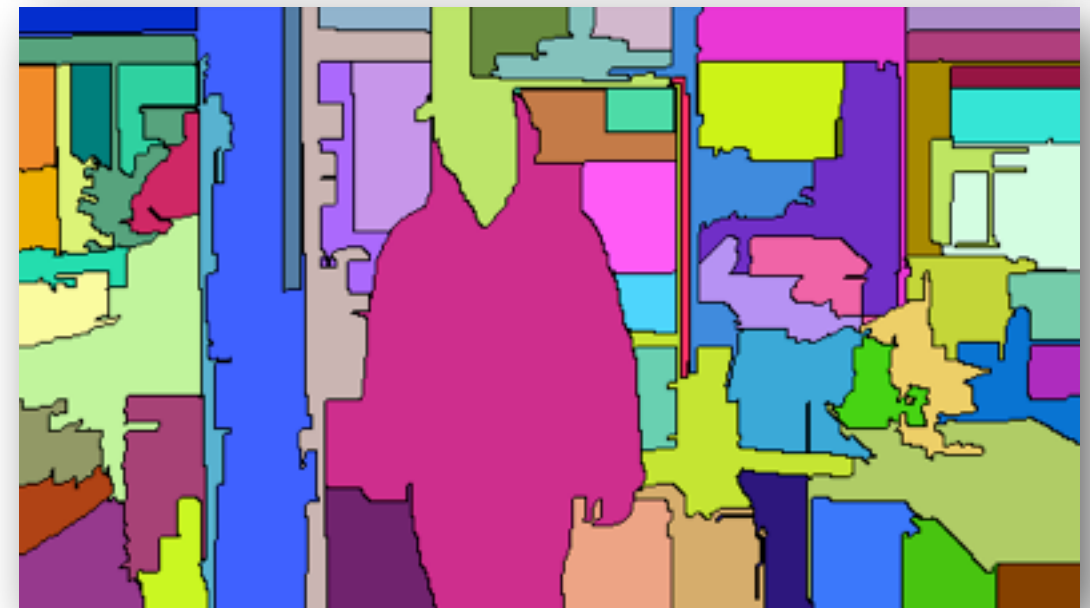


image segmentation applied to each frame

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image segmentation applied to each frame

Extending to Video Domain

- ◆ Direct application of image-based algorithm per frame
- ◆ [Felzenszwalb and Huttenlocher 2004]
- ◆ Lacking temporal coherence
- ◆ Unstable boundaries in time
 - ◆ *Associating 2D regions will yield noisy outcome*
- ◆ *Need to Cluster Pixels, Merge Regions in Time*

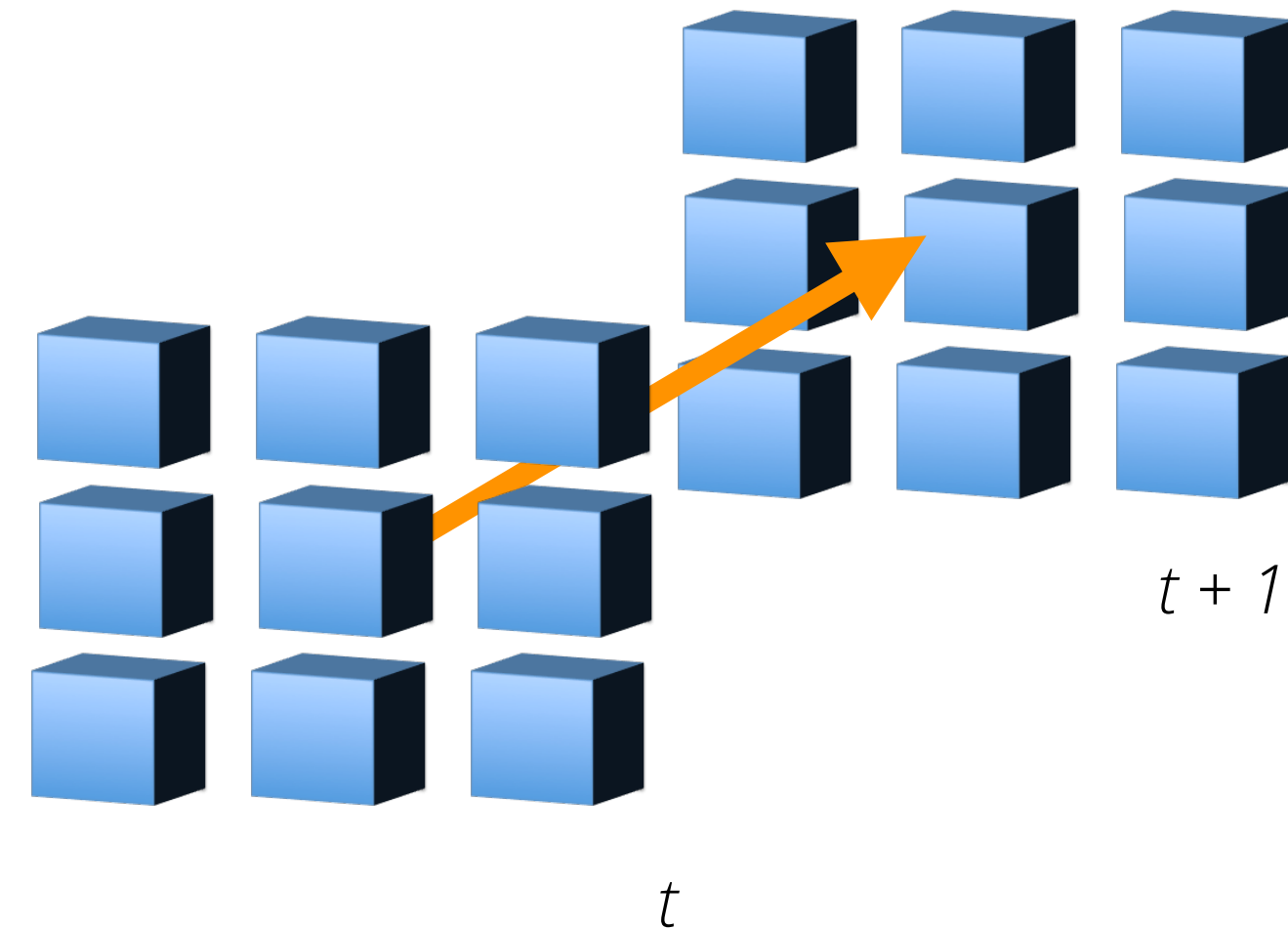


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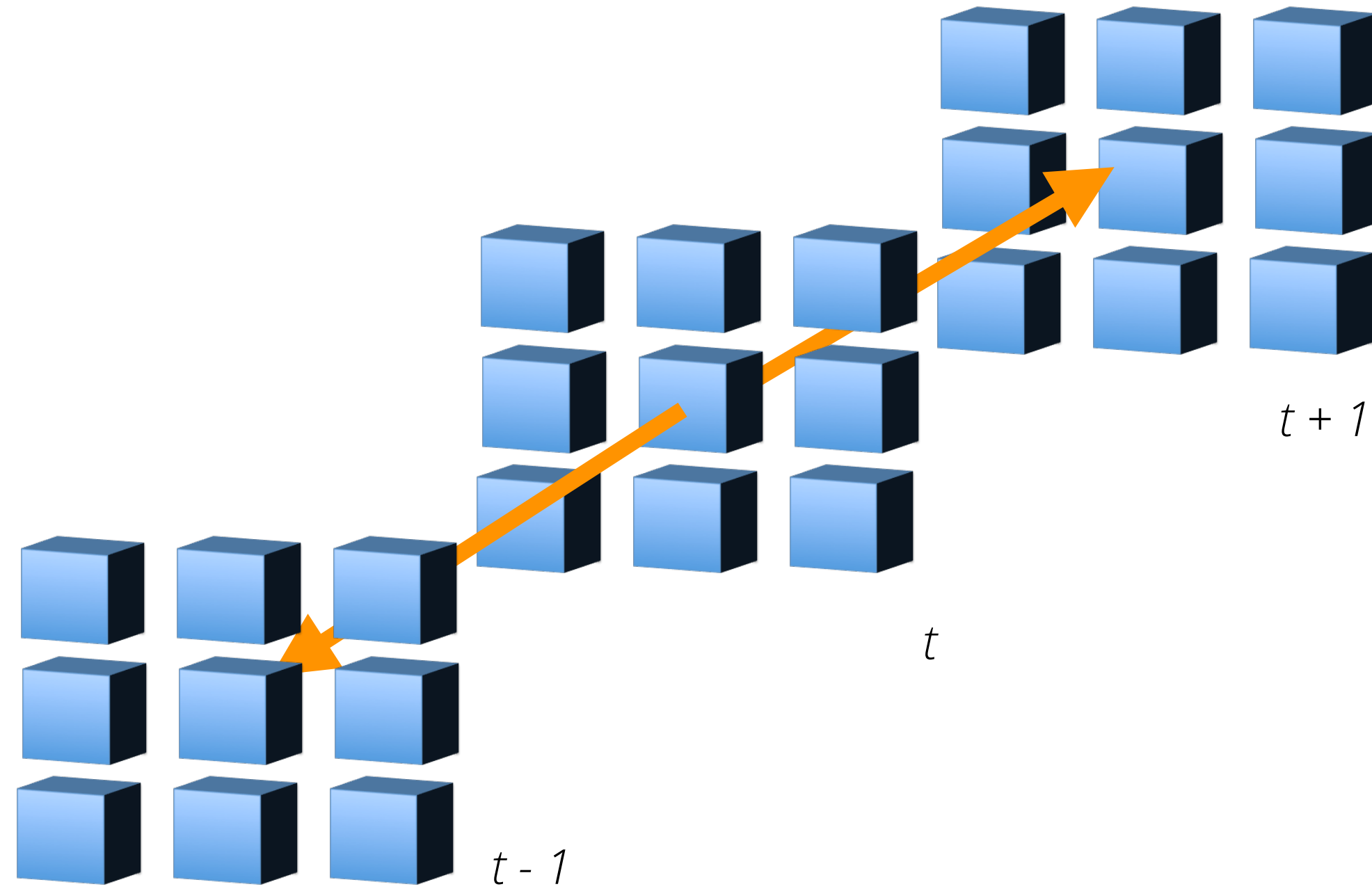
Extending to Video Domain

- ✦ Extend N8 graph in time:
Spatio-Temporal volume
- ✦ Connect each pixel to also to
its 9 neighbors in time
(forward / backward)



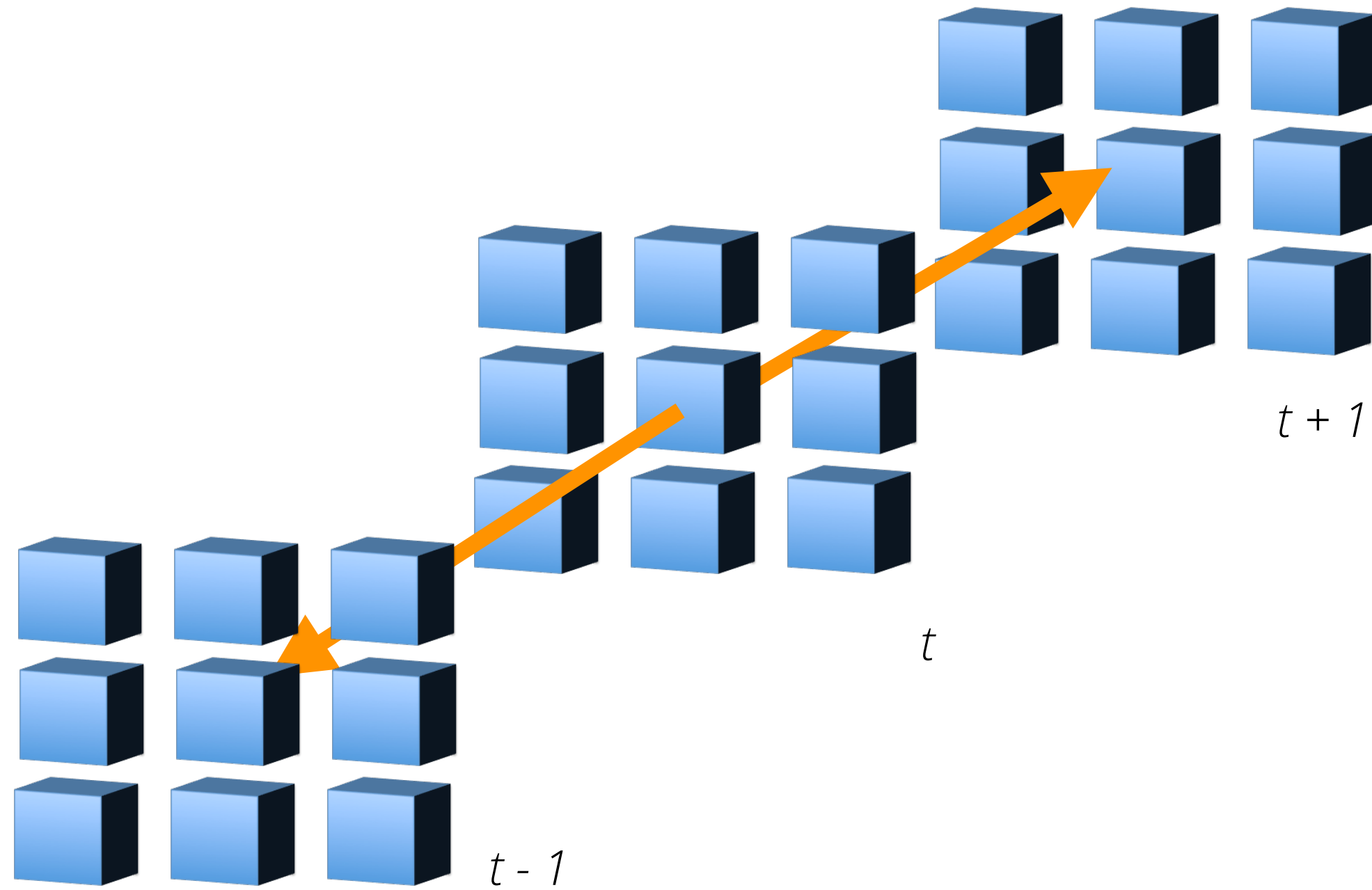
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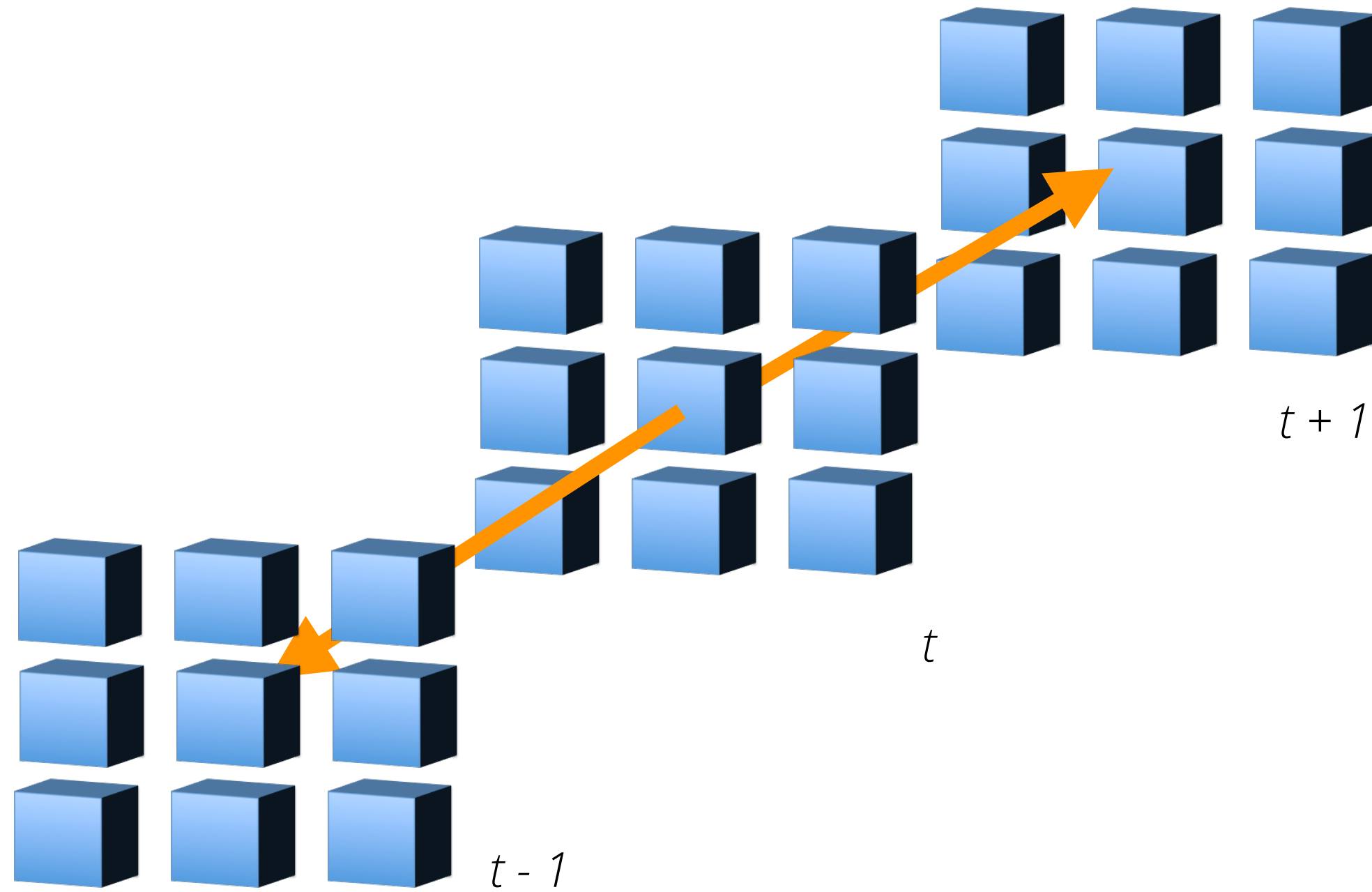
Extending to Video Domain

- ✦ Extend N8 graph in time: Spatio-Temporal volume
- ✦ Connect each pixel to also to its 9 neighbors in time (forward / backward)
- ✦ Connectedness: N26
 - ✦ *1 sec of 360p video: 90 million edges*
 - ✦ *vs. 1 million for image case*

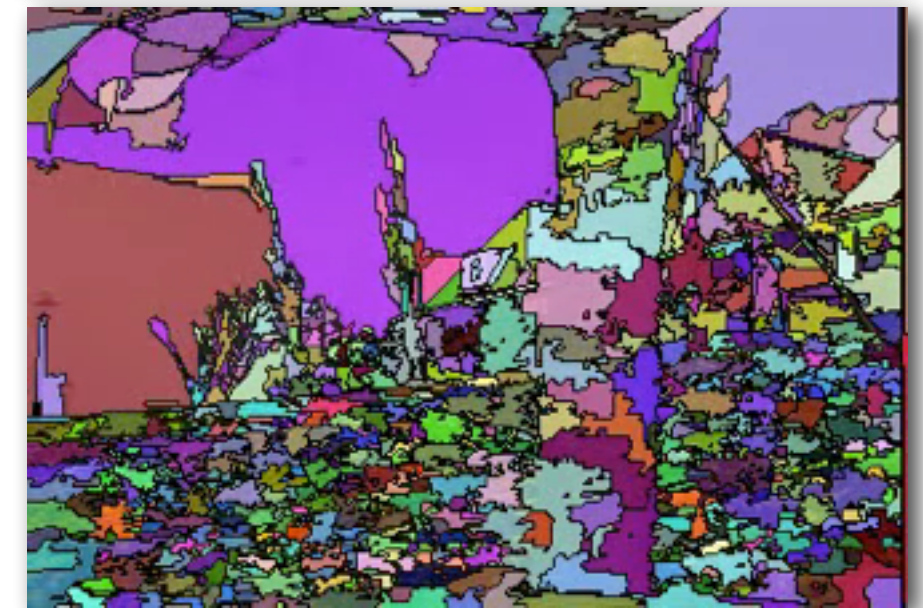


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- ✦ How to connect?
 - ✦ Direct predecessor
 - ✦ Displaced along optical flow

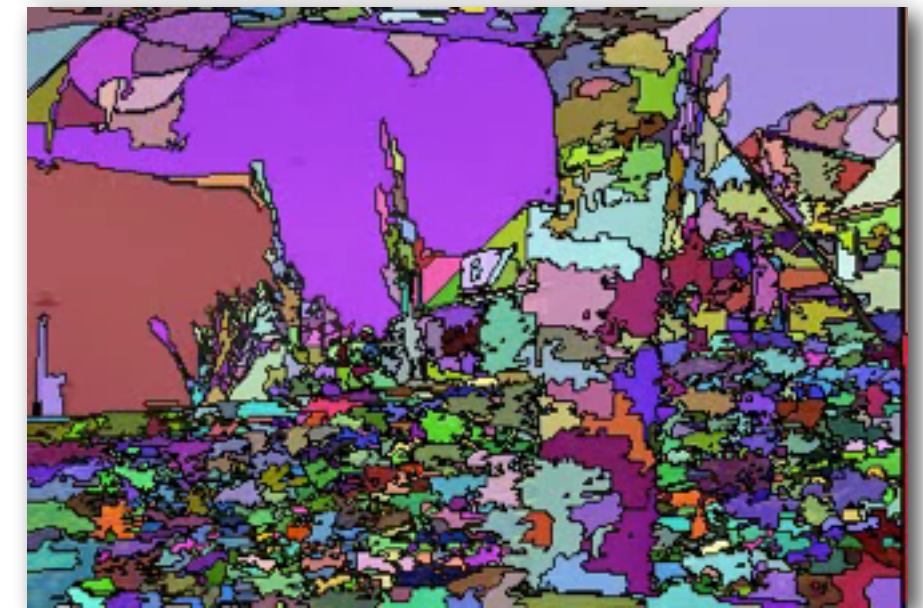


Pixel Connections in time



Pixel Connections in time

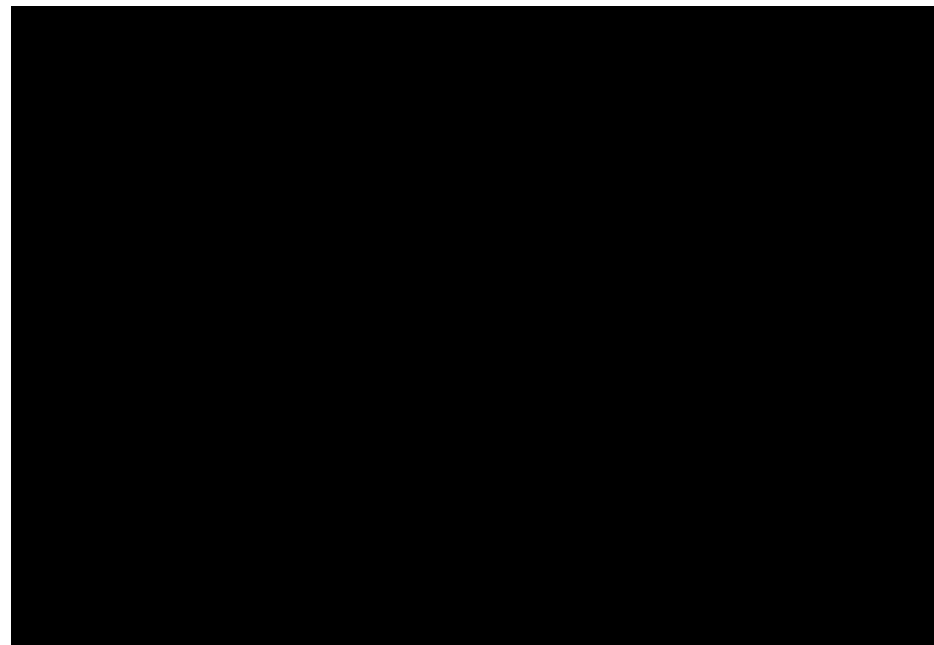
- ✦ Direct predecessor:
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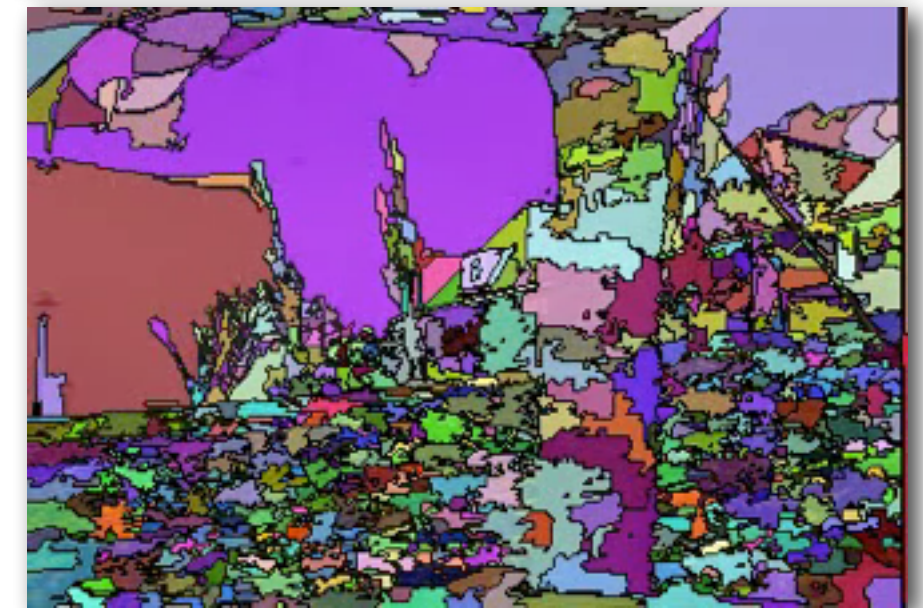
over-segmentation using direct predecessor in volume

Pixel Connections in time

- ✦ Direct predecessor:
 - ✦ *can't model movements > 1 pixel*
- ✦ Displace connection in time along dense optical flow



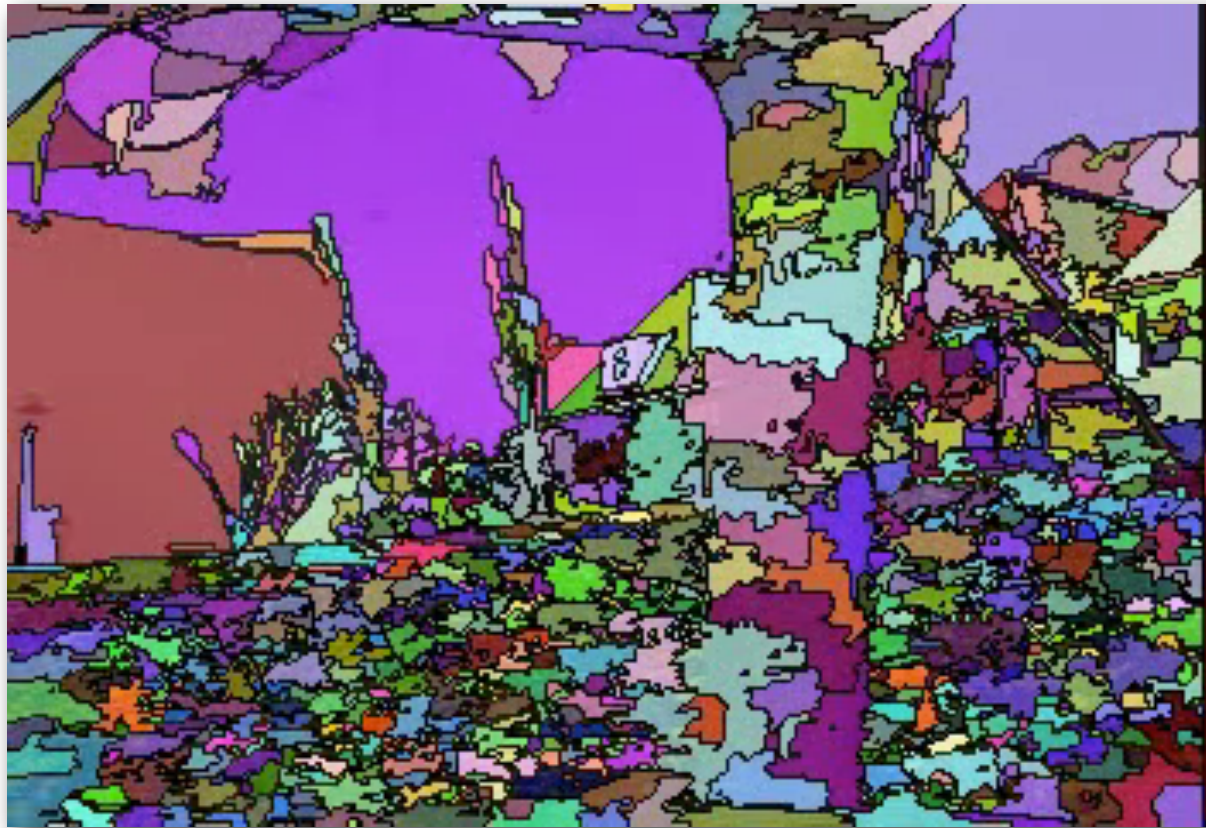
dense flow, hue encodes angle



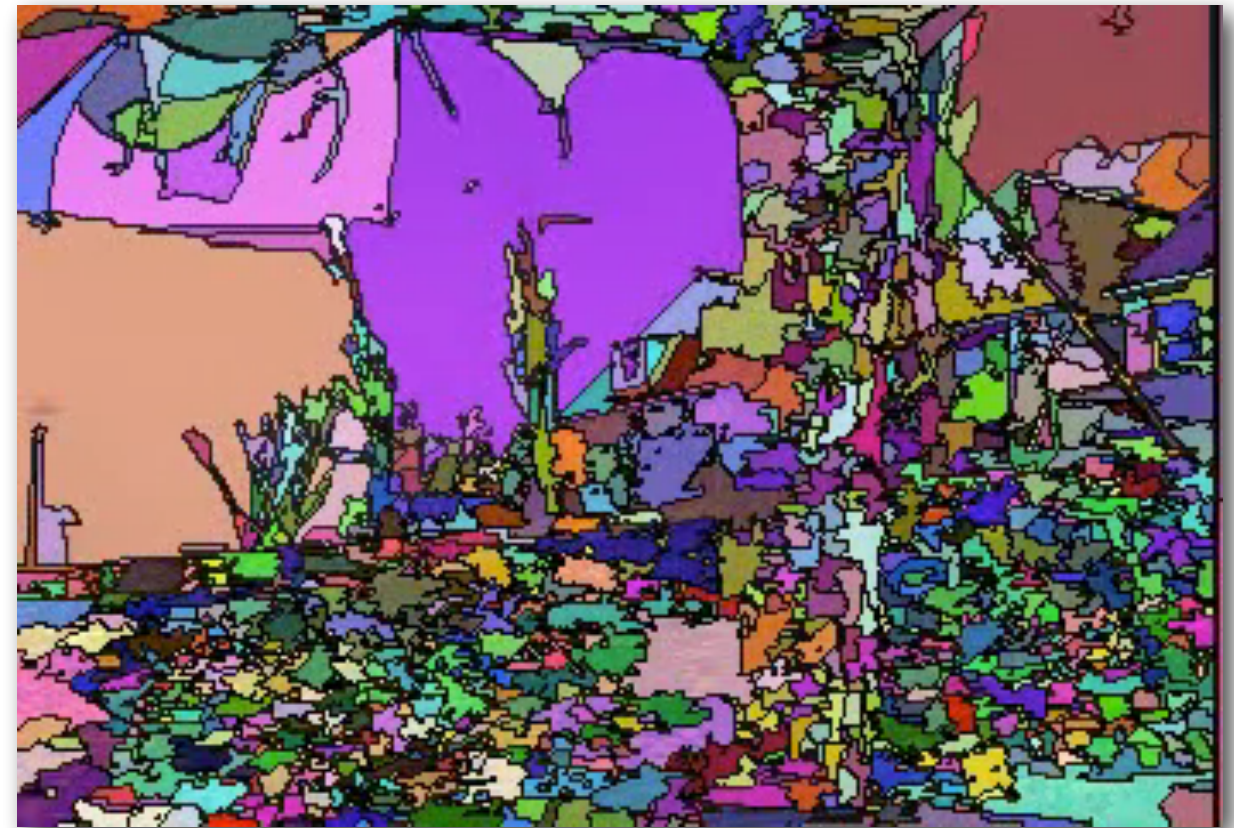
over-segmentation using direct predecessor in volume

Connection using dense optical flow

- ◆ Displace temporal connection along dense optical flow



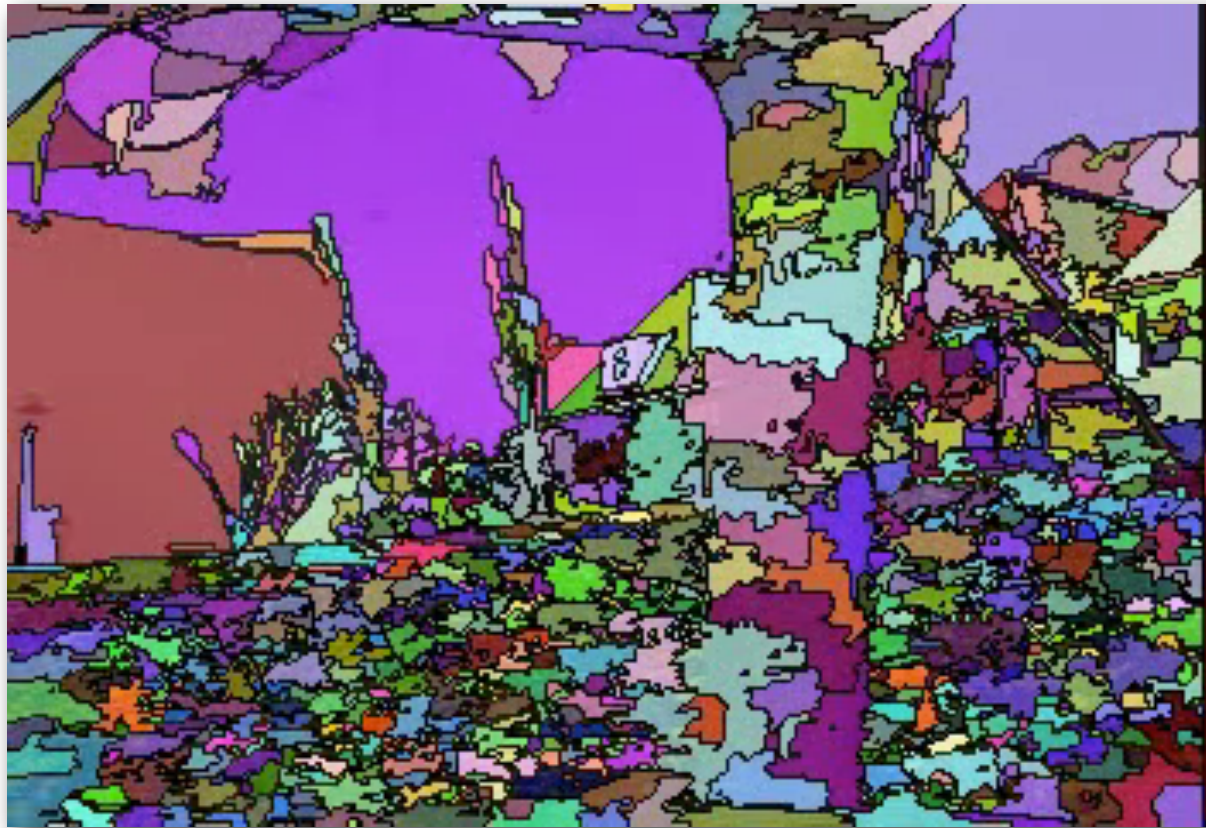
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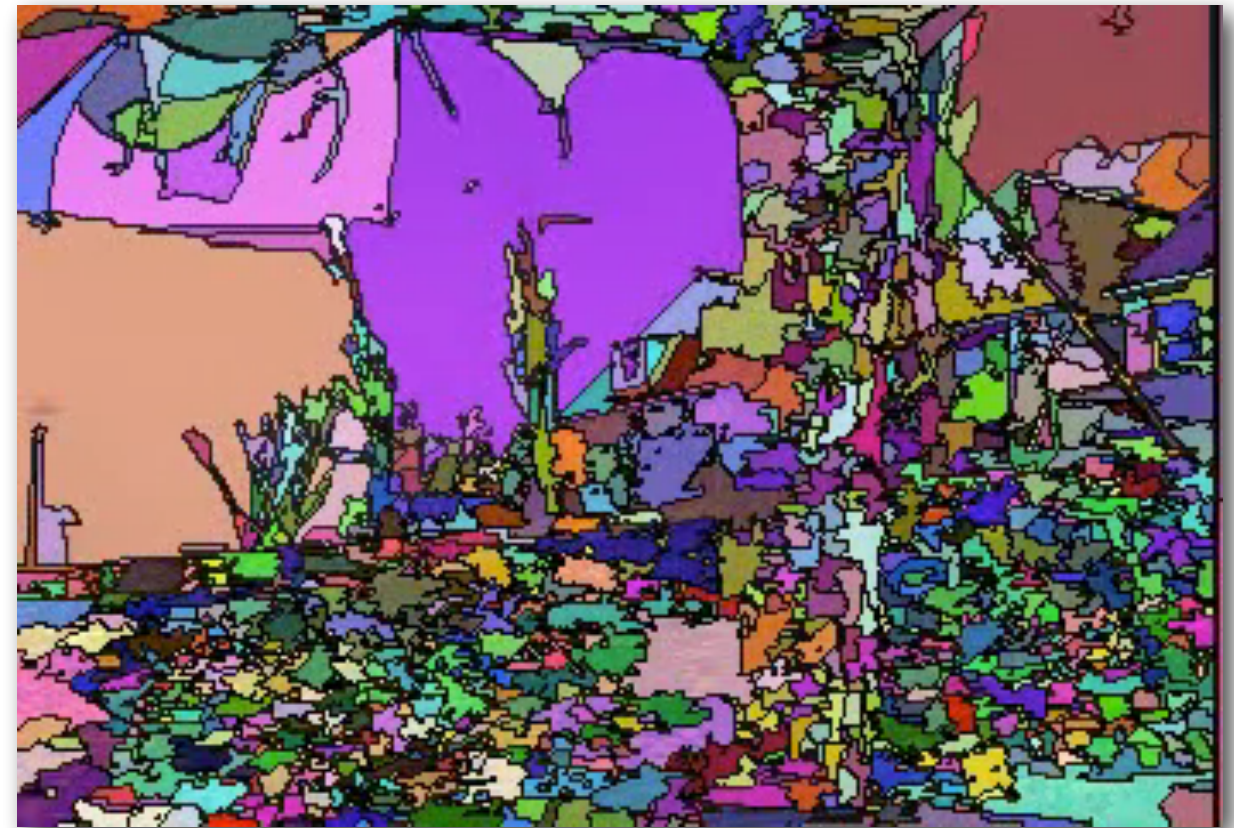
over-segmentation using predecessor along dense flow

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over-segmentation using direct predecessor in volume



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Why Graph-based segmentation?

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- ✦ Low-complexity segmentation algorithm
- ✦ Algorithm that we can constrain (for streaming segmentation)
- ✦ Initialization free (*i.e.* no prior user interaction or parameters, *e.g.* Snakes, GrabCut)
- ✦ Provide variety of approaches for clustering and merging.

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✦ *Mean-Shift [Comaniciu and Meer, 2002]*

✦ *Normalized cuts [Shi and Malik, 1997]*

✦ *k-Means, EM / Mixture of Gaussians [Bishop 2006]*

✦ *SLIC [Achanta et al. 2012]*

✦ *Watershed approaches*

✦ *Turbo Pixels [Levinshtein et al. 2009]*

✦ *Greedy Graph-Based [Felzenszwalb and Huttenlocher 2004]*

✦ *etc.,*

Agglomerative clustering

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- ◆ Simplest type of clustering:
 - ◆ *Put every item in a single cluster*
 - ◆ *Define distance between clusters*
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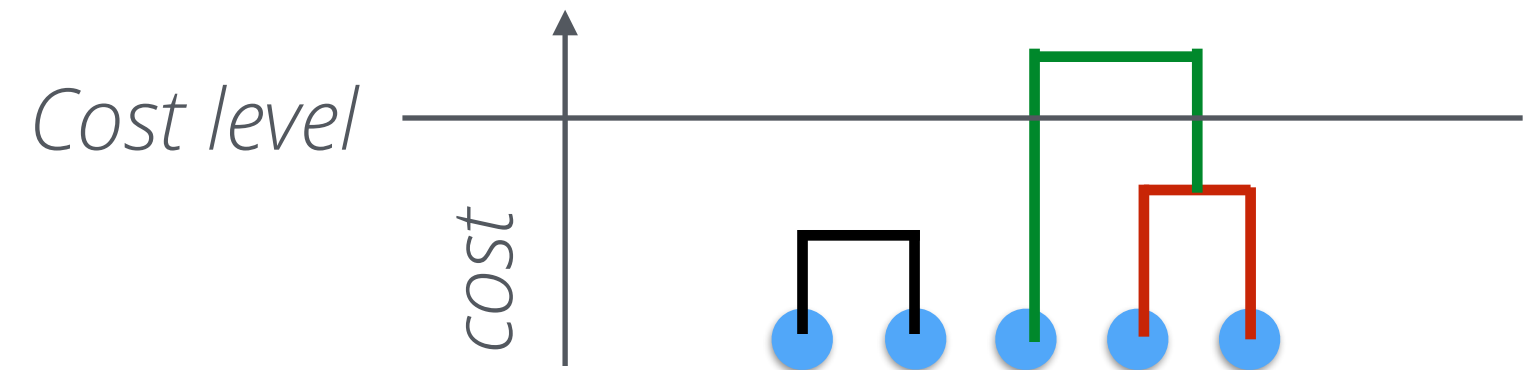
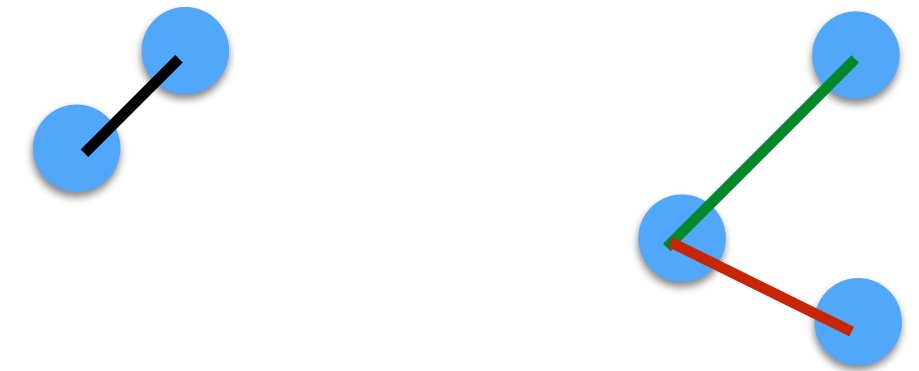
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✦ *Complete-link*

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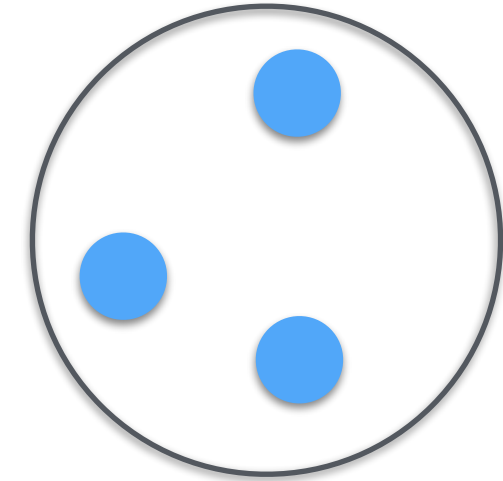
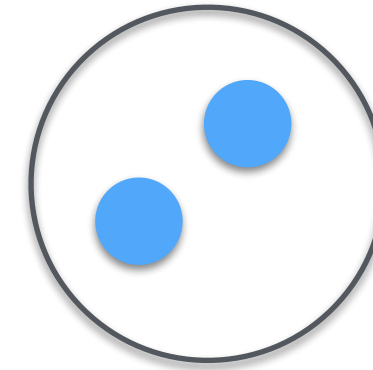
$$\max_{a \in C_1, b \in C_2} ||d(a) - d(b)||$$

✦ *Average-link*
(N = total number of
summands)

$$\frac{1}{N} \sum_{a \in C_1 \cup C_2} \sum_{b \neq a \in C_1 \cup C_2} ||d(a) - d(b)||$$

Agglomerative clustering

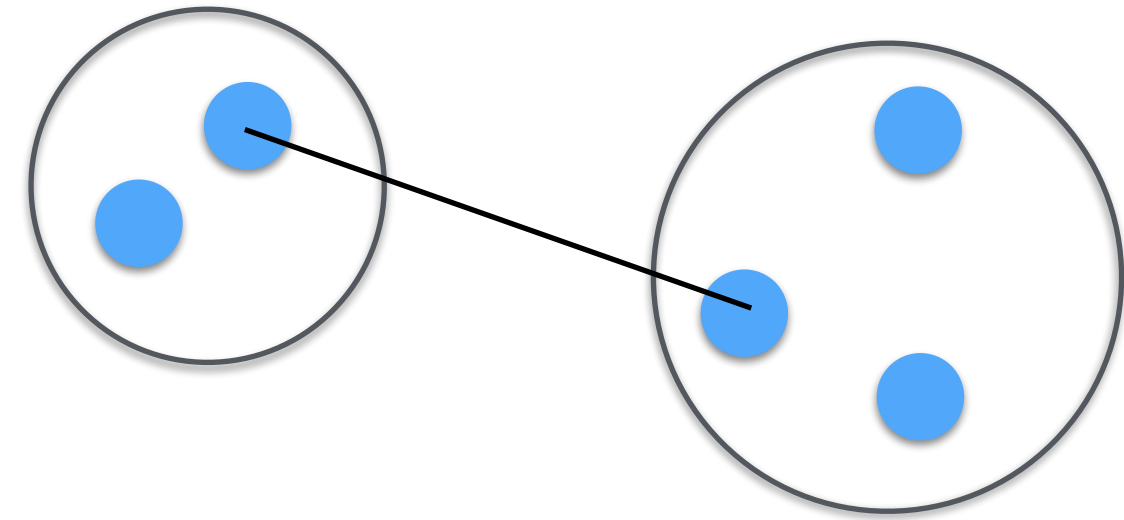
Agglomerative clustering



Agglomerative clustering

✦ Single link:

✦ *Distance between closest two elements*



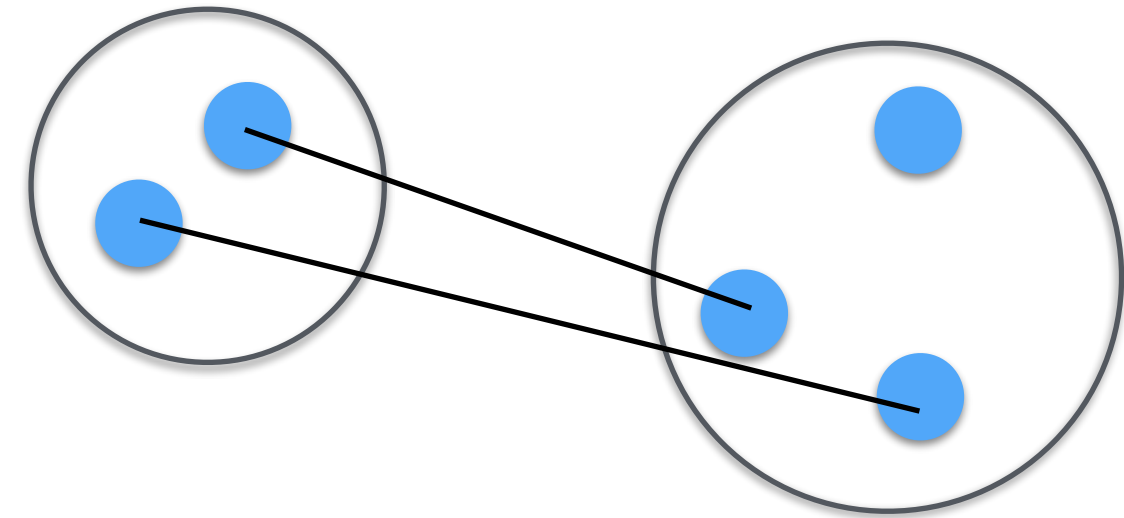
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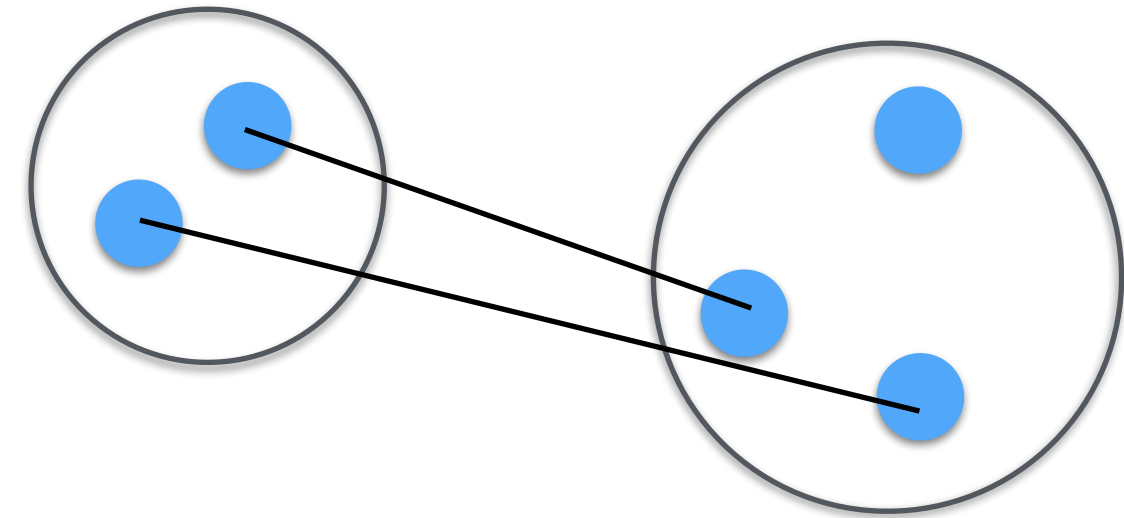
- ◆ *Distance between closest two elements*

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(not drawn)*



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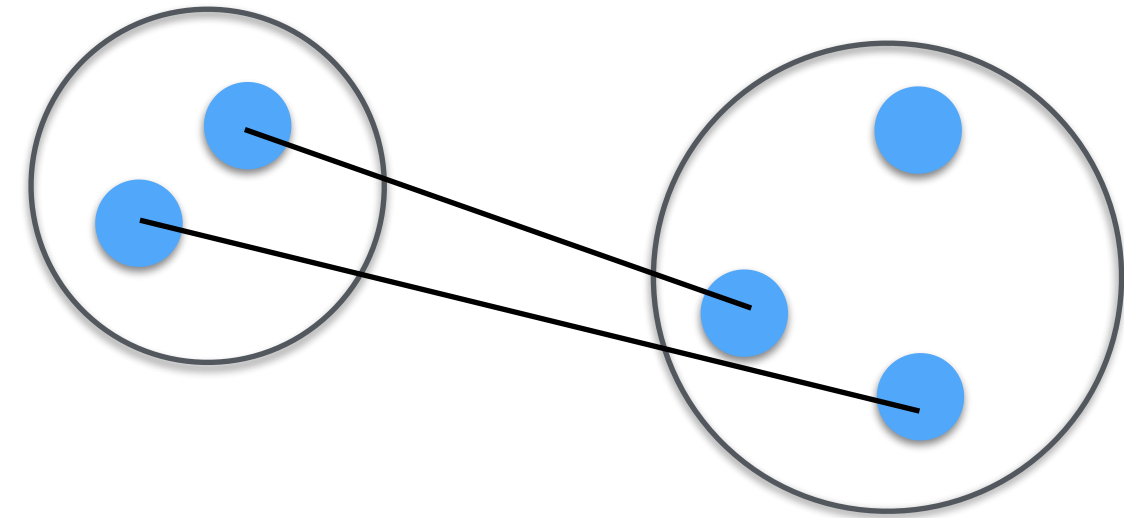
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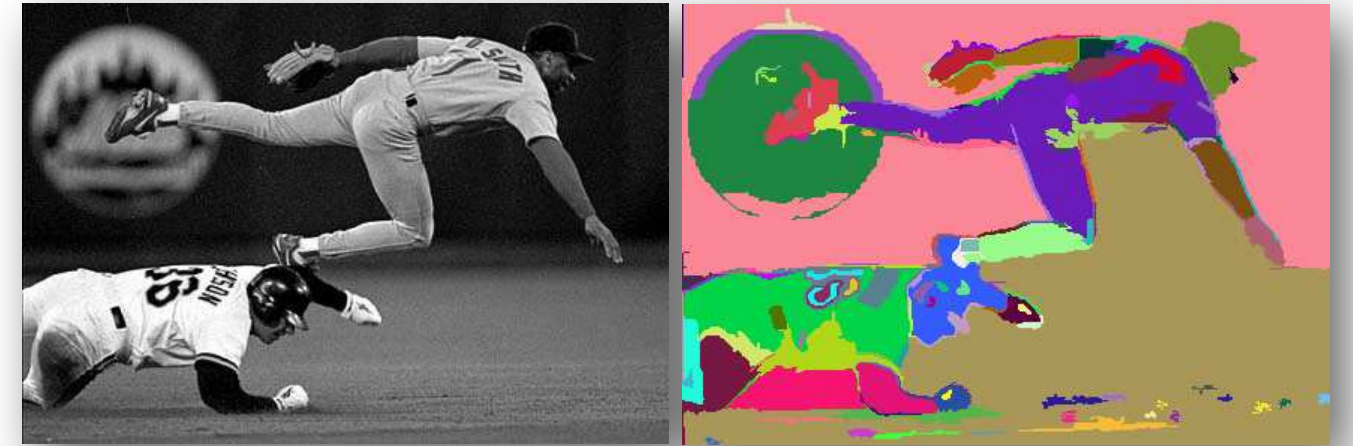
- ◆ *Average distance between all elements
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- ◆ Conclusion:

- ◆ *Only single link merges do not alter cluster distance!*
 - ◆ *1 sec of 360p video: 90 million edges*



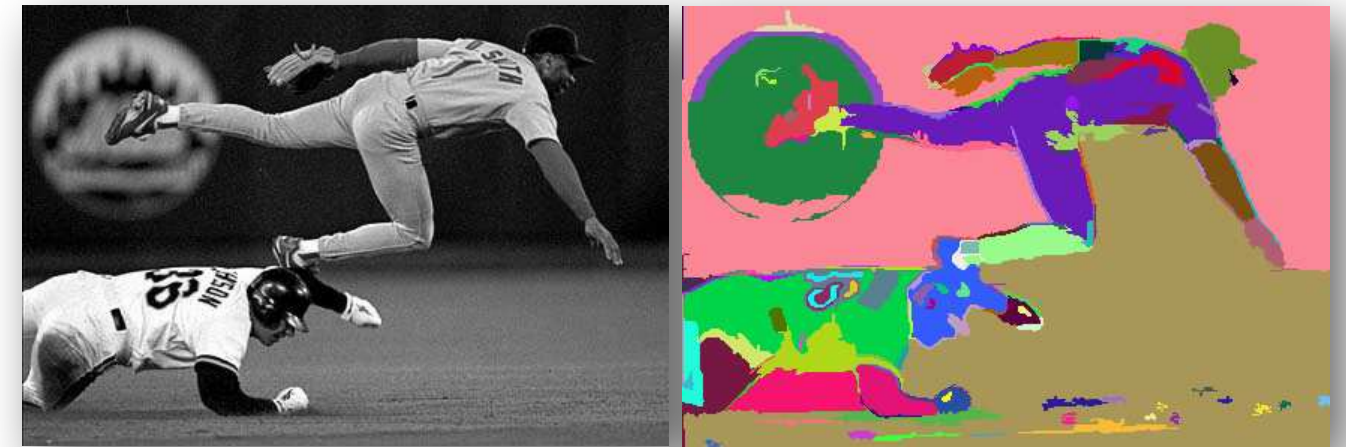
Efficient graph based image segmentation



from [Felzenszwalb and Huttenlocher 2004]

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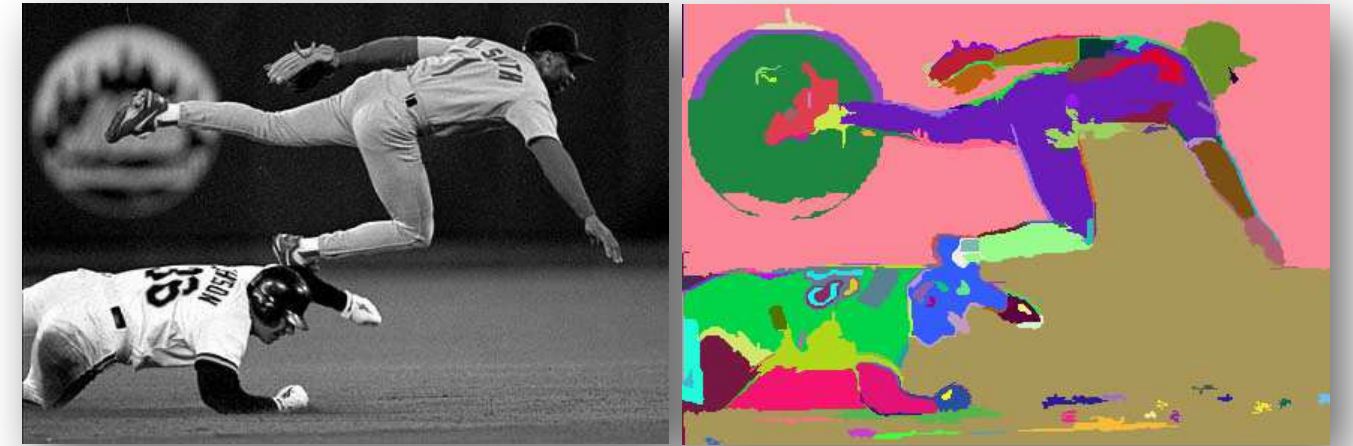
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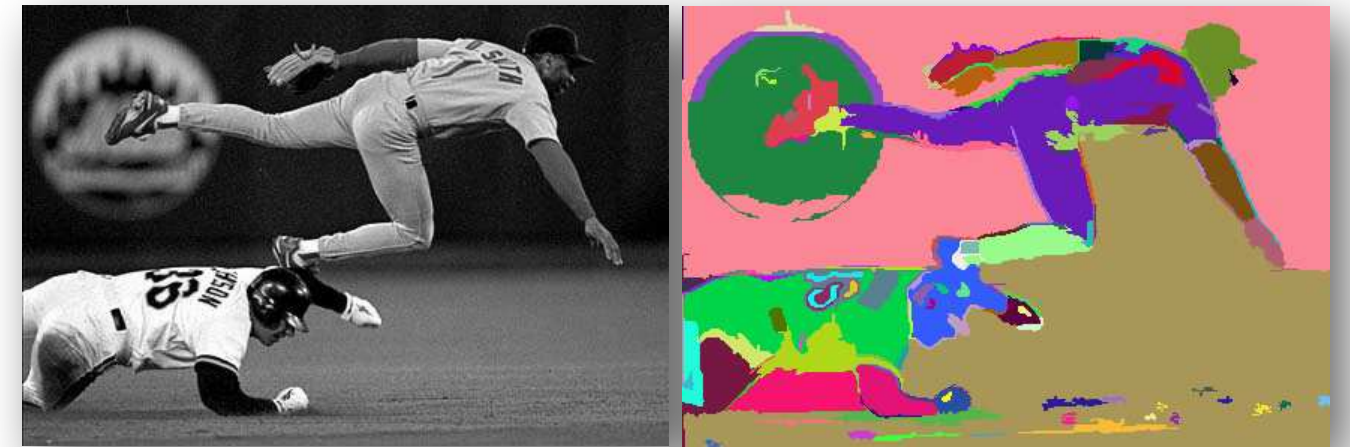
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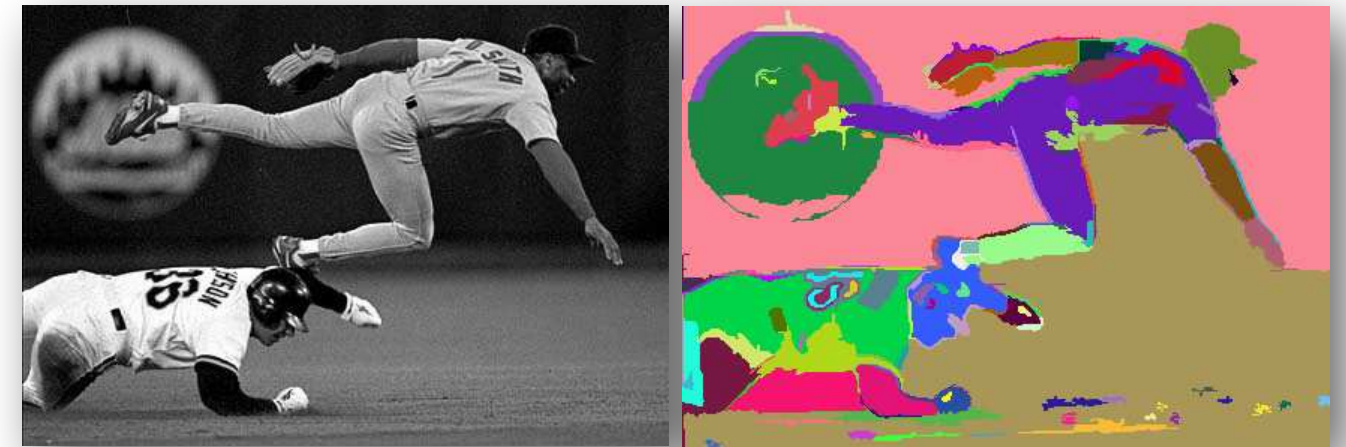
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 - ◆ *Cluster distance: Diff. pixel appearance*



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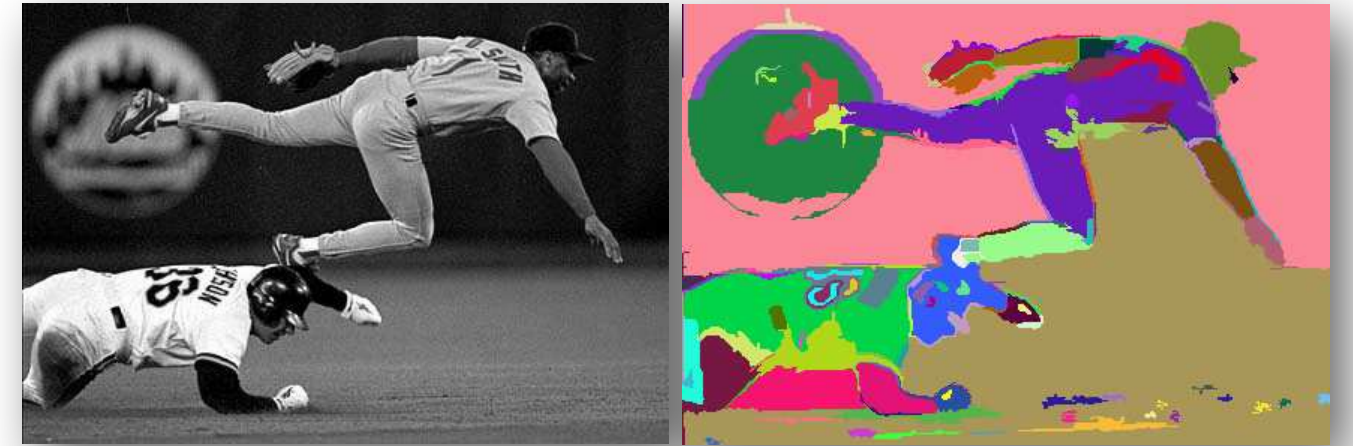
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 - ◆ *Int(C_i): last edge weight for each cluster (height from dendrogram)*
 - ◆ *Termination criteria:*



from [Felzenszwalb and Huttenlocher 2004]

$$\min_{a \in C_1, b \in C_2} ||d(a) - d(b)|| = \text{Int}(C_1 \cup C_2) > \min(\text{Int}(C_1) + \tau(C_1), \text{Int}(C_2) + \tau(C_2))$$

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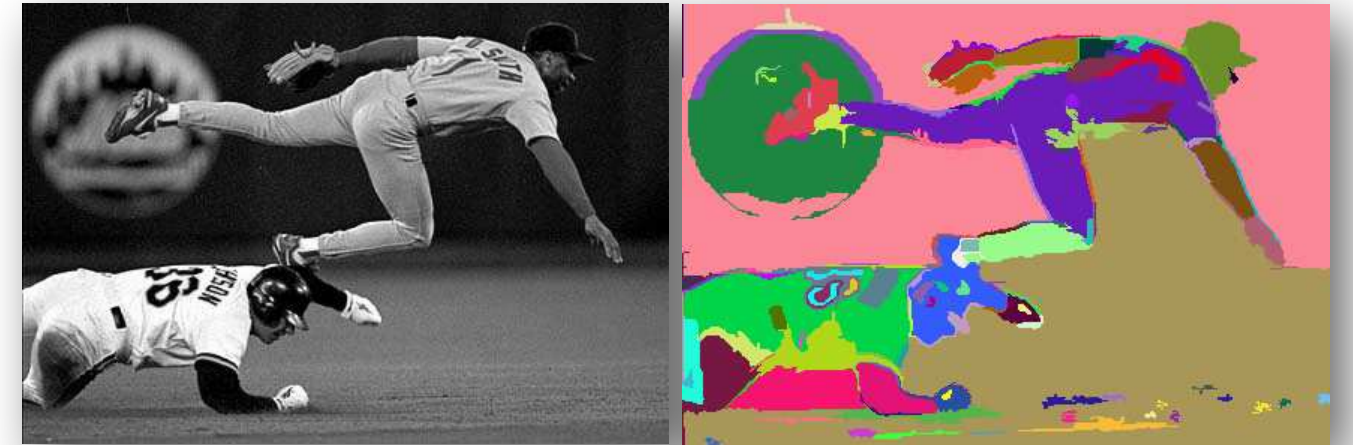
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Efficient graph based image segmentation

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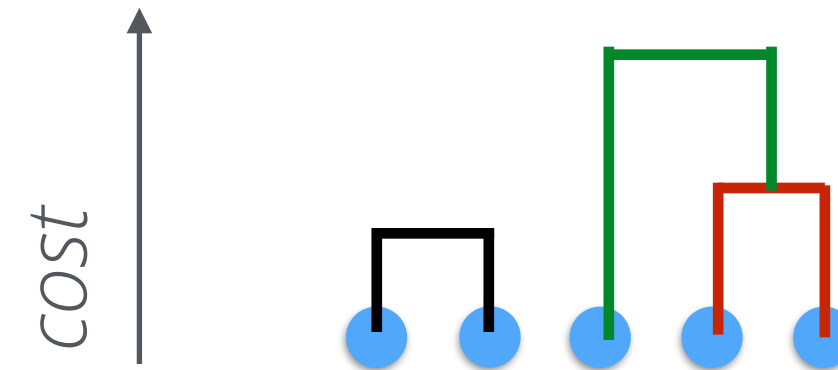
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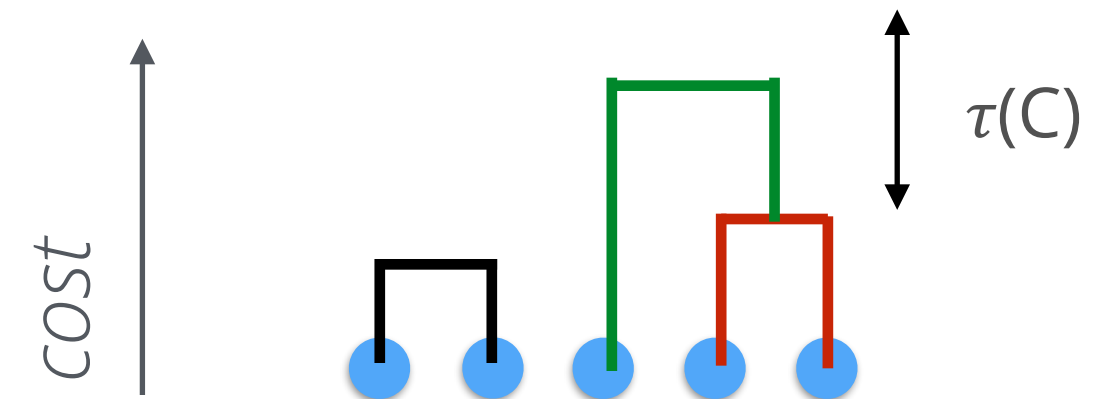
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✦ Relative test

✦ *space decreases with region size*



Efficient graph based image segmentation

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- ✦ Important take-away points

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 - ✦ Monotonic criteria: Once violated, the two clusters won’t be merged

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 - ✦ [Felzenszwalb and Huttenlocher 2004] is single link agglomerative clustering
 - ✦ “Local” termination criteria w.r.t. dendrogram spacing
 - ✦ Monotonic criteria: Once violated, the two clusters won’t be merged
 - ✦ **Also:** Any other monotonic criteria will do

Efficient graph based video segmentation

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- ✦ Applying the “Local” termination criteria to video is problematic
 - ✦ $\tau(C) = \text{constant} / |C|$ decreases with region size

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- ✦ Applying the “Local” termination criteria to video is problematic
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- ✦ For video:
 - ✦ *In video, region volume \gg region area for images*
 - ✦ *Either increase constant (more segmentation errors)*
 - ✦ *Or: Have many small regions*

Efficient graph based video segmentation

- ✦ Applying the “Local” termination criteria to video is problematic
 - ✦ $\tau(C) = \text{constant} / |C|$ decreases with region size
- ✦ For video:
 - ✦ In video, region volume \gg region area for images
 - ✦ Either increase constant (more segmentation errors)
 - ✦ Or: Have many small regions
- ✦ For practical implementations: $\tau(C) \rightarrow 0$
 - ✦ For large homogenous regions:
 \Rightarrow Regions are broken into small pieces
 - ✦ For textured regions: Additional merges required to achieve minimum region size

Homogenous regions

$$\tau(C) \rightarrow 0$$



Homogenous regions

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Introducing additional merges



with forced merges



without forced merges

Results use new merge criteria, not [Felzenszwalb and Huttenlocher 2004]

Introducing additional merges

- ◆ Forced merges: Merge everything with edge weight < 1 intensity / compression level
- ◆ Regular merges: [Felzenszwalb and Huttenlocher 2004] local criteria
- ◆ Small region merges: also [Felzenszwalb and Huttenlocher 2004]



with forced merges



without forced merges

Results use new merge criteria, not [Felzenszwalb and Huttenlocher 2004]

Introducing additional merges

- ◆ Forced merges: Merge everything with edge weight < 1 intensity / compression level
- ◆ Regular merges: [Felzenszwalb and Huttenlocher 2004] local criteria
- ◆ Small region merges: also [Felzenszwalb and Huttenlocher 2004]



with forced merges



without forced merges

Results use new merge criteria, not [Felzenszwalb and Huttenlocher 2004]

Merge percentages

forced includes merges due to constraints

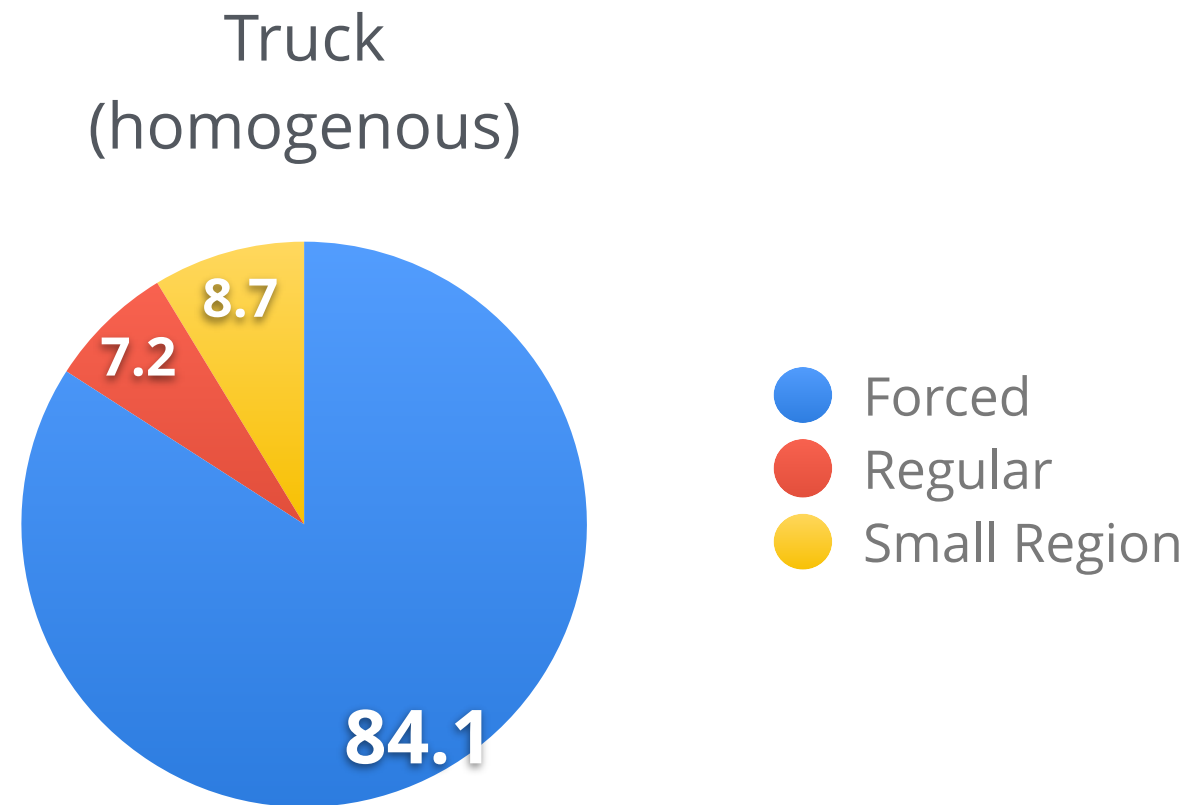
Merge percentages

- ✦ [Felzenszwalb and Huttenlocher 2004] with forced merges

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Merge percentages

✦ [Felzenszwalb and Huttenlocher 2004] with forced merges

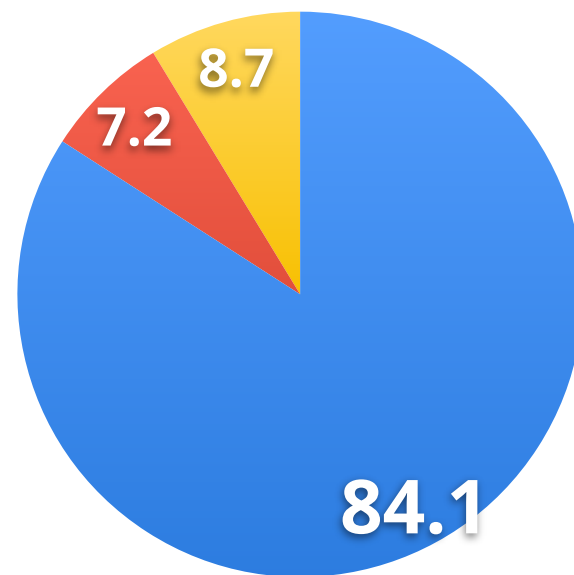


forced includes merges due to constraints

Merge percentages

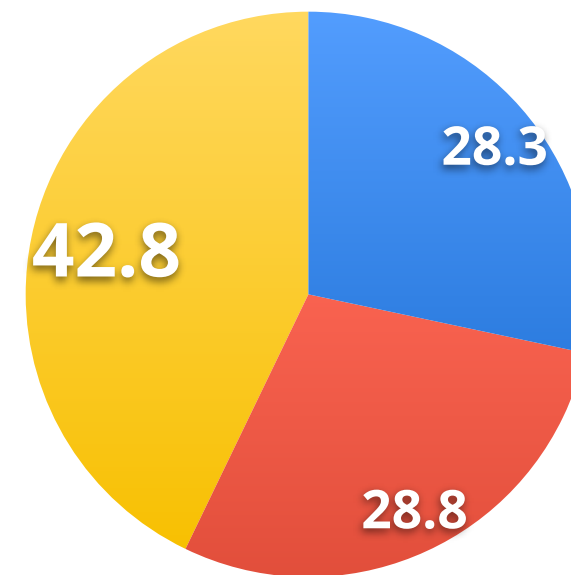
✦ [Felzenszwalb and Huttenlocher 2004] with forced merges

Truck
(homogenous)



● Forced
● Regular
● Small Region

Flowergarden
(textured)



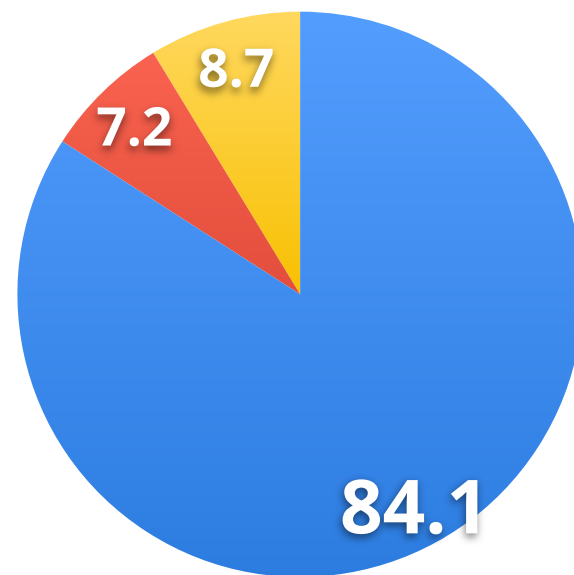
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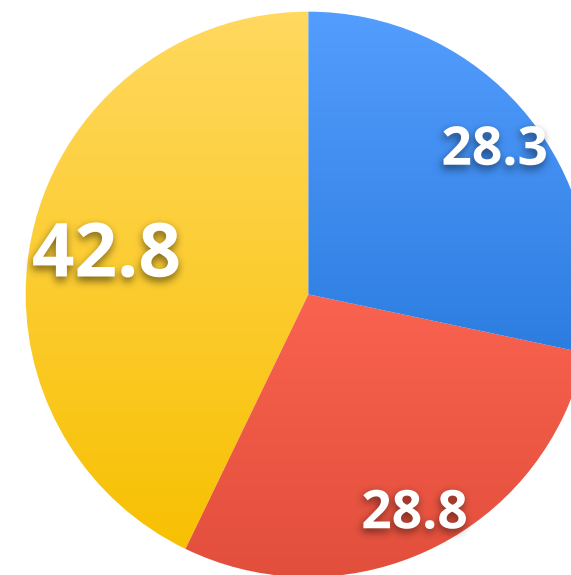
- ✦ [Felzenszwalb and Huttenlocher 2004] with forced merges
- ✦ Regular merges account for less than 1/3 of all merges

Truck
(homogenous)



● Forced
● Regular
● Small Region

Flowergarden
(textured)

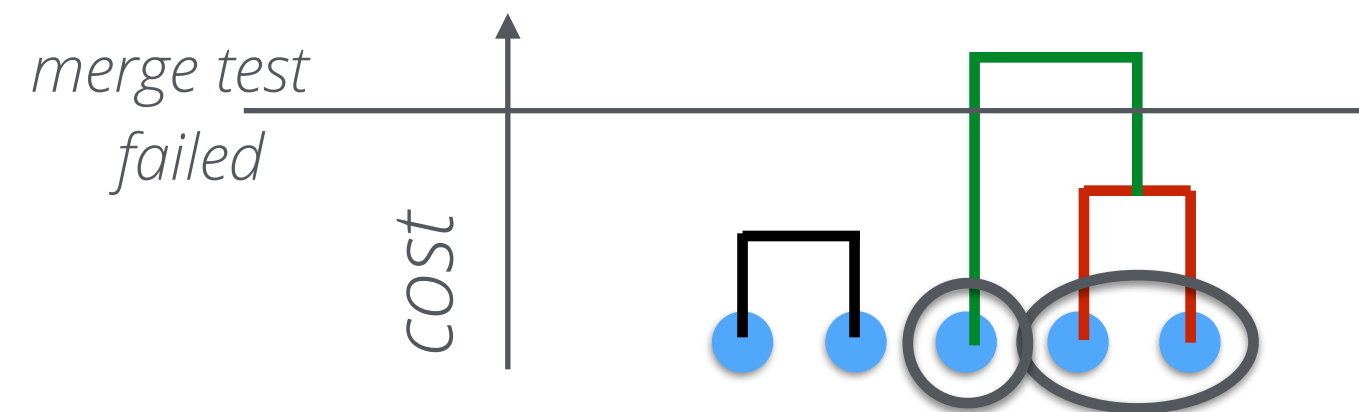


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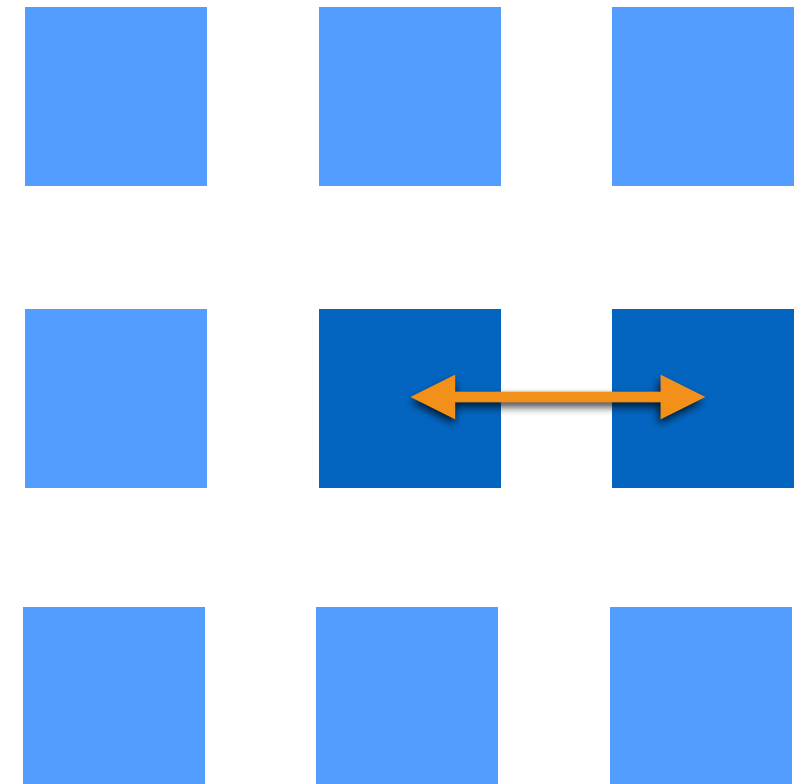
A new merge criteria

- ✦ Recall: **Any** monotonic criteria will do
- ✦ Need more regular merges, distance that accounts for compression levels
- ✦ Avoid “chaining” for single link clustering (small local edge weights can accumulate)
- ✦ Idea:
 - ✦ *Build up local descriptors during merge process*
 - ✦ *Use edge and descriptor distance to determine if a merge should be performed*
 - ✦ *Incorporate small region merges*
 - ✦ *Monotonicity: If merge test fails, label regions as done*



Our new merge criteria

- ✦ Descriptor during merges:
Mean color / Mean flow (any other possible)
- ✦ Merge regions if:
 - ✦ *Edge weight < 1 intensity level and descriptor distance $< 20\%$
(allow for variability but control cutoff)*
 - ✦ *Edge weight ≥ 1 intensity level and descriptor distance $< 5\%$ intensity range*
 - ✦ *One of them is too small*
- ✦ If violated: Flag as done (monotonicity!)

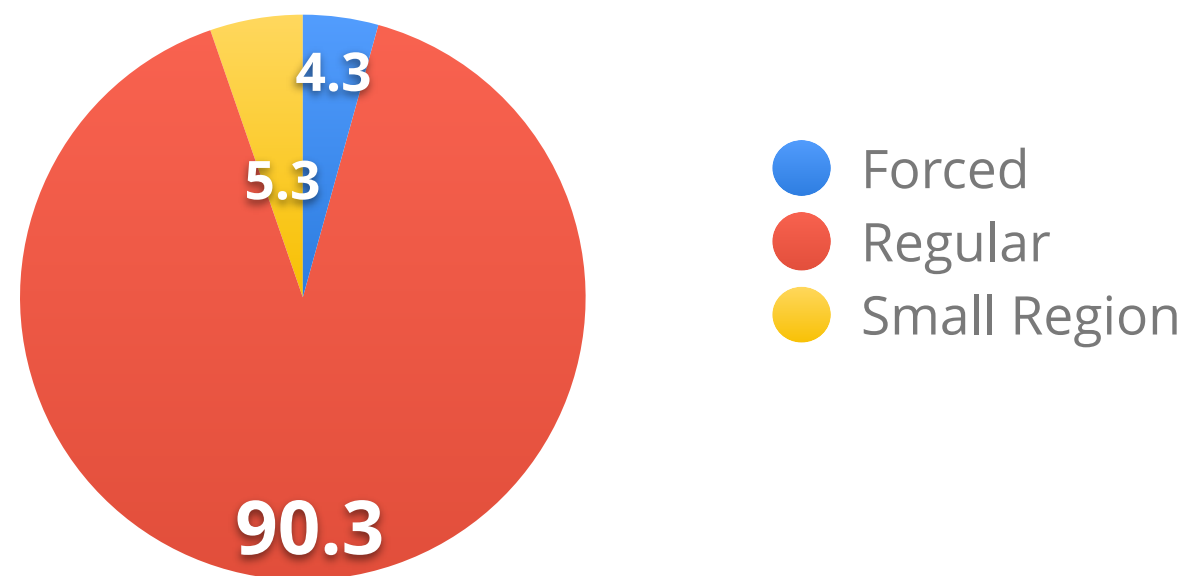


Merge percentages for new criteria

forced includes merges due to constraints

Merge percentages for new criteria

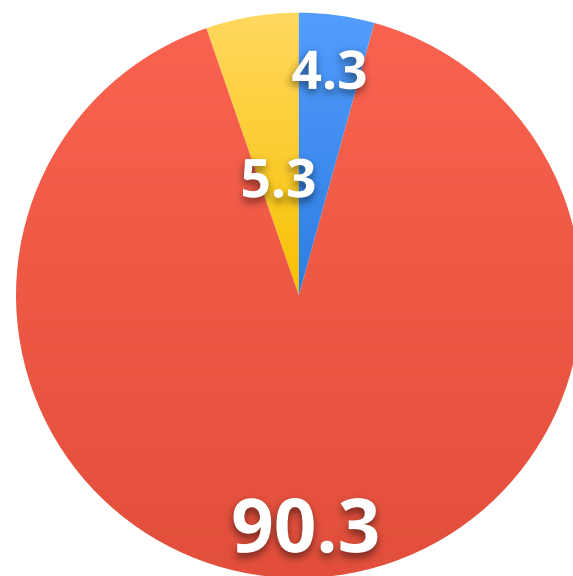
Truck
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forced includes merges due to constraints

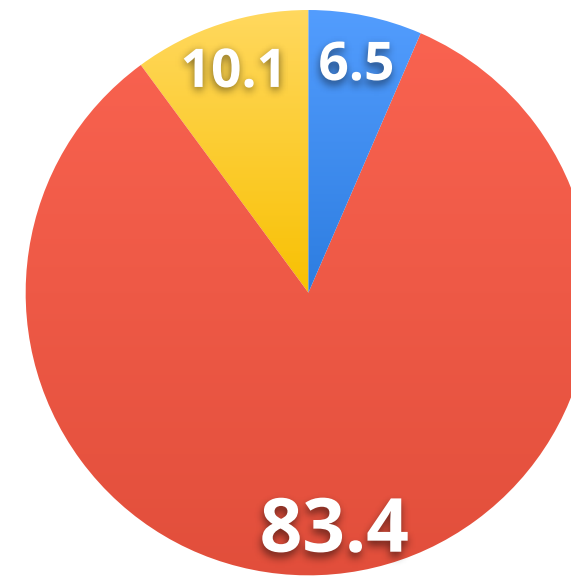
Merge percentages for new criteria

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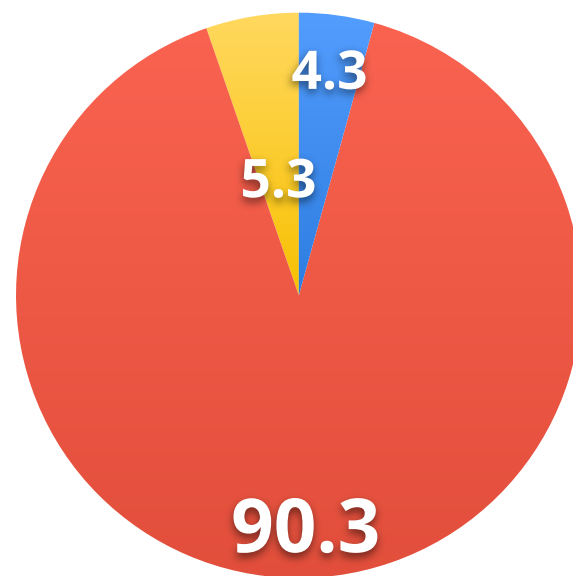
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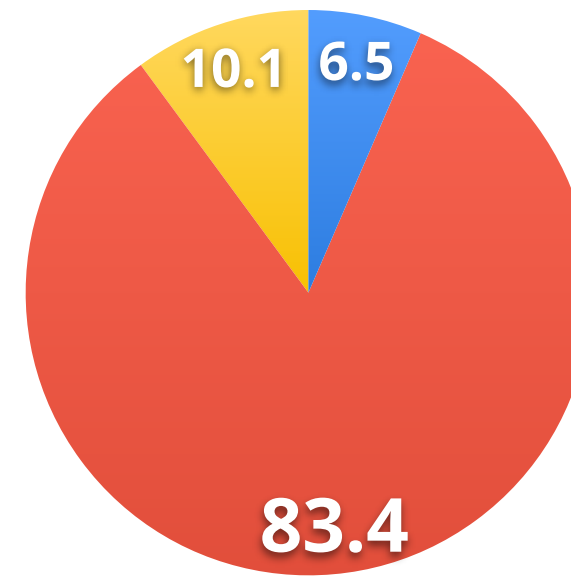
- ✦ Regular merges account for more than 80% of all merges! (as opposed to less than 1/3 of all merges)

Truck
(homogenous)



● Forced
● Regular
● Small Region

Flowergarden
(textured)

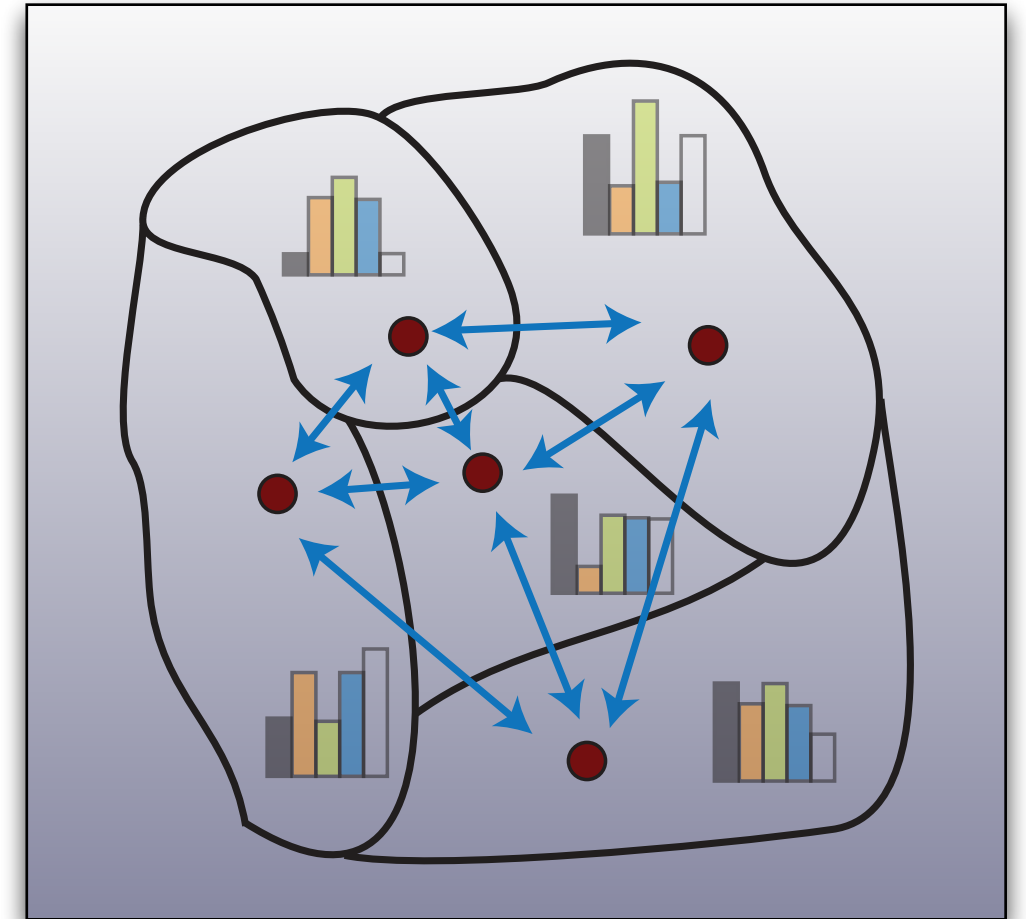


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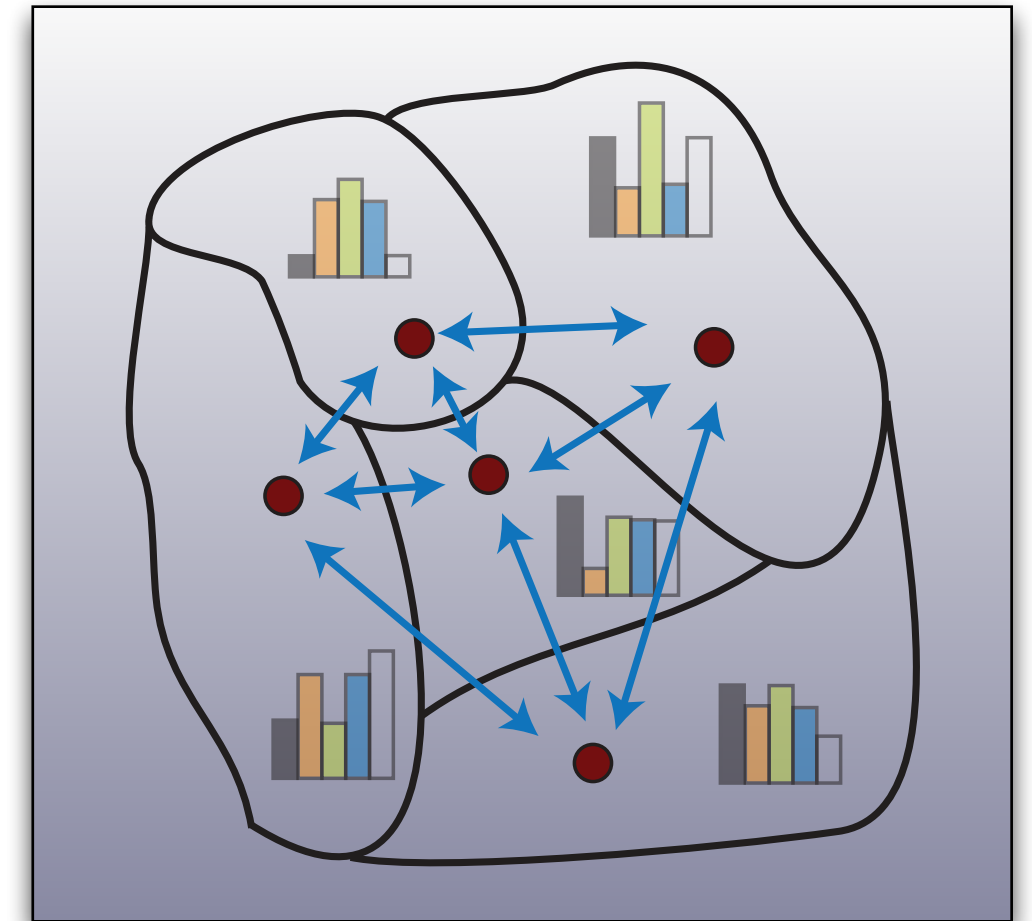
Hierarchical graph-based segmentation

Hierarchical graph-based segmentation



Hierarchical graph-based segmentation

- ✦ Size of regions: Controlled by merge threshold between descriptors (earlier: $\tau(C)$)
- ✦ Consider **Hierarchical segmentation**, instead of tweaking thresholds
- ✦ Build spatio-temporal adjacency graph of regions from **over-segmentation**
- ✦ Edge weights based on similarity of region descriptors (Appearance, texture, motion)
- ✦ Segment regions into “super-regions”
- ✦ Repeat until: Minimum region number reached



Spatio-Temporal Over-Segmentation



original video



over-segmentation

Spatio-Temporal Over-Segmentation



original video



over-segmentation

Hierarchical Segmentation



Over-segmentation



Hierarchy at 20%

Hierarchical Segmentation



Over-segmentation



Hierarchy at 20%

Hierarchical Segmentation



Hierarchy at 20%



Hierarchy at 50%

Hierarchical Segmentation



Hierarchy at 20%



Hierarchy at 50%

Benefits of hierarchical segmentation

Instability in over-segmentation

(identities of region change [lights, window], boundaries are more unstable)



*Hierarchical segmentation
(shown at 50% of height of
segmentation tree)*



*Over-segmentation only
(manually tuned to give similar sized
regions)*

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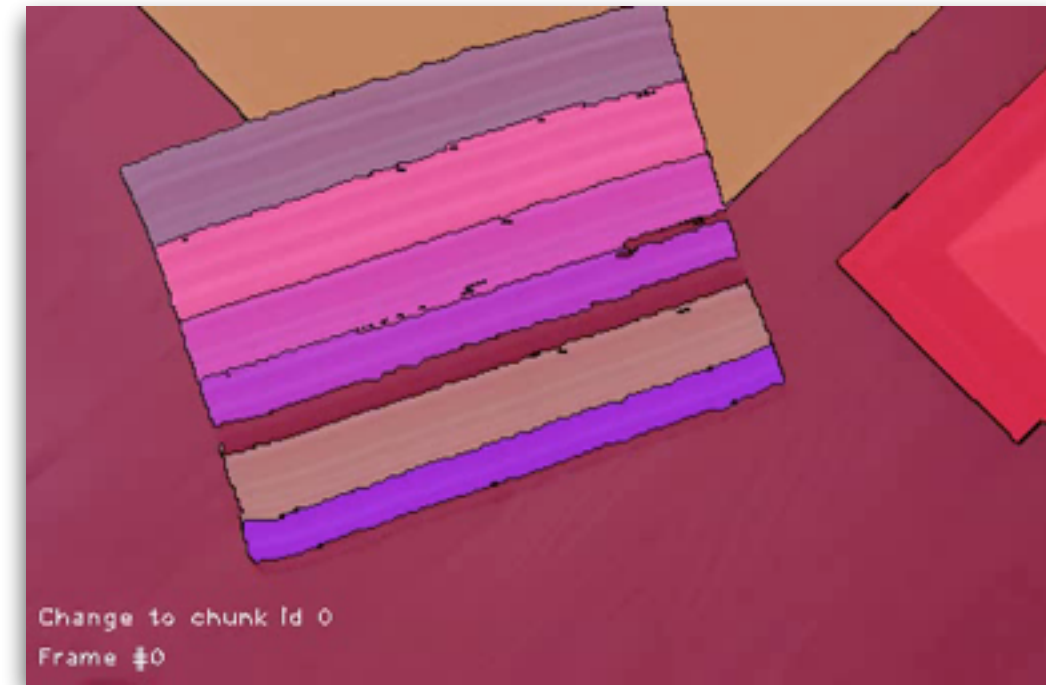
Benefits of hierarchical segmentation



Benefits of hierarchical segmentation



Hierarchical segmentation



*Over-segmentation only
(manually tuned to give similar sized
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Effect of flow as feature

original



no flow

*flow in hierarchical
segmentation*

*flow in over-segmentation &
flow in hierarchical
segmentation*

Effect of flow as feature

original

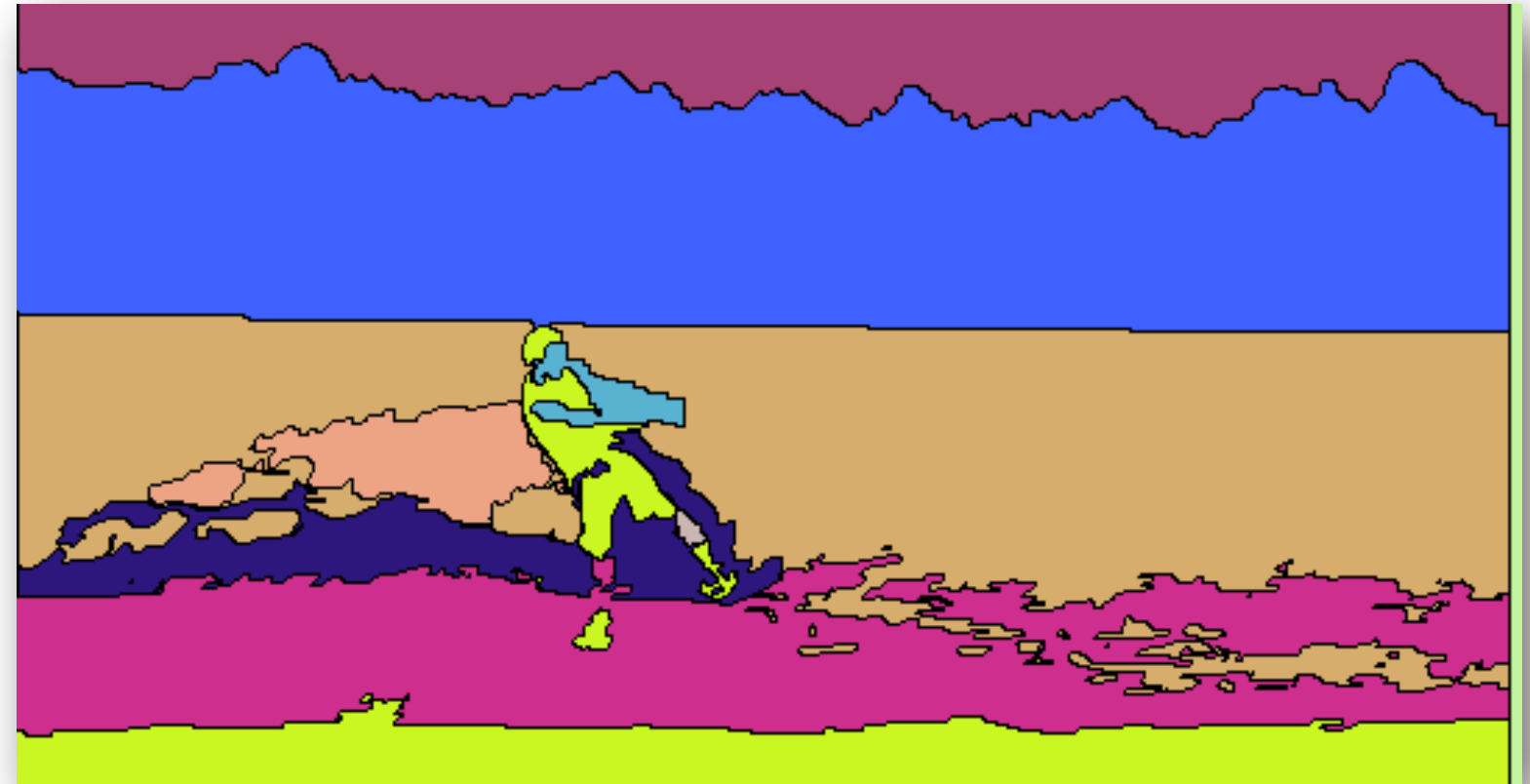


no flow

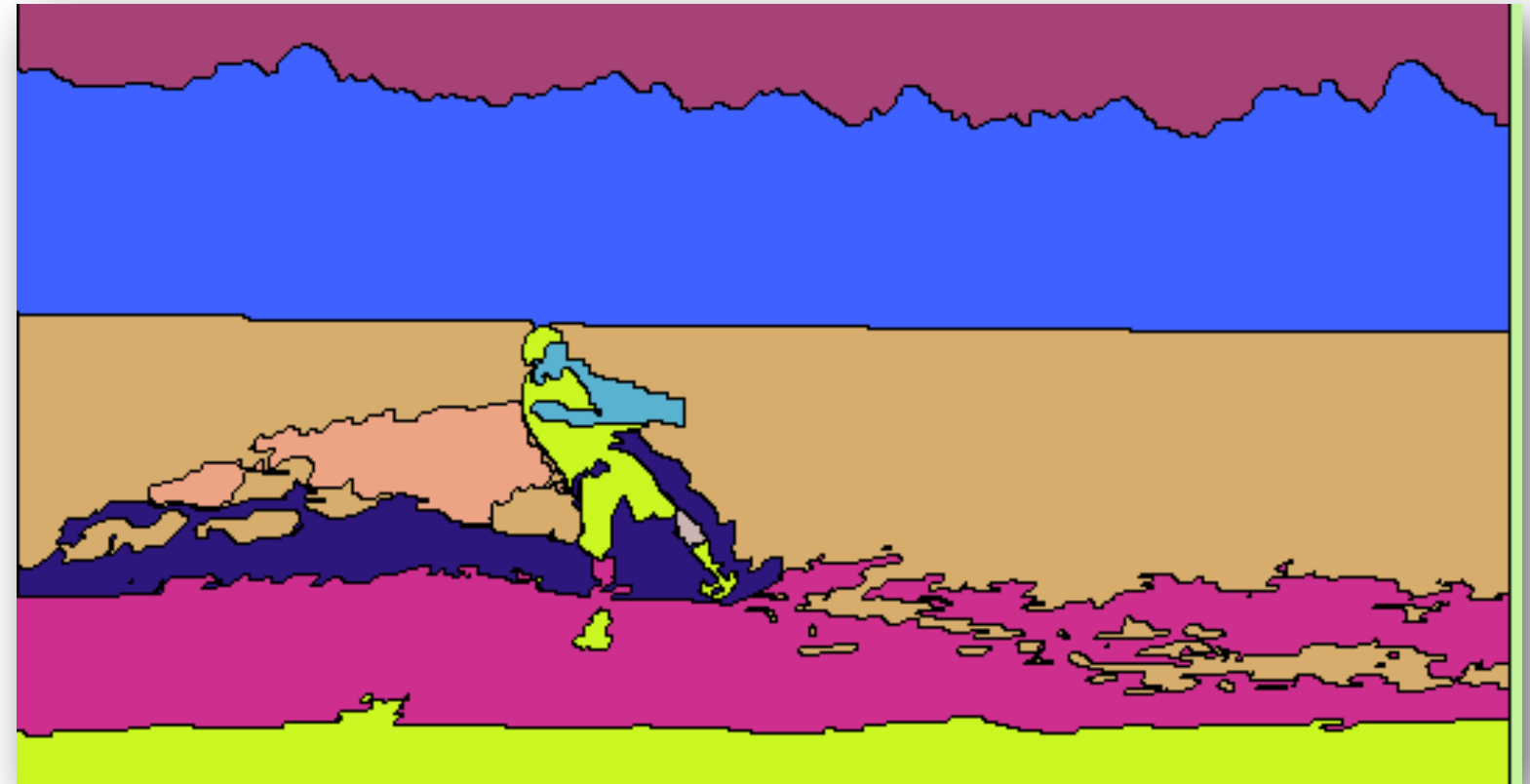
*flow in hierarchical
segmentation*

*flow in over-segmentation &
flow in hierarchical
segmentation*

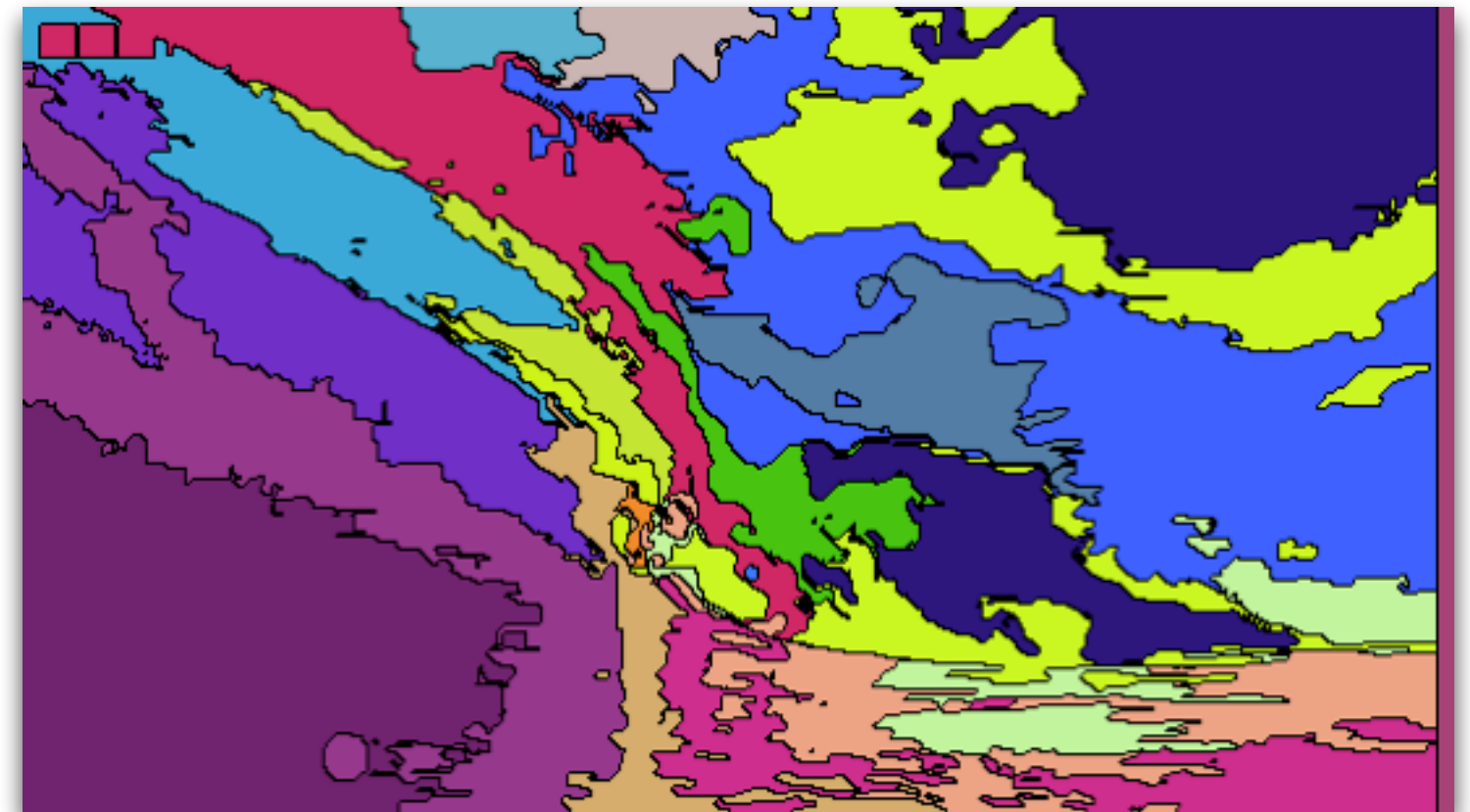
Results



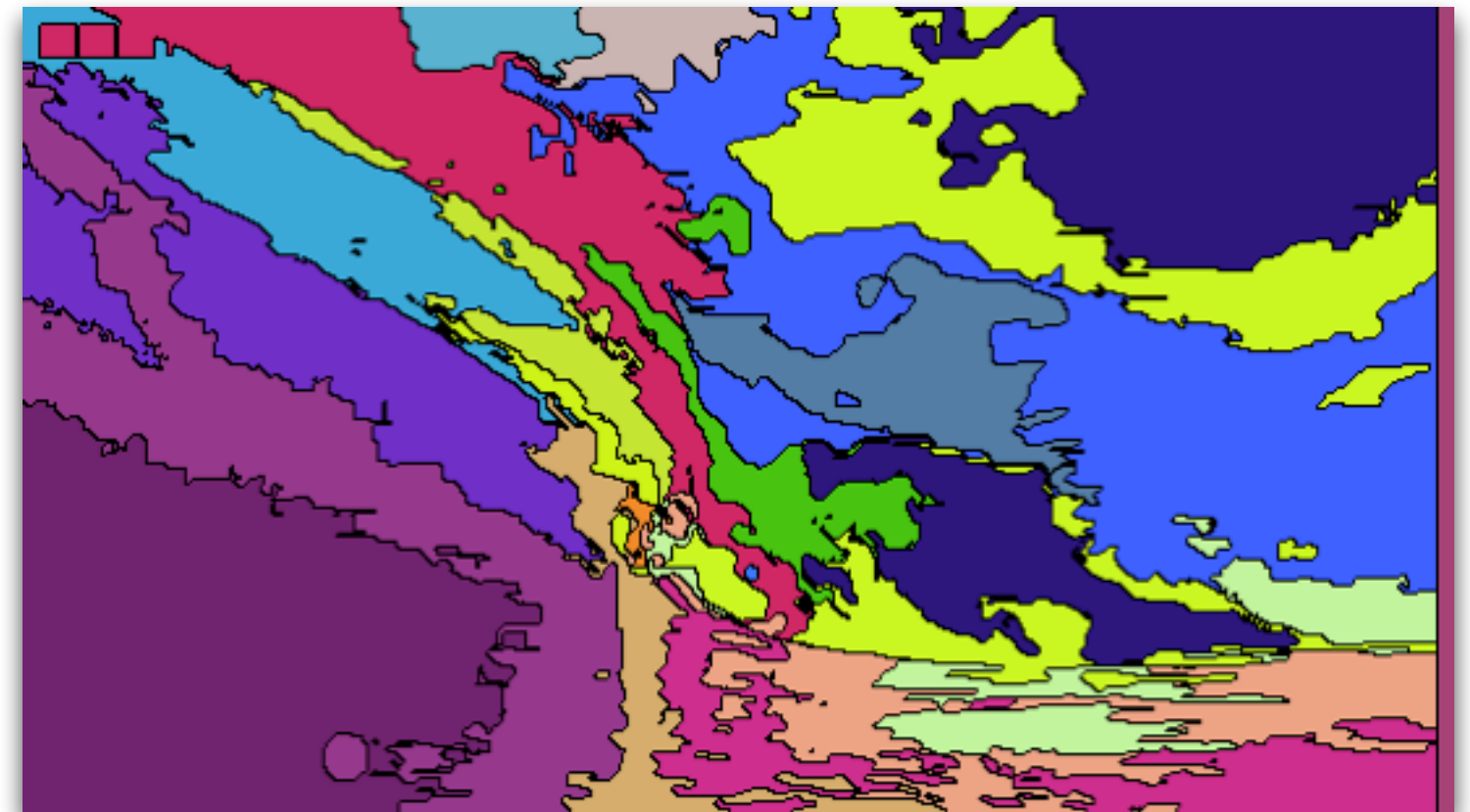
Results



Results



Results



Applications of Video Segmentation

Applications of Video Segmentation

- ✦ Use for Scene Analysis

Applications of Video Segmentation

- ◆ Use for Scene Analysis
 - ◆ *Geometric Context (CVPR 2013)*



Applications of Video Segmentation

- ◆ Use for Scene Analysis
 - ◆ *Geometric Context (CVPR 2013)*
 - ◆ *Objects localization in Videos (ECCV 2013 Workshop on Web-scale Social Media)*



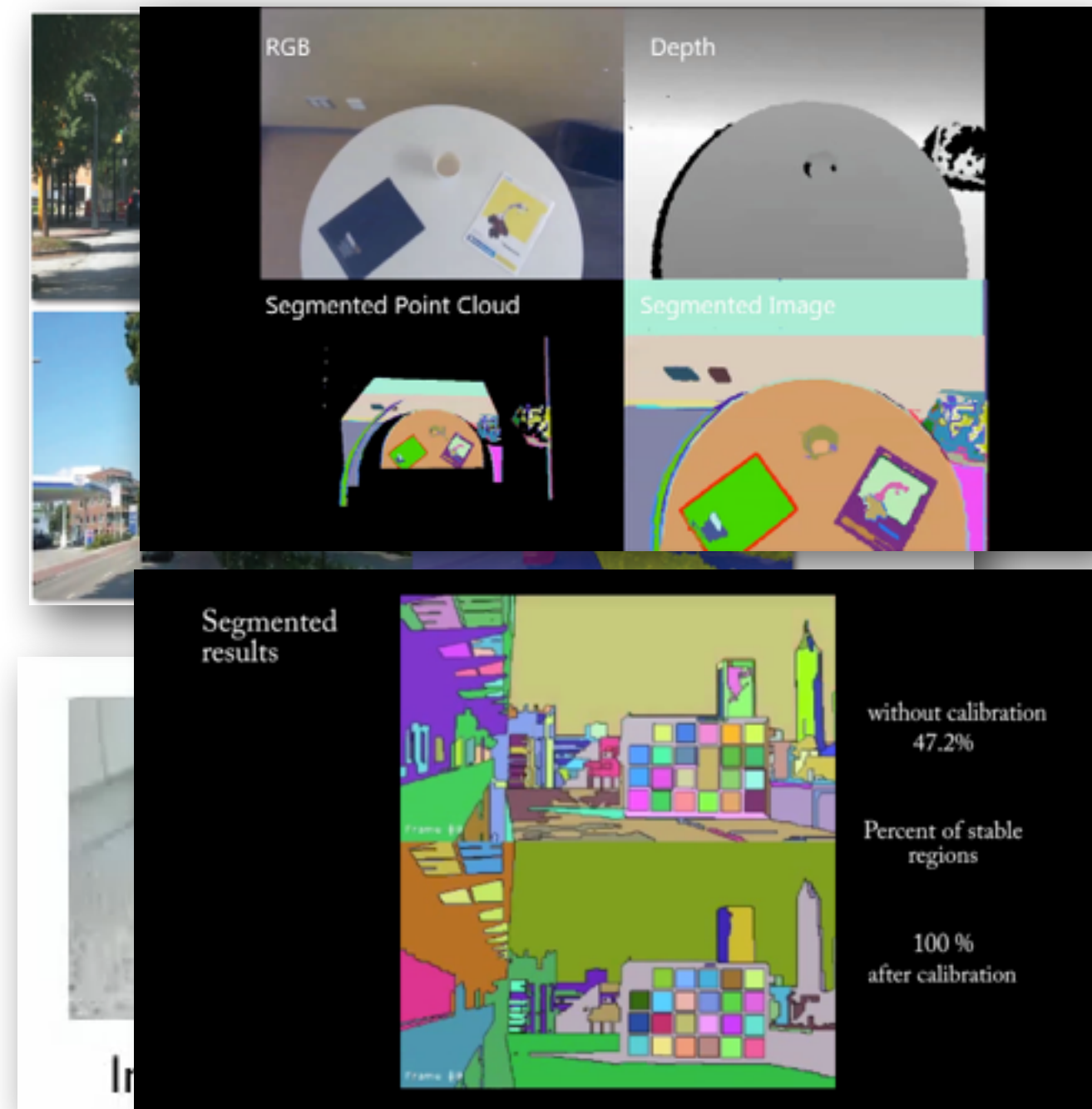
Input video: dog



Result

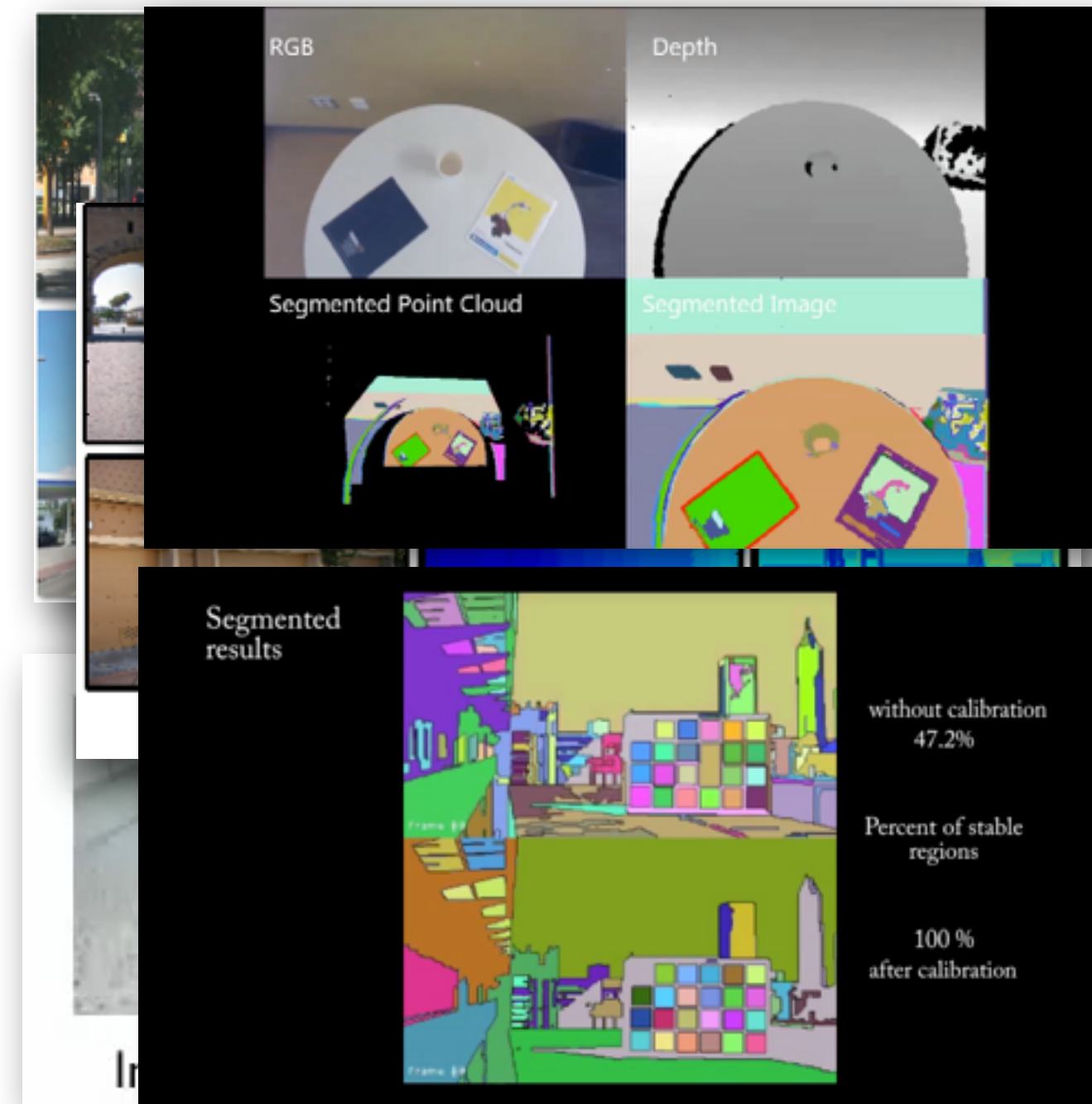
Applications of Video Segmentation

- ◆ Use for Scene Analysis
 - ◆ *Geometric Context (CVPR 2013)*
 - ◆ *Objects localization in Videos (ECCV 2013 Workshop on Web-scale Social Media)*
- ◆ Using RGBD (CVPR 2014)
- ◆ Radiometric Calibration (ICCP 2013)



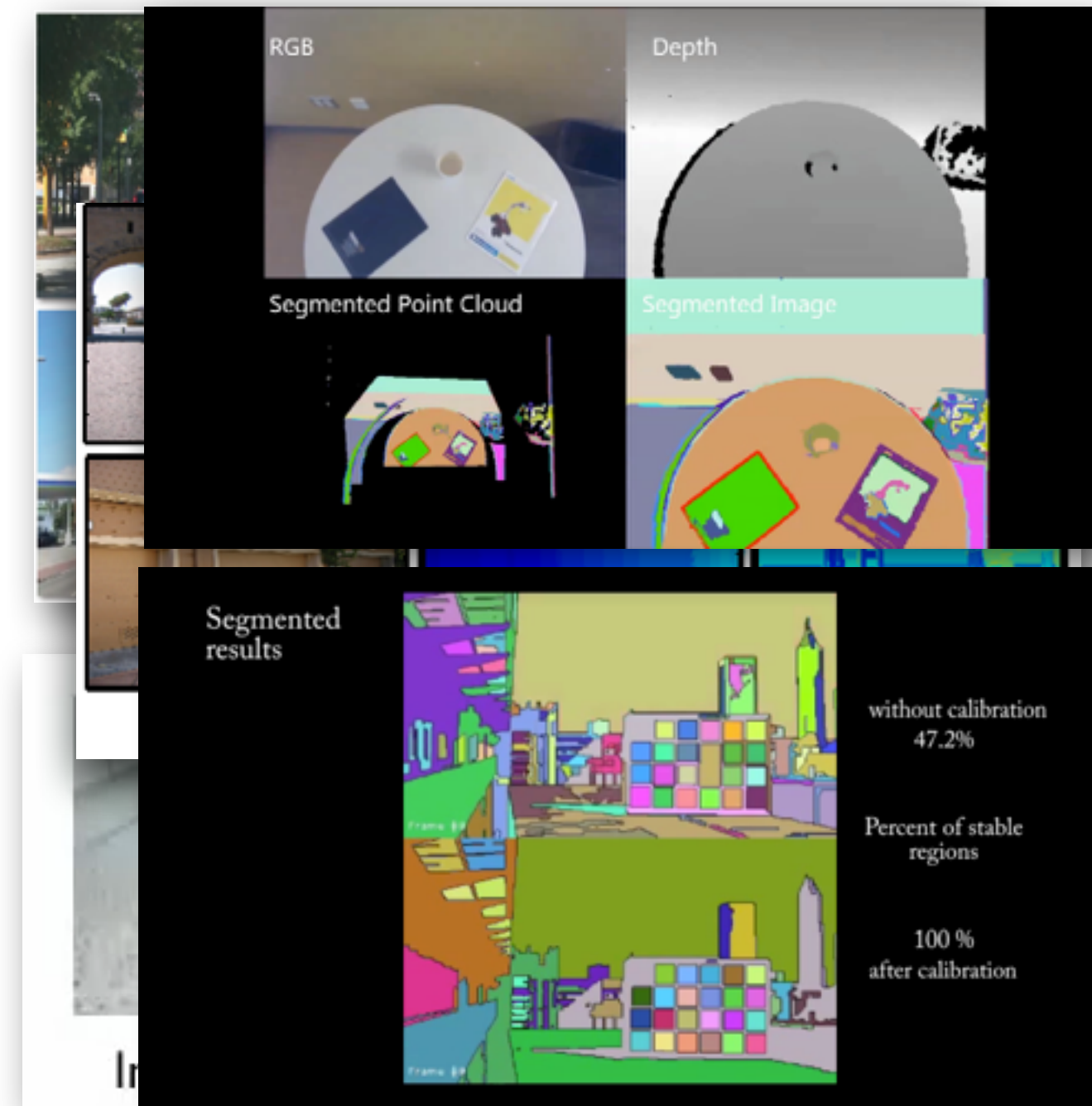
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- ◆ Monocular Depth (BMVC 2014)



Applications of Video Segmentation

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- ◆ Radiometric Calibration (ICCP 2013)
- ◆ Monocular Depth (BMVC 2014)
- ◆ Extracting Occlusion Layers (WACV 2015)



Geometric Context from Video

- ✦ Hoiem, Efros, Hebert, "Geometric Context from a Single Image", *ICCV 2005*.
- ✦ Hussein, Grundmann, Essa, "Geometric Context from Video", *CVPR 2013*.



<http://www.cc.gatech.edu/cpl/projects/videocontext/>





A comprehensive
dataset for
Geometric Context
in Video

A comprehensive
dataset for
Geometric Context
in Video





Results

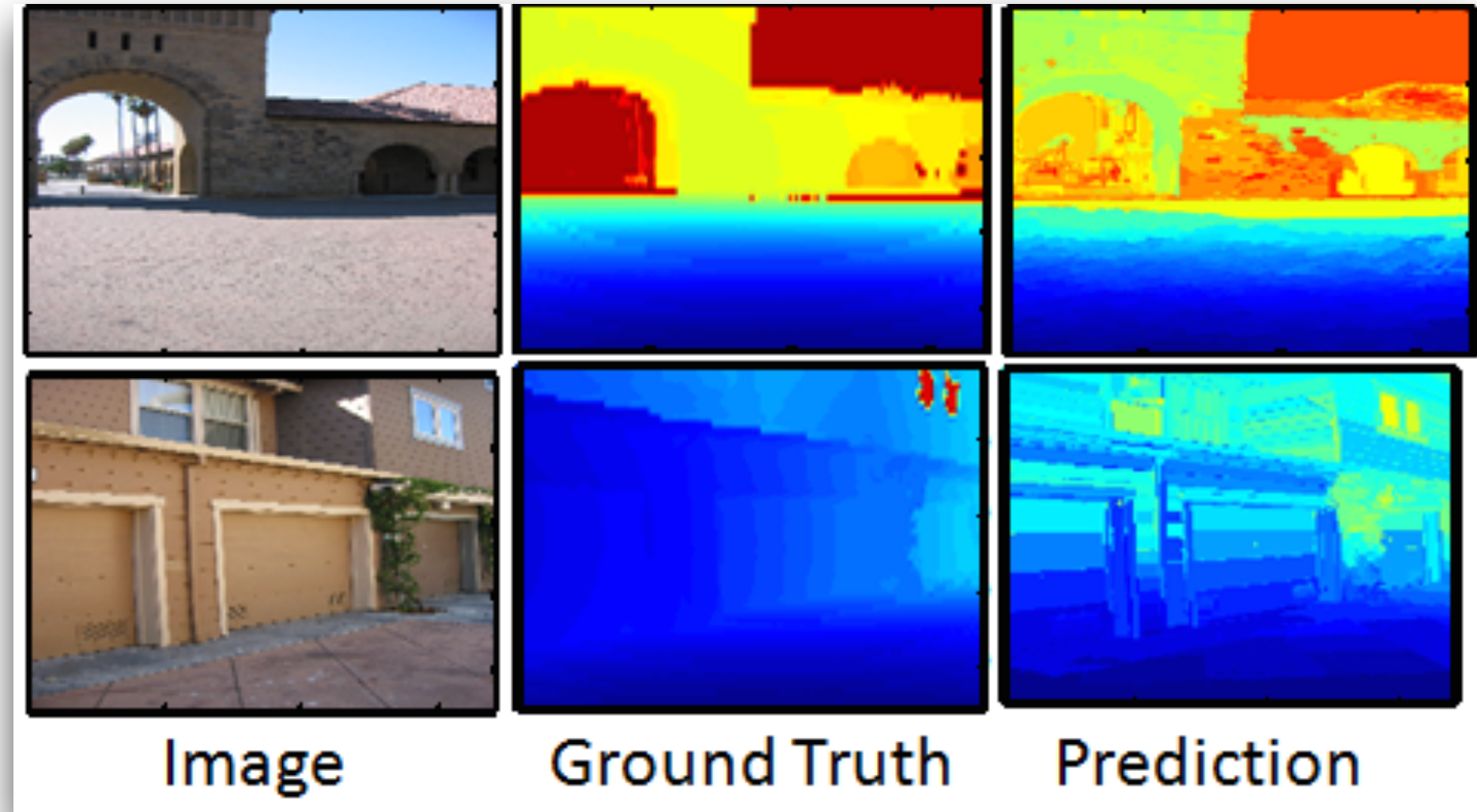
Results

Classification

- ✦ Boosted decision trees
- ✦ 5-Fold cross-validation (63 videos)
- ✦ Main Classifier
 - ✦ *Probability for ground, sky, and vertical*
- ✦ Vertical Classifier
 - ✦ *Probability for solid, porous, and objects*
- ✦ Homogeneity Classifier
 - ✦ *Quality of a segment (single or mix)*

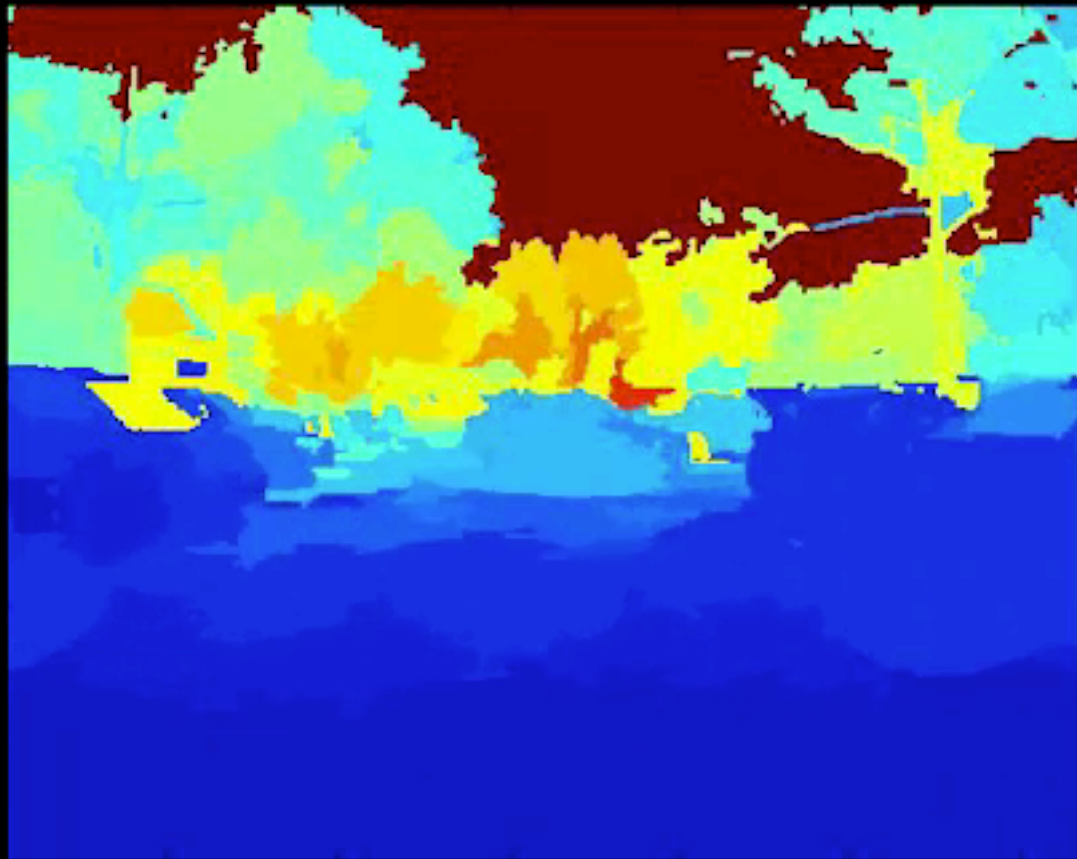
Depth from Videos Using Geometric Context

- ✦ Raza, et al. (2014), BMVC 2014
- ✦ Use segmentation + geometric context to “learn” depth

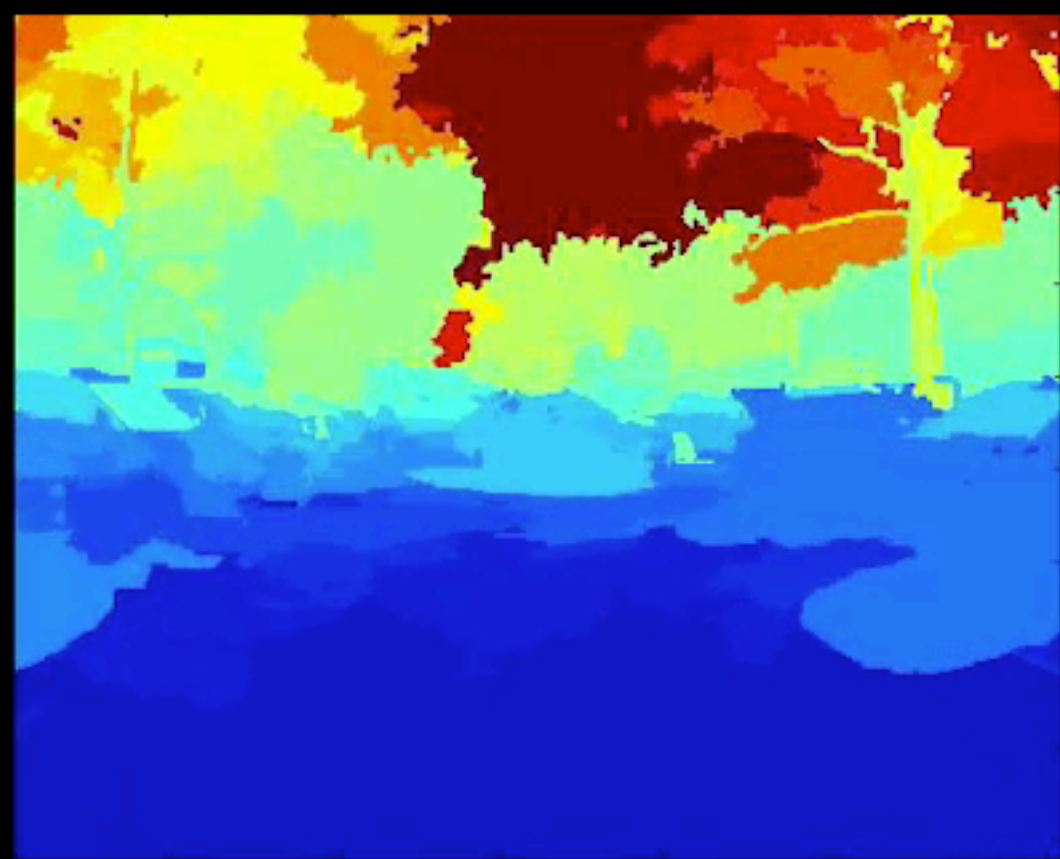




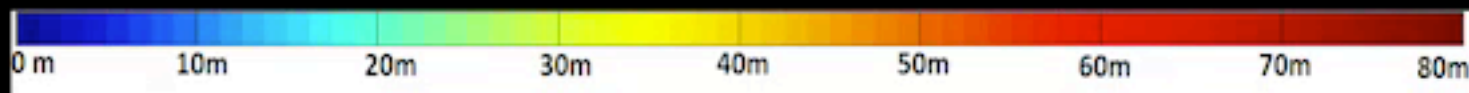
Video



Ground Truth Depth

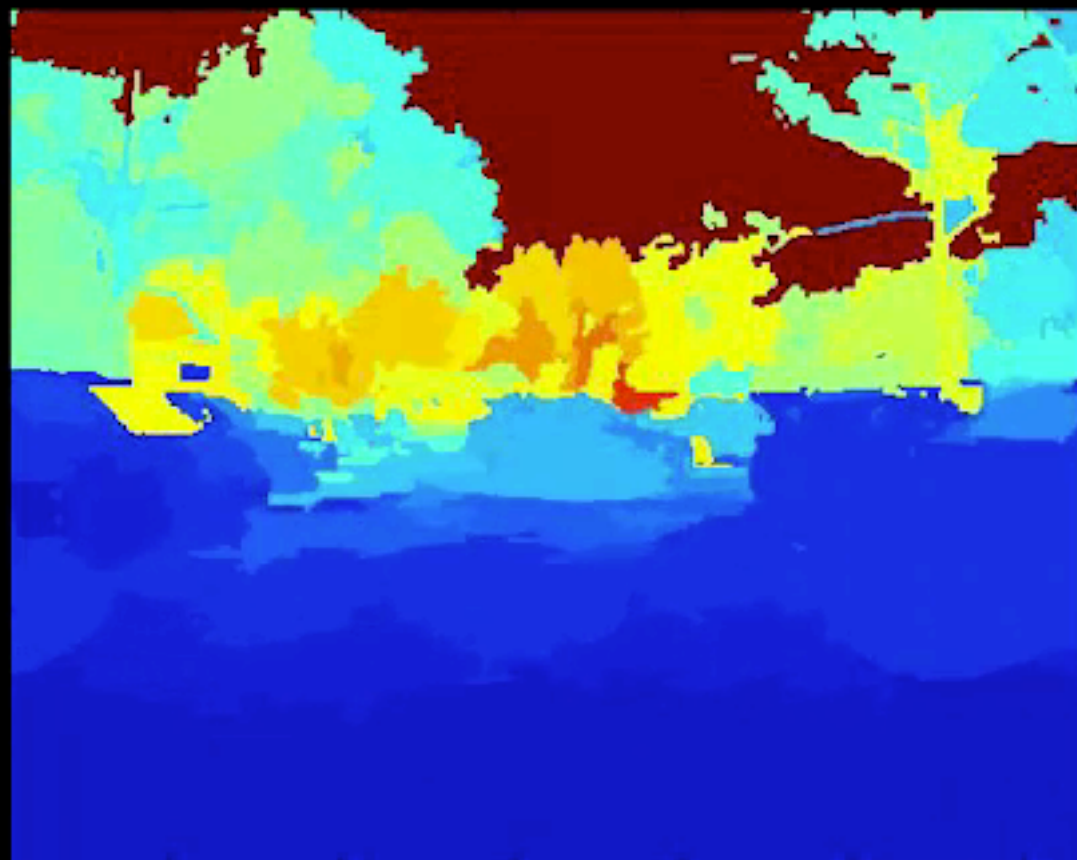


Estimated Depth
(Our Approach)

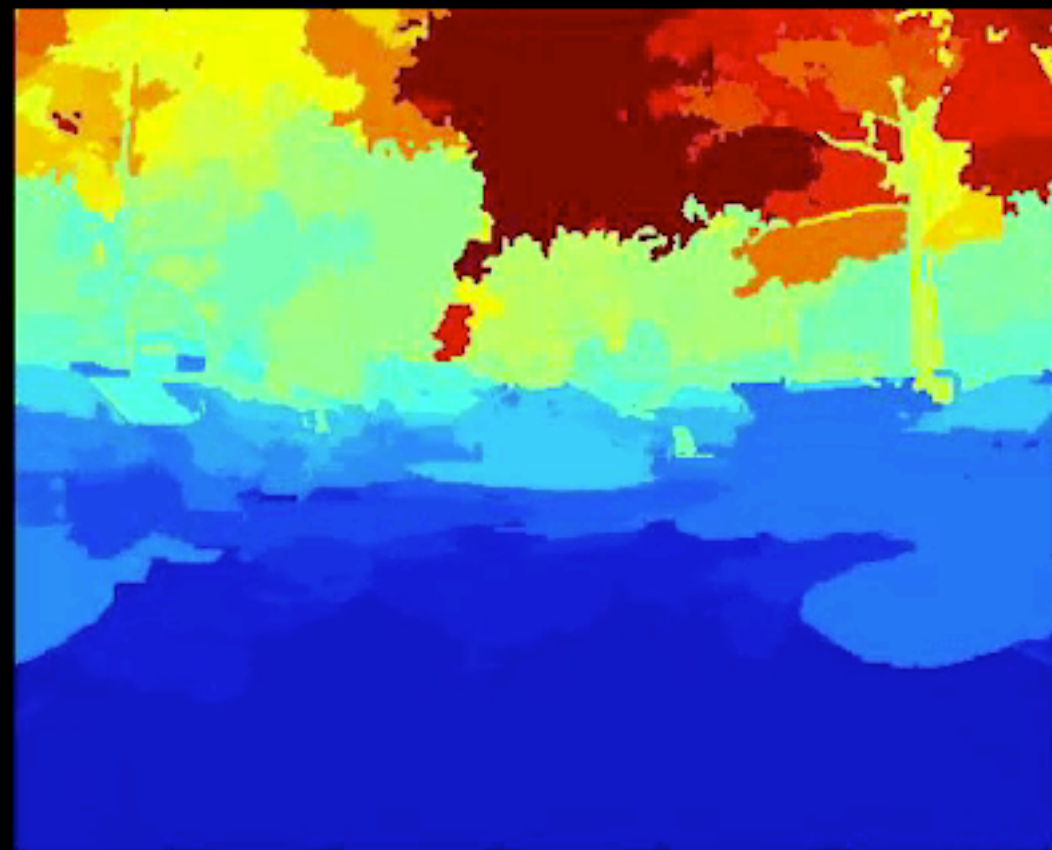




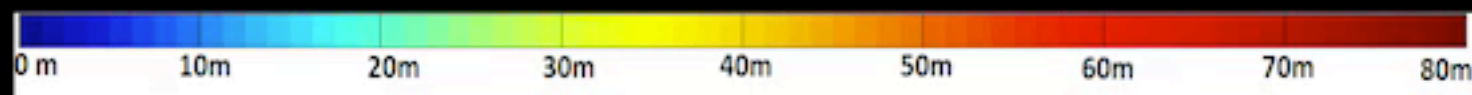
Video



Ground Truth Depth



Estimated Depth
(Our Approach)



Pixels to Semantics (YouTube scale)

- ✦ G. Hartmann, M. Grundmann, J. Hoffman, D. Tsai, V. Kwatra, O. Madani, S. Vijayanarasimhan, I. Essa, J. Rehg, R. Sukthankar
“Weakly Supervised Learning of Object Segmentations from Web-Scale Video” *ECCV Workshop on Web-scale Vision and Social Media, 2012 (Best Paper)*



Input video: dog



Result

Pixels to Semantics (YouTube scale)

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Input video: dog



Result

Weakly Supervised Training Data (video-level tags)



dog



bike



boat



horse



helicopter



transformers



card



robot

Weakly Supervised Training Data (video-level tags)



dog



bike



boat



horse



helicopter



transformers



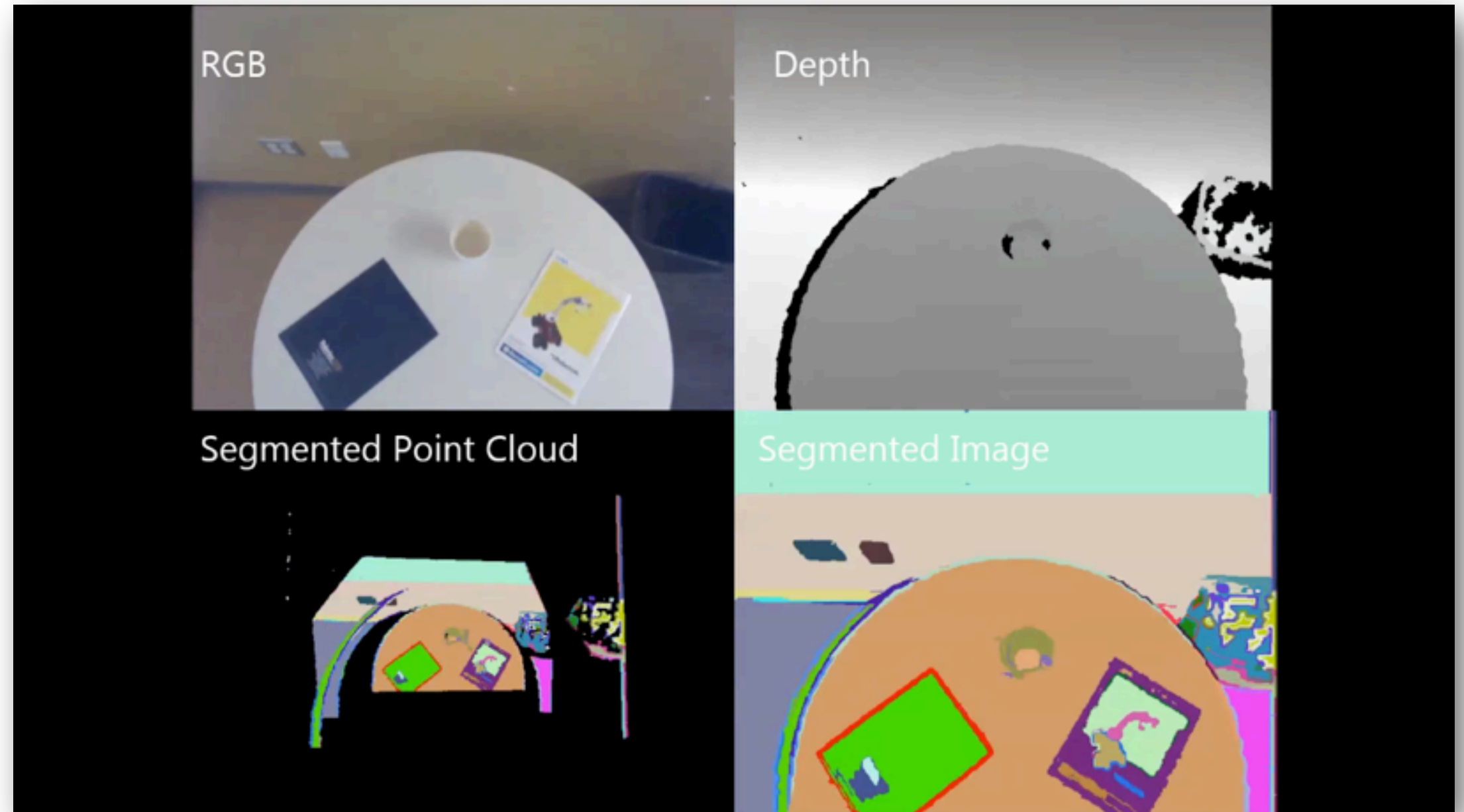
card



robot

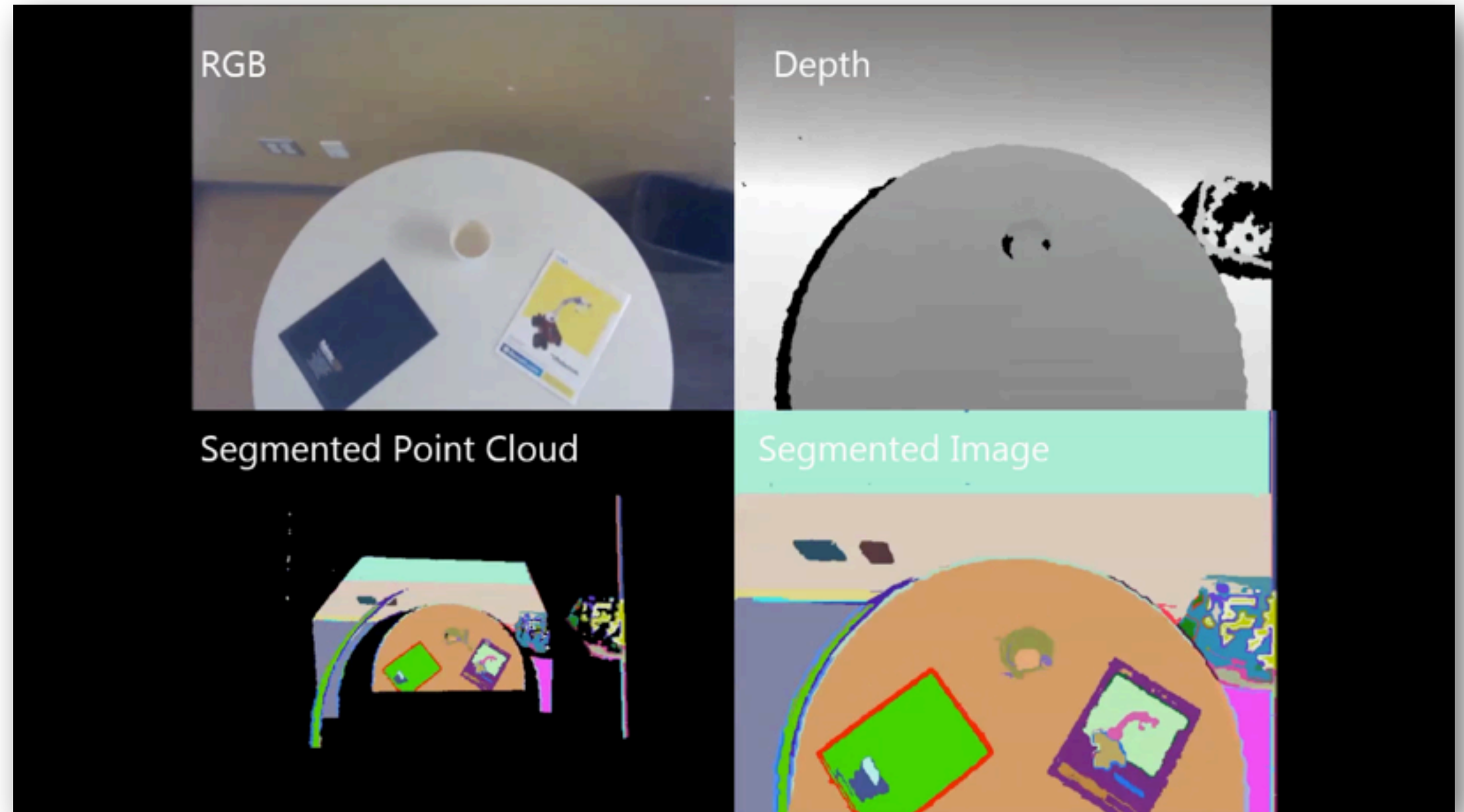
Video Segmentation with RGBD

- ✦ Hickson, Birchfield, I. Essa, and Christensen (2014), "Efficient Hierarchical Graph-Based Segmentation of RGBD Videos," *CVPR 2014*
- ✦ Use RGBD to assist in video segmentation.



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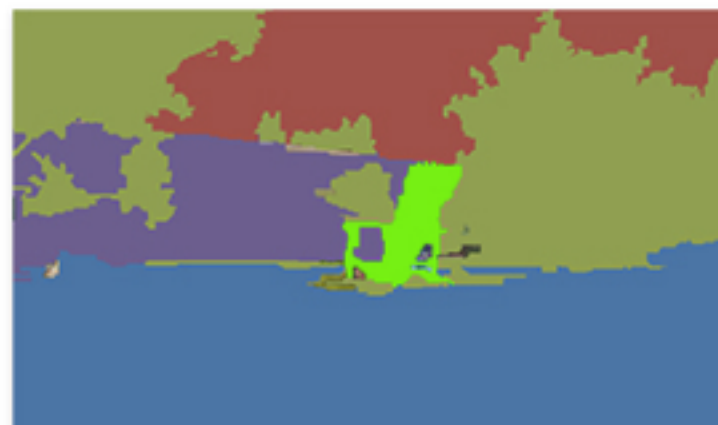
Video Segmentation & Annotation

The Video Segmentation Project has been a collaborative effort between Georgia Tech and Google Research to put a state of the art segmentation and annotation system online for other researchers to use. In addition to making this system available online, we have made all of our source code open source and therefore available for you to use if our system does not fulfill your specific needs.

[Login to get started!](#)

Upload

Send your video to our servers for processing, you are free to customize your settings!



Segment

Run our video segmentation technology. Our system will then output the segments for you to use in your research!



Annotate

You may also annotate your segments using our Flash-based annotator, and save / download your results!



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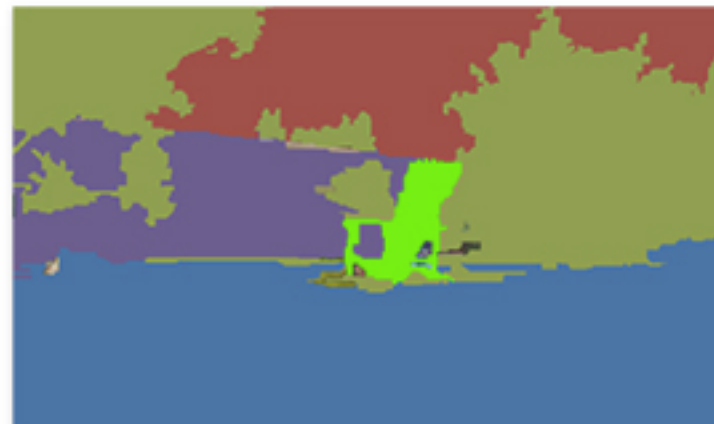
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Online video segmentation

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✦ Goal:

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- ◆ In 2011: videosegmentation.com
 - ◆ *Hosted on two machines with GPUs (for flow)*
 - ◆ *No limits on resolution or length (streaming)*
 - ◆ *One job at a time (HD video could stall queue for everyone)*
 - ◆ *REST API for terminal based usage*

Online video segmentation

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- ◆ Now:

- ◆ *Build fast, highly parallel cloud solution*

Fast online video segmentation

✦ Main ingredients:

- ✦ *Underlying segmentation algorithm $O(n)$*
Parallelize over segmentation and hierarchical segmentation
- ✦ *Streaming segmentation*
- ✦ *Run flow and both segmentations in a parallel pipeline*
- ✦ *Resolution independence*

Fast $O(n)$ segmentation

Fast $O(n)$ segmentation

- Use bucket sort: Discretize edge weight domain into 2-4K buckets (bucket sort)
L1 RGB color distance: 768 values

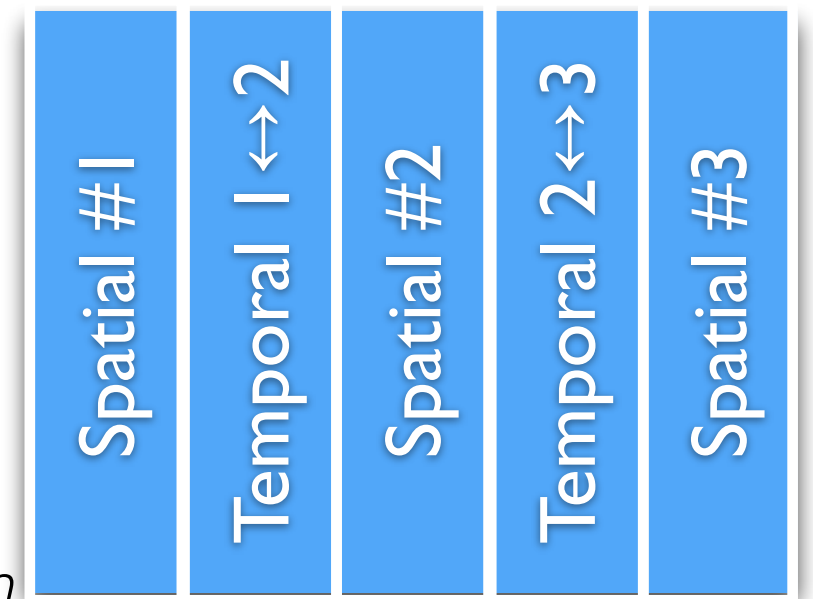
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- Spatial and temporal edges are disjoint \rightarrow Bucket lists:
 - ✦ For N frames use $2 * N - 1$ list of 2K buckets
 - ✦ Create in parallel via on-demand threads! **31% faster!!**

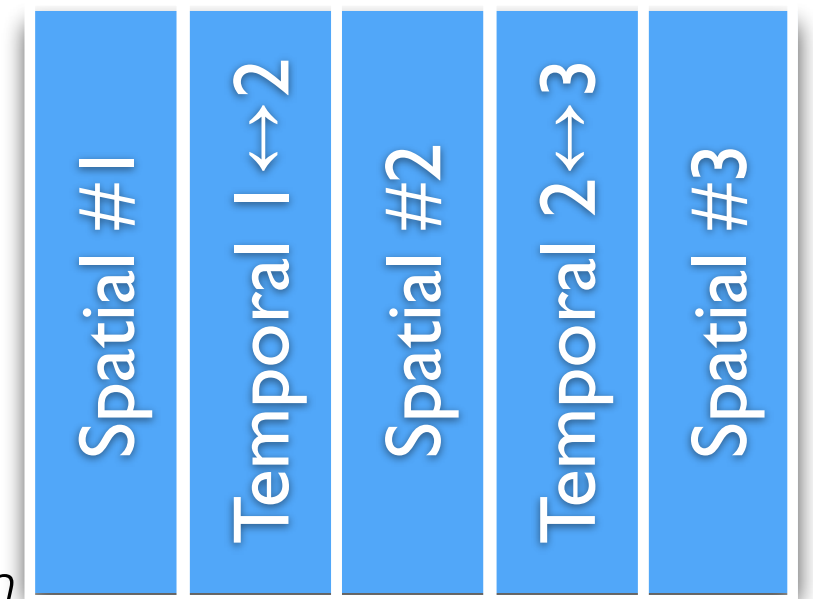
Parallel
construction



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- Spatial and temporal edges are disjoint \rightarrow Bucket lists:
 - ✦ For N frames use $2 * N - 1$ list of 2K buckets
 - ✦ Create in parallel via on-demand threads! **31% faster!!**
- ✦ For hierarchical segmentation:
 - ✦ Evaluate region \leftrightarrow neighbor edges in parallel
 - ✦ Hash edges to weights for fast graph construction

Parallel
construction



Streaming video segmentation

Video Volume: frame# →



Streaming video segmentation

- ✦ Clip-based with overlap

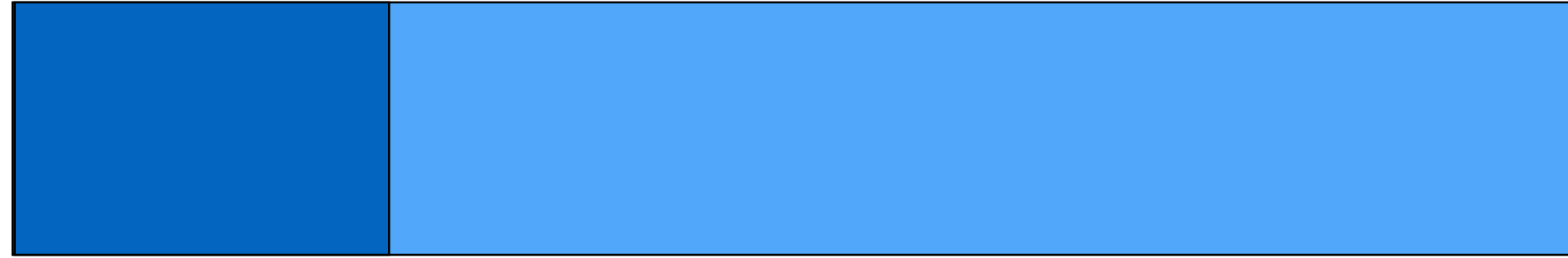
Video Volume: frame# →



Streaming video segmentation

✦ Clip-based with overlap

Video Volume: frame# →

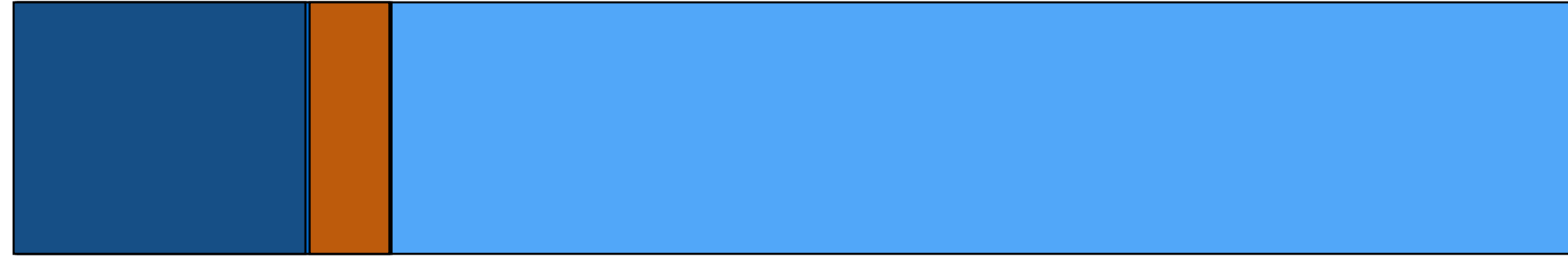


Segment 30 frames

Streaming video segmentation

✦ Clip-based with overlap

Video Volume: *frame#* →

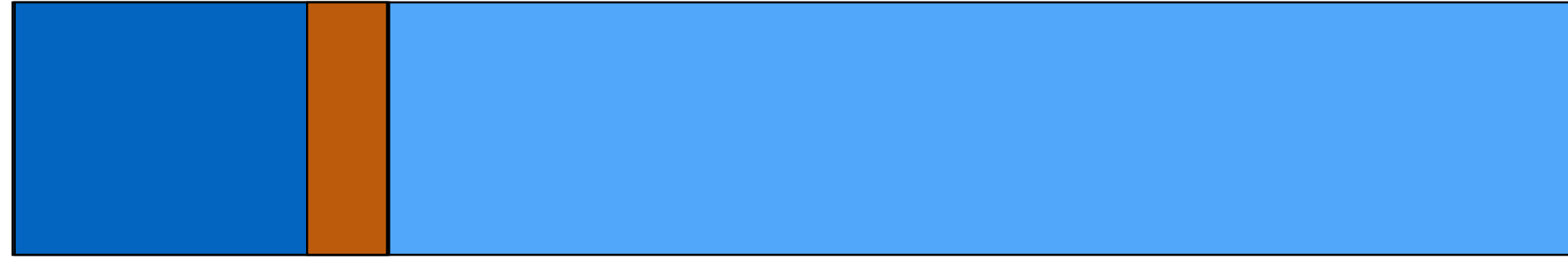


Segment 30 frames

Streaming video segmentation

✦ Clip-based with overlap

Video Volume: frame# →



Segment 30 frames

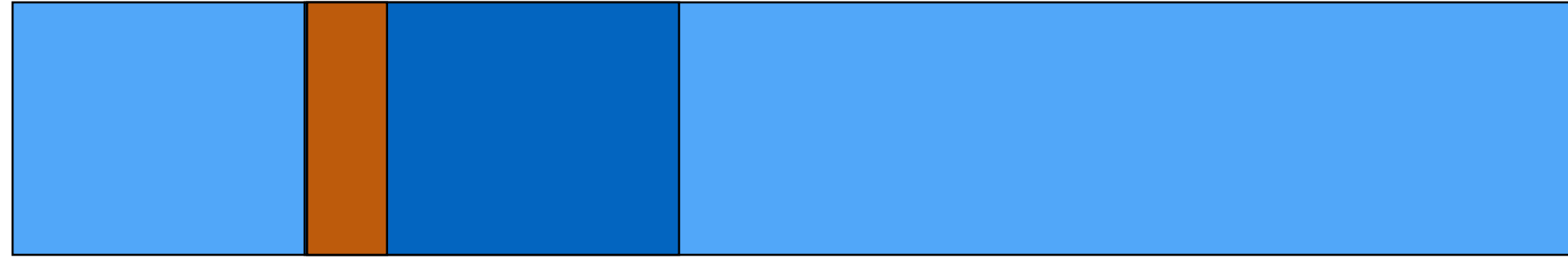


Output result

Streaming video segmentation

✦ Clip-based with overlap

Video Volume: frame# →



Segment 30 frames



Output result

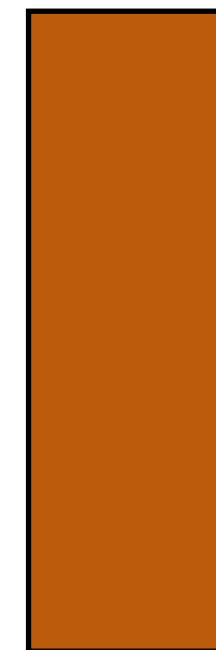
Streaming video segmentation

✦ Clip-based with overlap

Video Volume: frame# →



Output result

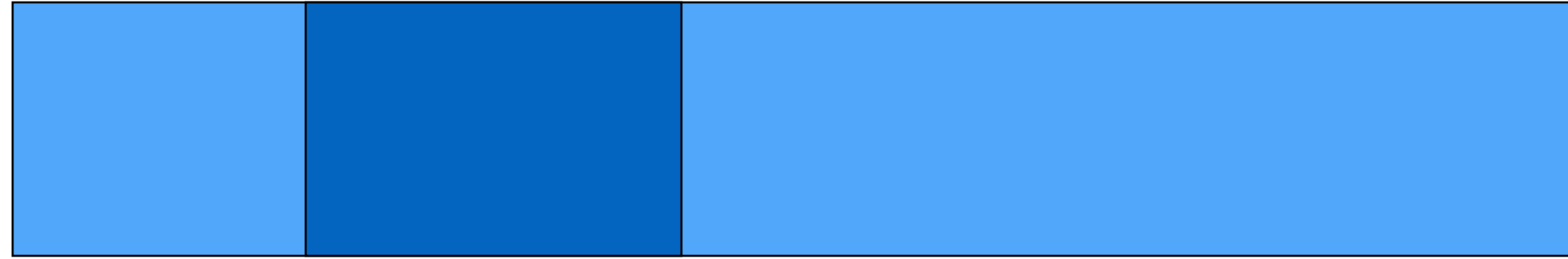


Constrain graph before
segmentation using result
of previous clip

Streaming video segmentation

✦ Clip-based with overlap

Video Volume: frame# →



Segment 30 frames



Output result



Constrain graph before segmentation using result of previous clip

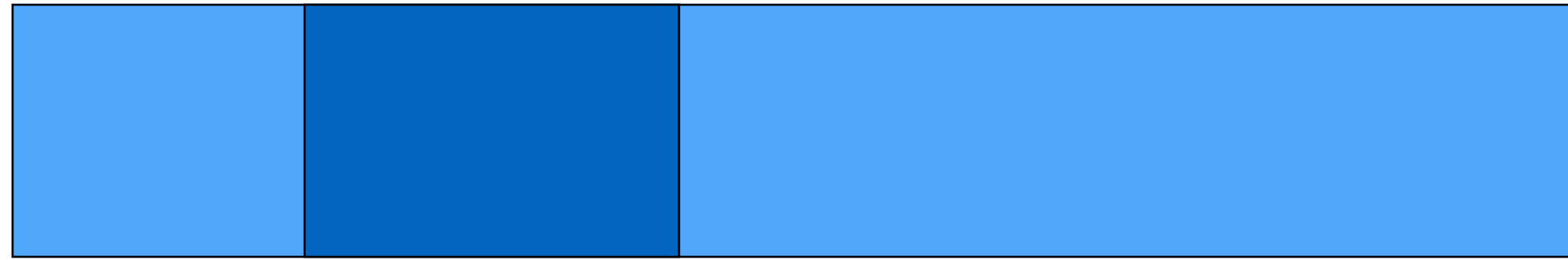
Edge within a region
 $\Rightarrow \text{weight} = 0$

Edge across boundary
 $\Rightarrow \text{weight} = \infty$

Streaming video segmentation

- ✦ Clip-based with overlap
- ✦ Original implementation modified edge weights

Video Volume: frame# →



Segment 30 frames



Output result



Constrain graph before segmentation using result of previous clip

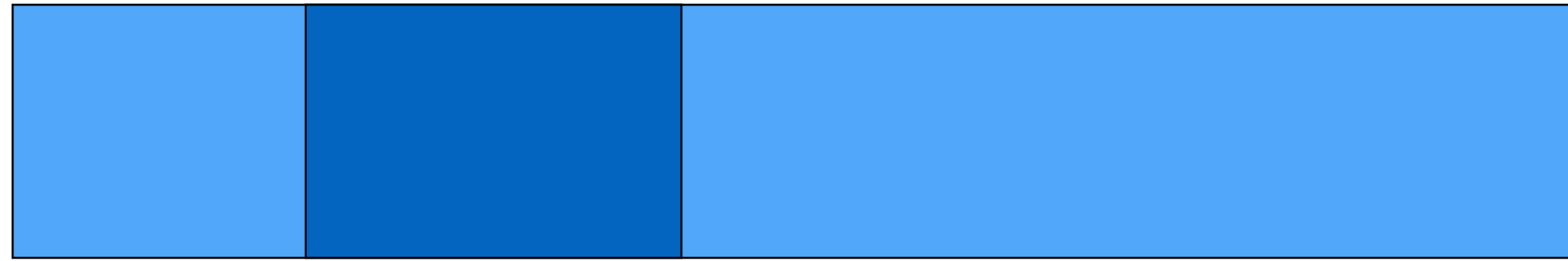
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Edge across boundary
 $\Rightarrow \text{weight} = \infty$

Streaming video segmentation

- ✦ Clip-based with overlap
- ✦ Original implementation modified edge weights
- ✦ Modifying edge weights is bad!
 - ✦ *Single-link clustering*
 - ✦ *Changes order of merges*
 - ✦ *If used with Felzenszwalb criteria prohibits merges*

Video Volume: frame# →



Segment 30 frames



Output result

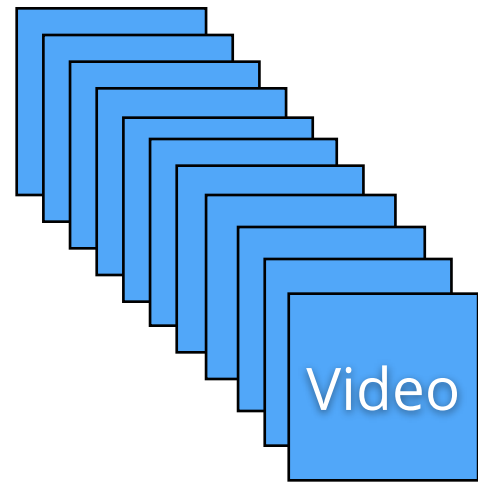


Constrain graph before segmentation using result of previous clip

*Edge within a region
⇒ weight = 0*

*Edge across boundary
⇒ weight = ∞*

Segmentation Pipeline



Flow computation on
video frame pairs

Dense
flow
computation

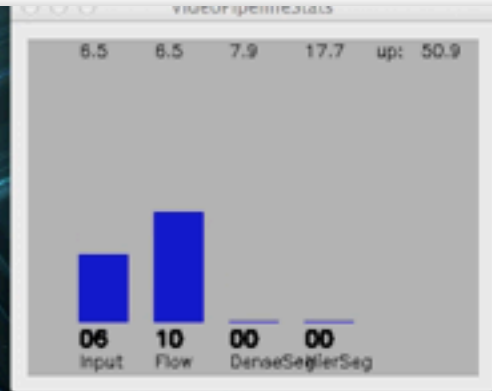
Buffers extracted features
Builds graph in parallel

Over-
segmentation

Segments
clips of 30 frames

Computing region
descriptors
discard frames

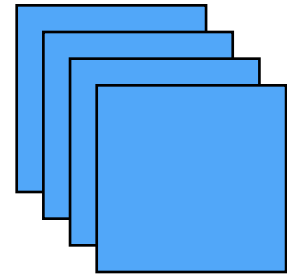
Hierarchical
Segmentation



```
seg_tree_sample — seg_tree_sample — 92x26
seg__mple  bash  bash  matt...tion  bash ...
10621 15:58:50.541306 266072064 dense_segmentation.cpp:319] Outputting from 190 to 209
10621 15:58:50.637850 266072064 segmentation_unit.cpp:150] __STREAMING_SIZE__: 209
10621 15:58:50.637928 266072064 dense_segmentation.cpp:92] Processing frame 210
10621 15:58:50.670902 266072064 dense_segmentation.cpp:92] Processing frame 211
10621 15:58:50.717425 266072064 dense_segmentation.cpp:92] Processing frame 212
10621 15:58:50.758332 266072064 dense_segmentation.cpp:92] Processing frame 213
10621 15:58:50.795724 266072064 dense_segmentation.cpp:92] Processing frame 214
10621 15:58:50.833319 266072064 dense_segmentation.cpp:92] Processing frame 215
10621 15:58:50.885272 266072064 dense_segmentation.cpp:92] Processing frame 216
10621 15:58:50.932142 266072064 dense_segmentation.cpp:92] Processing frame 217
10621 15:58:50.983661 266072064 dense_segmentation.cpp:92] Processing frame 218
10621 15:58:51.038287 265535488 flow_reader.cpp:335] Processed Frame #220
10621 15:58:51.038369 266072064 dense_segmentation.cpp:92] Processing frame 219
10621 15:58:51.203913 266072064 dense_segmentation.cpp:92] Processing frame 220
10621 15:58:51.362016 266072064 dense_segmentation.cpp:92] Processing frame 221
10621 15:58:51.518537 266072064 dense_segmentation.cpp:92] Processing frame 222
10621 15:58:51.673398 266072064 dense_segmentation.cpp:92] Processing frame 223
10621 15:58:51.824586 266072064 dense_segmentation.cpp:92] Processing frame 224
10621 15:58:51.983318 266072064 dense_segmentation.cpp:92] Processing frame 225
10621 15:58:52.148962 266072064 dense_segmentation.cpp:92] Processing frame 226
10621 15:58:52.307929 266072064 dense_segmentation.cpp:92] Processing frame 227
10621 15:58:52.463804 266072064 dense_segmentation.cpp:92] Processing frame 228
10621 15:58:52.491336 266072064 dense_segmentation.cpp:253] Chunk boundary reached 11
10621 15:58:52.549633 266072064 segmentation_graph.h:301] Segmenting graph ...
10621 15:58:52.641587 265535488 flow_reader.cpp:335] Processed Frame #230

Downloads — http — 92x27
1 [|||||1194.7%] Tasks: 242 total, 11 running
2 [|||||1190.] Load average: 6.24 5.78
3 [|||||1192.] Uptime: 1 day, 17:44:34
4 [|||||1188.]
5 [|||||1194.1]
6 [|||||1187.]
7 [|||||1190.]
8 [|||||1190.]
Mem [|||||17248/16384MB]
Swap [|||||]
```


Segmentation Pipeline



Flow computation on
video frame pairs

Dense
flow
computation



Buffers extracted features
Builds graph in parallel

Over-
segmentation

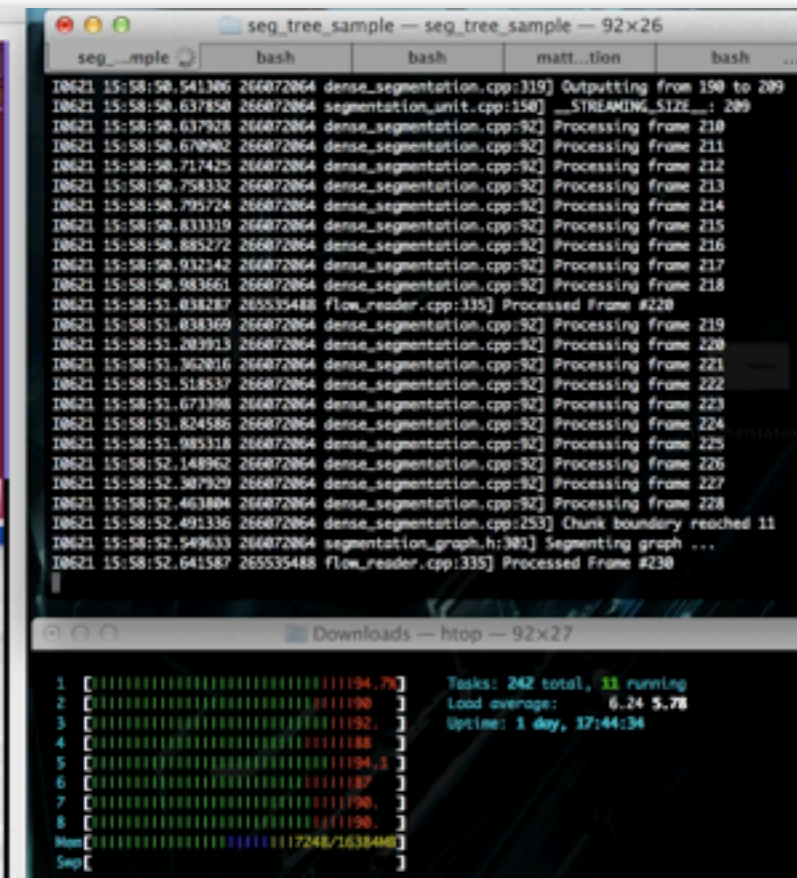
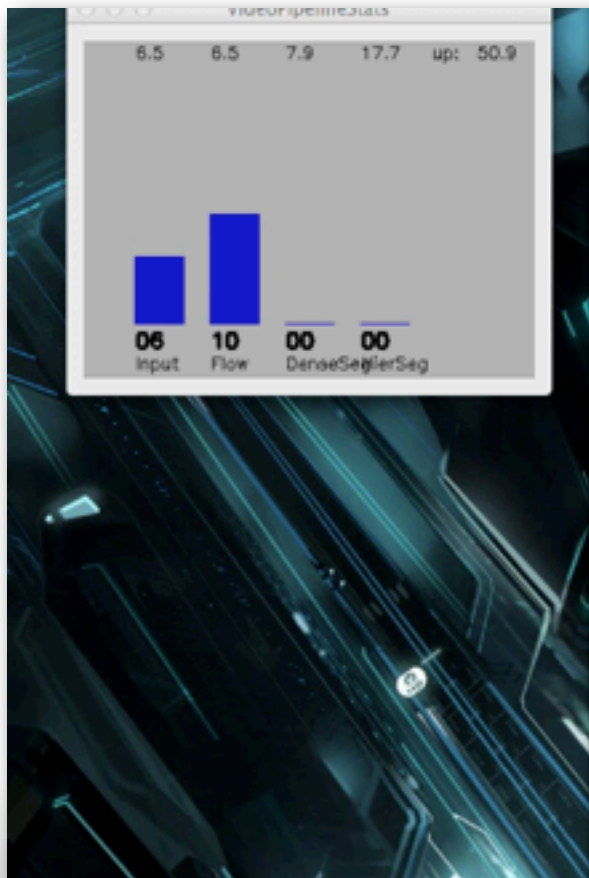
Segments
clips of 30 frames



Computing region
descriptors
discard frames

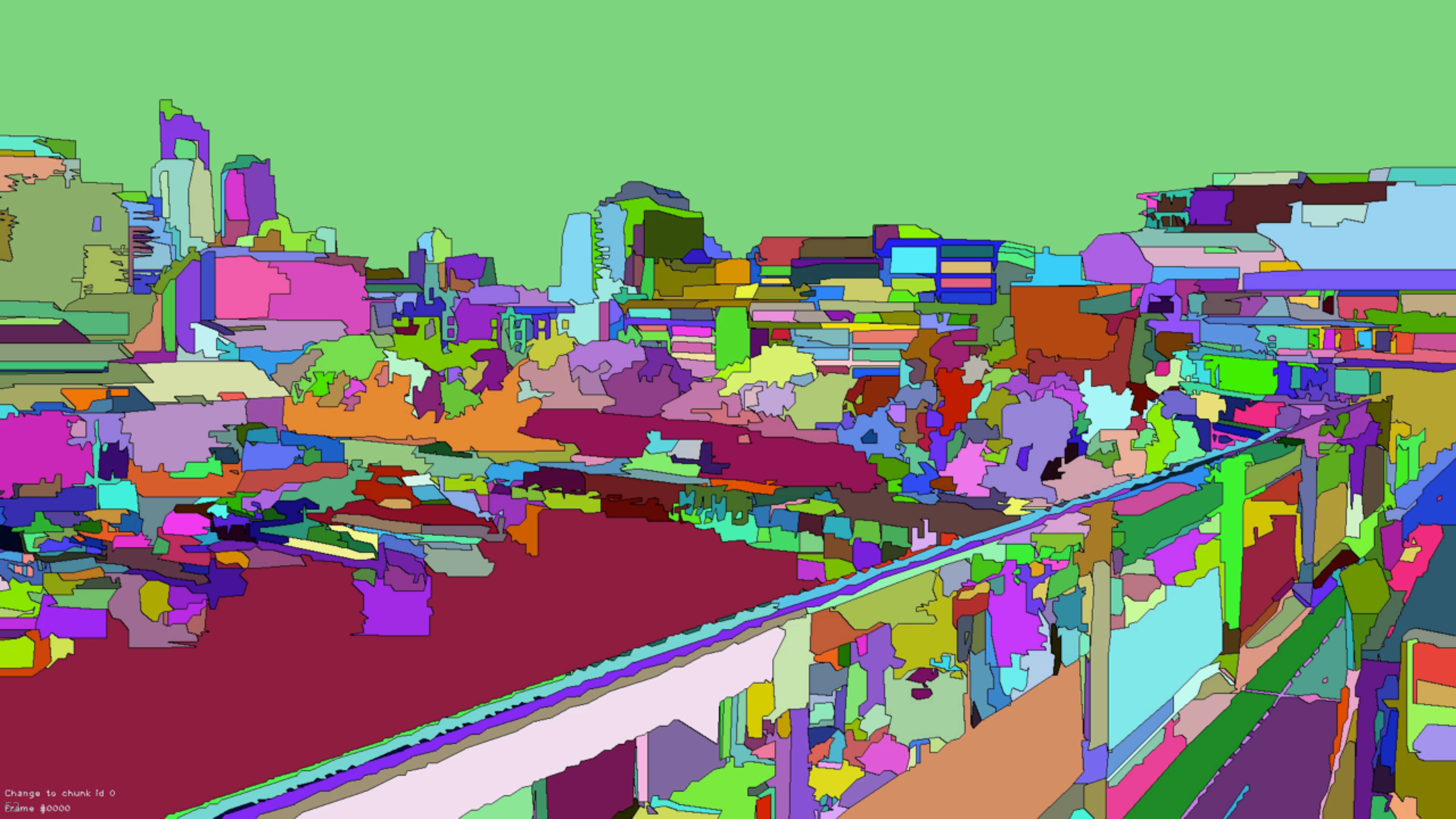
Hierarchical
Segmentation

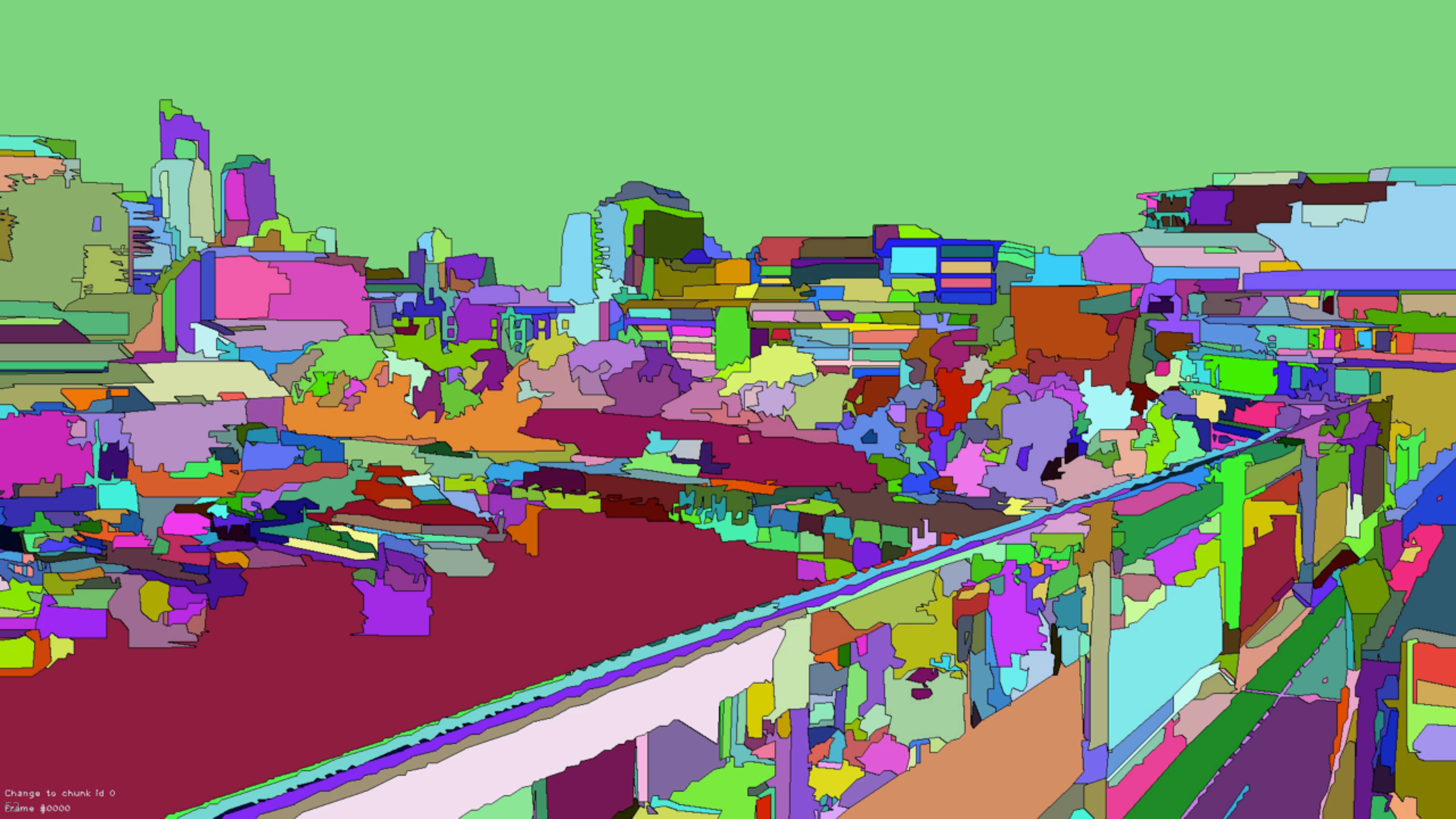
Video









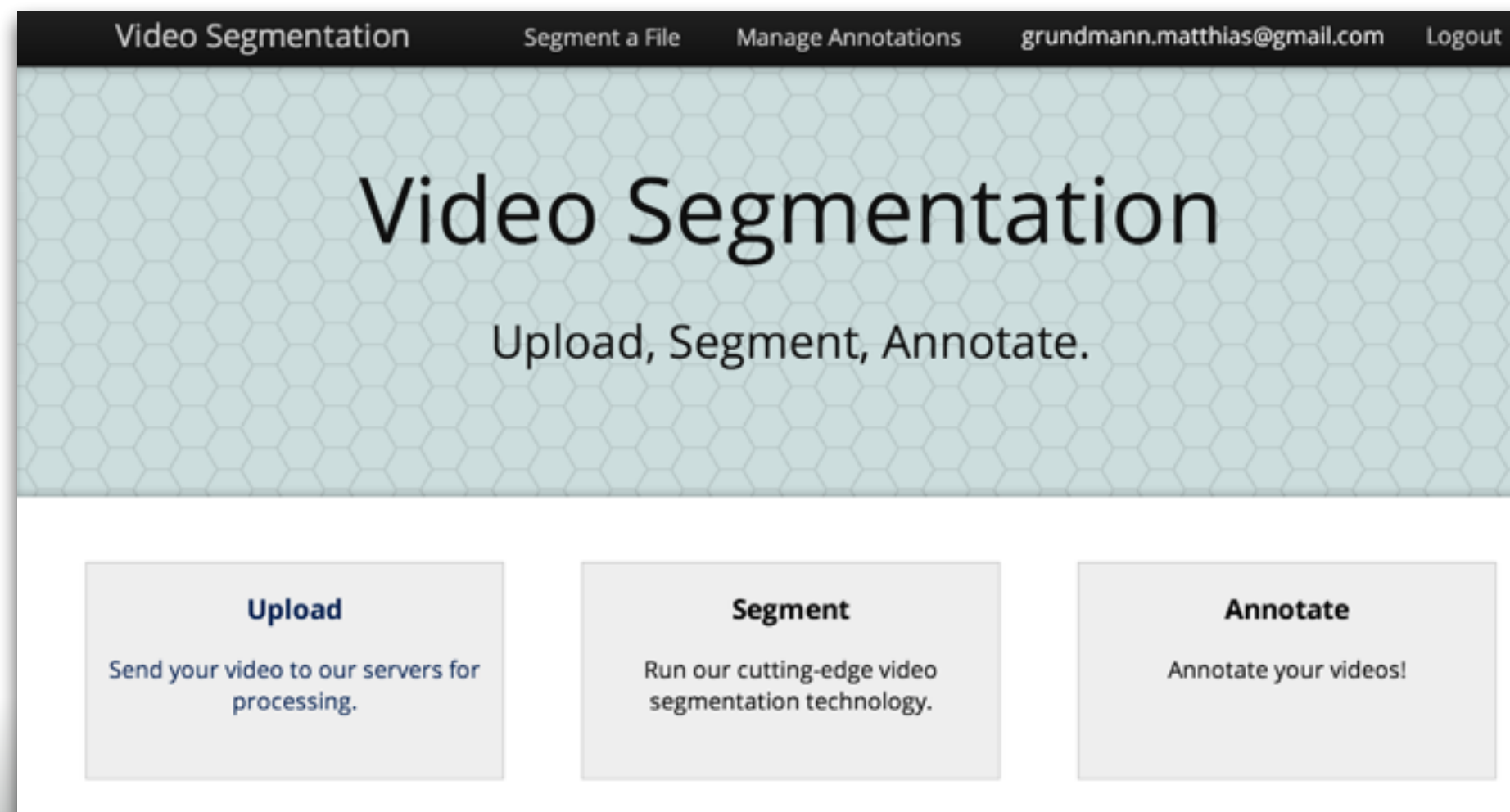






Online Video Segmentation and Annotation

- ✦ End-to-end system for online video segmentation and annotation
- ✦ www.videosegmentation.com





Video Segmentation & Annotation

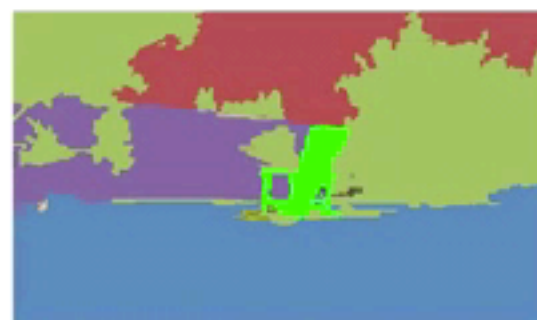
The Video Segmentation Project has been a collaborative effort between Georgia Tech and Google Research to put a state of the art segmentation and annotation system online for other researchers to use. In addition to making this system available online, we have made all of our source code open source and therefore available for you to use if our system does not fulfill your specific needs.

Let us know what you're working on!



Upload

Send your video to our servers for processing, you are free to customize your settings!



Segment

Run our video segmentation technology. Our system will then output the segments for you to use in your research!



Annotate

You may also annotate your segments using our Flash-based annotator, and save / download your results!

We recently gave a talk at CVPR 2014, see the slides ([Keynote](#) | [PDF](#) | [PPTX](#)).

[Learn more.](#)

Research Resources





Video Segmentation & Annotation

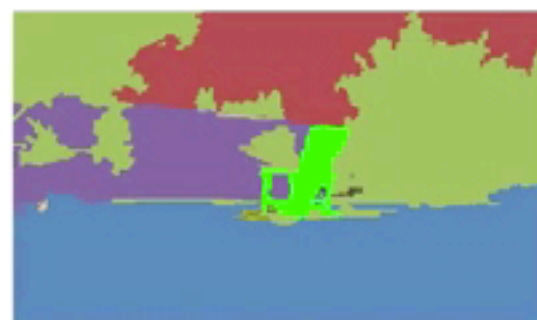
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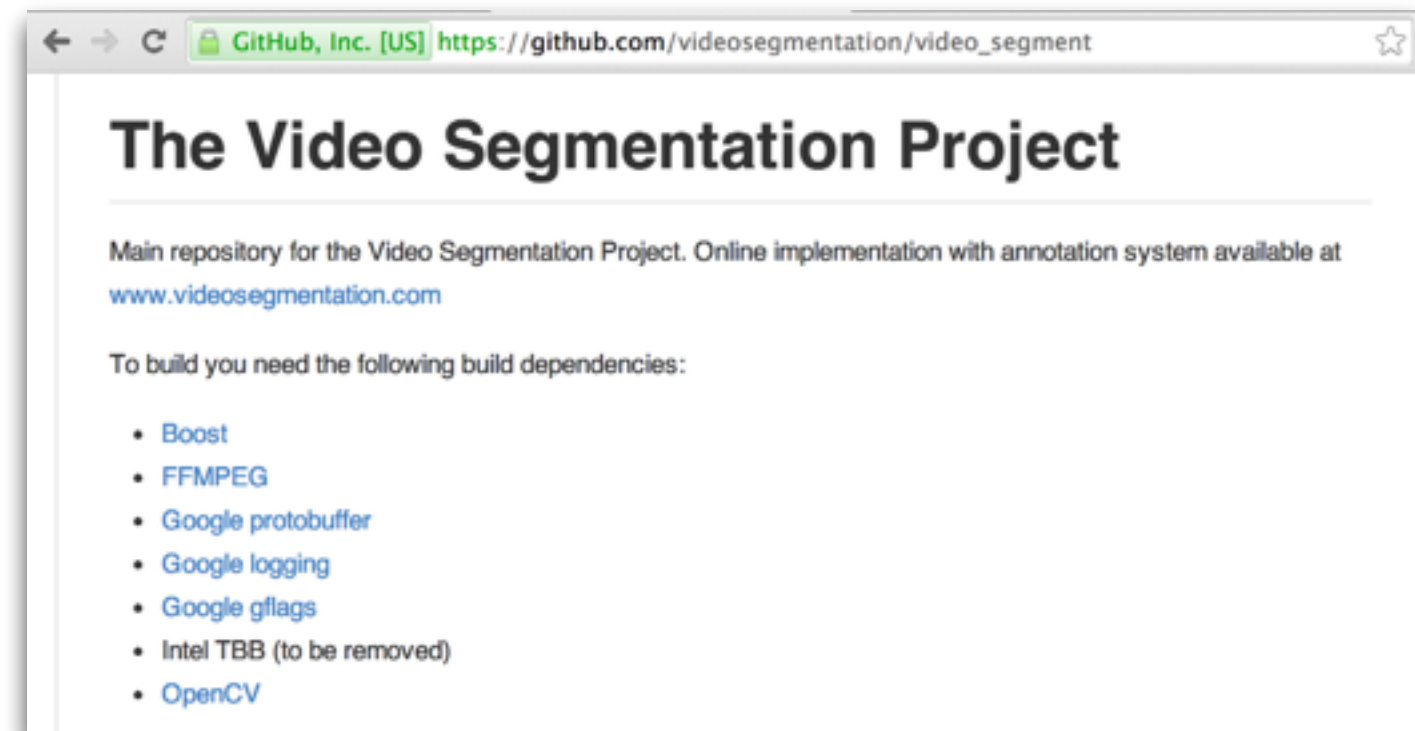
[Learn more.](#)

Research Resources

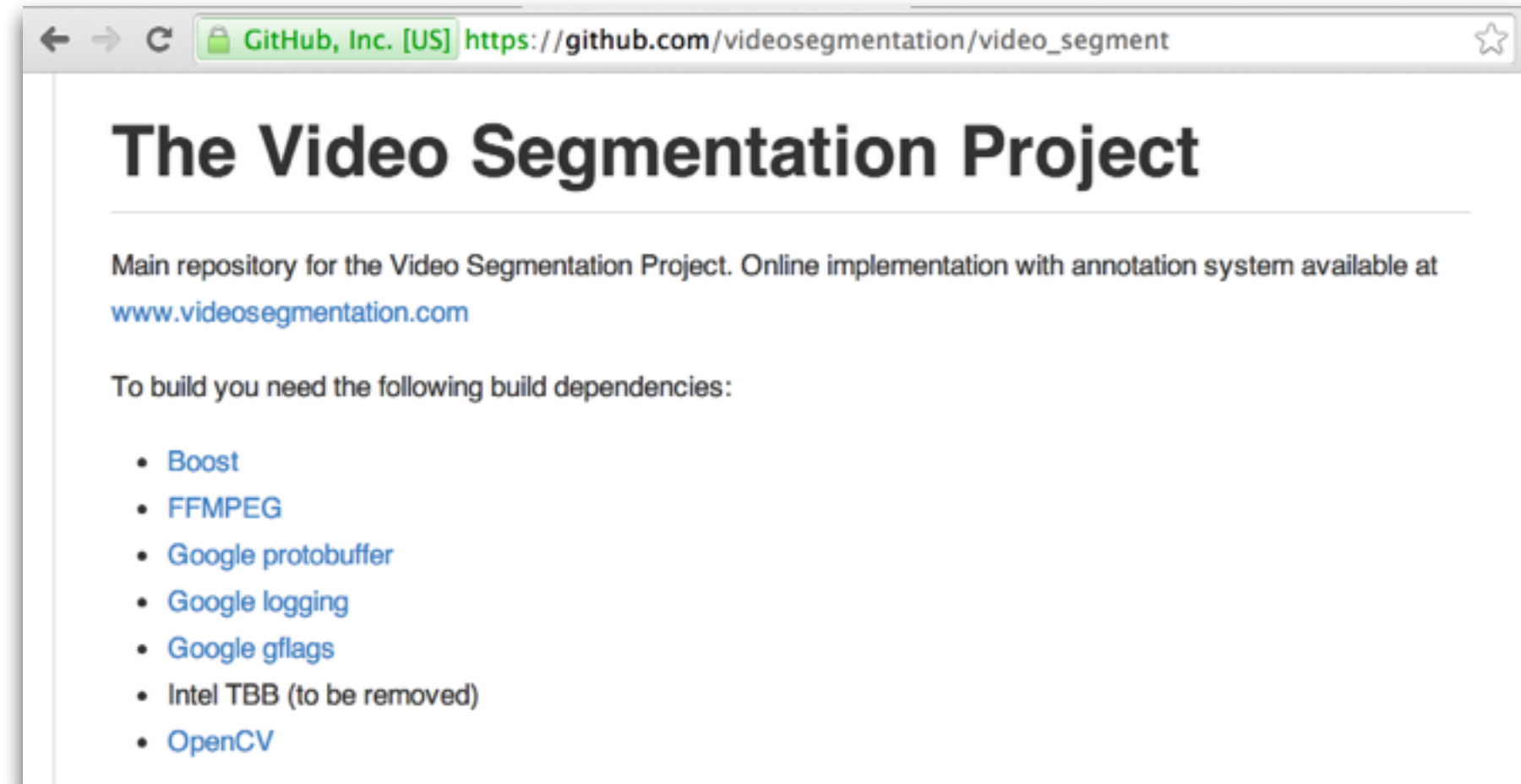


Open Source Video Segmentation System

https://github.com/videosegmentation/video_segment

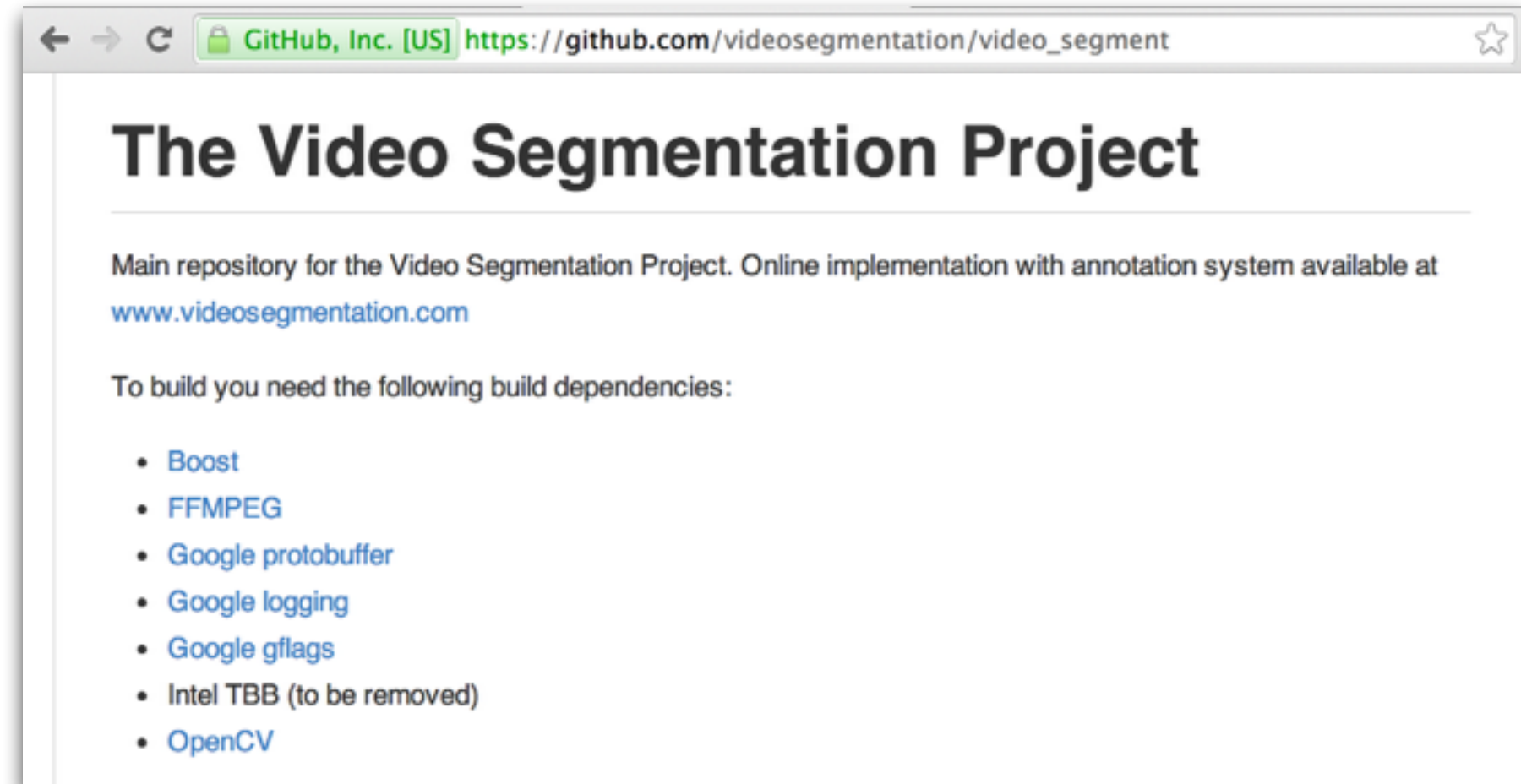


The Video Segmentation Project



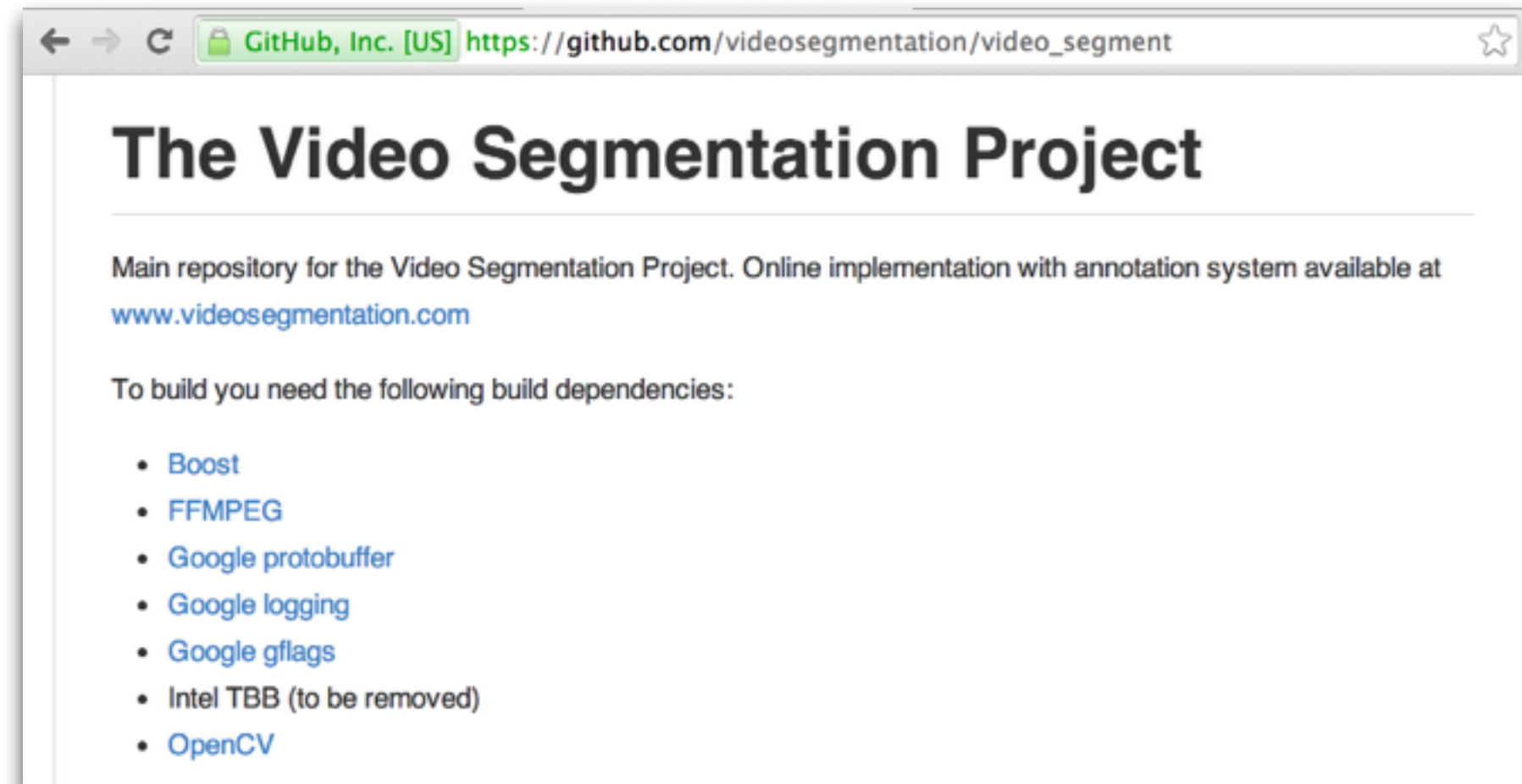
The Video Segmentation Project

- ✦ Open source implementation of everything shown today
 - ✦ https://github.com/videosegmentation/video_segment
 - ✦ *BSD license*



The Video Segmentation Project

- ◆ Open source implementation of everything shown today
 - ◆ https://github.com/videosegmentation/video_segment
 - ◆ BSD license
- ◆ Generic segmentation interfaces
 - ◆ *Over segmentation:*
 - ◆ Define pixel distance
 - ◆ region descriptors,
 - ◆ merge thresholds
 - ◆ *Hierarchical segmentation:*
 - ◆ Define region descriptors
 - ◆ distances



Summarizing..



Research
at Google



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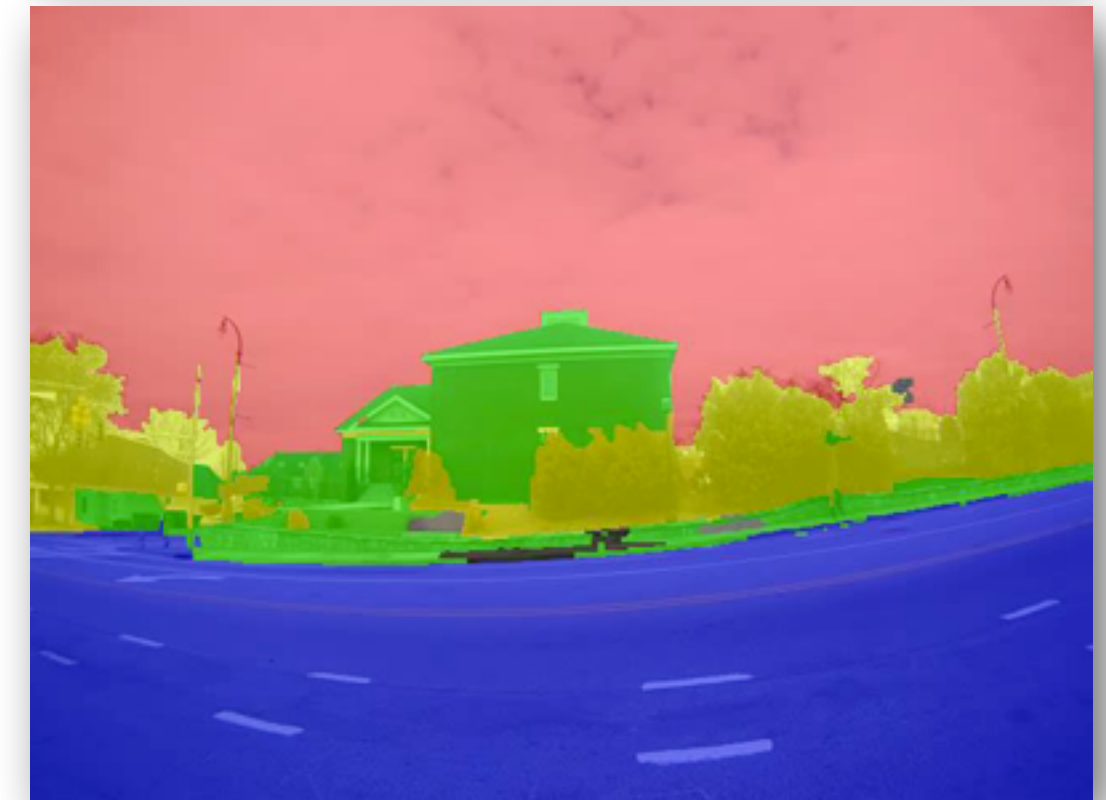
Summarizing ..

◆ Video Segmentation

- ◆ *Efficient, Hierarchical, Super-pixel/voxel-based*
- ◆ *Running as a WebAPI and Source code available (videosegmentation.com)*
- ◆ *already in use by some research groups*
- ◆ *ideas for future extensions welcome*
- ◆ *Uses for “Video Scene Understanding”*

◆ More Info:

- ◆ *prof.irfanessa.com*



Research
at Google

Georgia
Tech College of
Computing